# Existence of the Solution to Discrete Surface Ricci Flow

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# **Discrete Surface Curvature Flow Theorem**

# Vertex Scaling

### Definition (Vertex Scaling)

Two triangulated PL surface  $(S, V, \mathcal{T}, d)$  and  $(S, V, \mathcal{T}, d')$  are said to differ by a vertex scaling, if  $\exists \lambda : V(\mathcal{T}) \to \mathbb{R}_{>0}$ , such that  $d' = \lambda * d$  on  $E(\mathcal{T})$ , where

$$\lambda * d(u, v) = \lambda(u)\lambda(v)d(u, v).$$

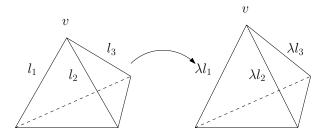


Figure: vertex scaling.

### Definition (Gu-Luo-Sun-Wu)

Two PL metrics d, d' on a closed marked surface (S, V) are *discrete conformal*, if they are related by a sequence of two types of moves: vertex scaling and edge flip preserving Delaunay property.

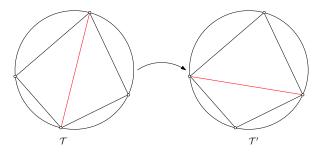


Figure: Edge flip, both triangulations are Delaunay.

# Discrete Conformal Equivalence

Given a PL metric d on (S, V), produce a Delaunay triangulation  $\mathcal{T}$  of (S, V),

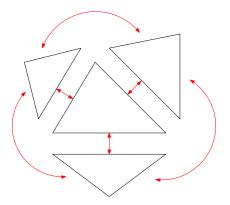
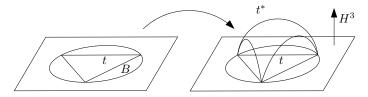


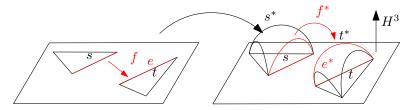
Figure: (S, V) with PL metric d, the triangulation is Delaunay.

# Discrete Conformal Equivalence

Each face  $t \in \mathcal{T}$  is associated an ideal hyperbolic triangle:

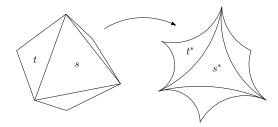


If  $t, s \in \mathcal{T}$  glued by isometry f along e, then  $t^*$  and  $s^*$  are glued by the same  $f^*$  alonge  $e^*$ ,



# Discrete Conformal Equivalence

This induces a hyperbolic metric  $d^*$  on S - V.



Motivated by the important work of Bobenko-Pinkall-Springborn, equivalent to the previous definiton using vertex scaling and Delaunay condition.

### Definition (Gu-Luo-Sun-Wu, JDG 2018)

Two PL metrics  $d_1$  and  $d_2$  on (S, V) are *discrete conformal* iff  $d_1^*$  and  $d_2^*$  are isometric by an isometry homotopic to identity on S - V.

#### Theorem (Gu-Luo-Sun-Wu)

Given a PL metric d on a closed marked surface (S, V), and curvature  $K^* : V \to (-\infty, 2\pi)$ , such that K satisfies the Gauss-Bonnet condition  $\sum K(v) = 2\pi\chi(S)$ , there there is a  $d^*$  discrete conformal to d, and  $d^*$  realizes the curvature  $K^*$ .

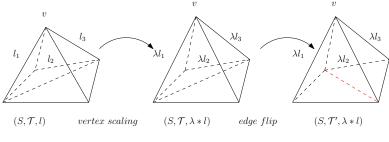


Figure: Discrete surface Yamabe flow.

#### Convex Optimization

Using Newton's method to minimize the following energy

$$\min_{\lambda} \int^{(\lambda_1,\lambda_2,\ldots,\lambda_n)} \sum_{\nu} (K^*(\nu) - K(\nu)) d \log \lambda(\nu),$$

such that  $\Pi_{\nu}\lambda(\nu) = 1$ . During the optimization, keep the triangulation always to be Delaunay.

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# Proof of the Discrete Surface Curvature Flow Theorem

### Definition (Marked Surface)

Let S be a closed topological surface,  $V = \{v_1, v_2, \cdots, v_n\} \subset S$  is the set of distinct points, satsifying negative Euler number condition  $\chi(S - V) < 0$ . We call (S, V) a marked surface.

We consder the polyhedral metric **d** on the marked surface (S, V), with cone singularities at vertices.

#### Definition (Discrete Conformal Equivalence)

Two polyhedral metrics **d** and **d'** on a marked surface (S, V) are discrete conformal equivalent, if there is a series polyhedral metrics on (S, V),

$$\mathbf{d} = \mathbf{d}_1, \mathbf{d}_2, \cdots, \mathbf{d}_m = \mathbf{d}'$$

and a series of triangulations  $\mathcal{T}_1, \mathcal{T}_2, \cdots, \mathcal{T}_m$ , such that

- every triangulation  $T_k$  is Delaunay on the metric  $\mathbf{d}_k$ ;
- ② if  $T_i = T_{i+1}$ , then there is a conformal factor  $\mathbf{u} : V \to \mathbb{R}$ , such that  $\mathbf{d}_{i+1} = \mathbf{u} * \mathbf{d}_i$ , namely the two polyhedral metrics differ by a vertex scaling operation;
- if T<sub>i</sub> ≠ T<sub>i+1</sub>, then there is an isometric transformation
   h: (S, V, d<sub>i</sub>) → (S, V, d<sub>i+1</sub>), this transformation is homotopic to the identity map of (S, V), preserving the vertices.

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Existence and Uniqueness of the Solution to the Discrete Surface Ricci Flow:

### Theorem (Gu-Luo-Sun)

Suppose  $(S, V, \mathbf{d})$  is a closed polyhedral surface, the for any  $K^* : V \to (-\infty, 2\pi)$ , satisfying the Gauss-Bonnet condition  $\sum_{v \in V} K^*(v) = 2\pi\chi(S)$ , there exists a polyhedral metric  $\mathbf{d}^*$ 

- **1 d**<sup>\*</sup> *is discrete conformal equivalent to the metric* **d***;*
- **2**  $\mathbf{d}^*$  induces the discrete Gaussian curvature  $K^*$ .

All such kind of polyhedral metrics differ by a global scaling. Furthermore,  $\mathbf{d}^*$  can be obtained by discrete surface Ricci flow.

# Uniformization

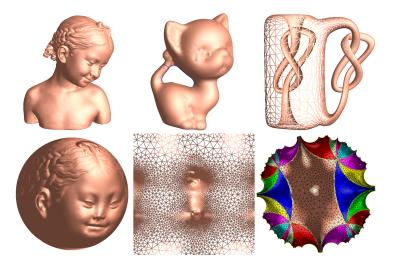


Figure: Closed surface uniformization.

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Computational Conformal Geometry

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### Corollary (Gu-Luo-Sun)

Suppose  $(S, V, \mathbf{d})$  is a closed polyhedral surface, then there exists a polyhedral metric  $\mathbf{d}^*$ ,  $\mathbf{d}^*$  and the metric  $\mathbf{d}$  are discrete conformal equivalent,  $\mathbf{d}^*$  induces constant discrete Gaussian curvature  $2\pi\chi(S)/|V|$ . Such kind of polyhedral metrics differ by a global scaling.

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#### Definition (Equivalent Polyhedral Metrics)

Two polyhedral metrics **d** and **d'** on a marked surface (S, V) are equivalent, if there is an isometric transformation  $h: (S, V, \mathbf{d}) \rightarrow (S, V, \mathbf{d'})$ , and h is homotopic to the identity map of (S, V), namely h preserves V.

#### Definition (Teichmüller Space of Polyhedral Metrics)

All the equivalence classes of polyhedral metrics on a marked surface (S, V) form the Teichmüller Space of polyhedral metrics.

 $T_{pl}(S, V) = \{\mathbf{d} | \text{polyhedral metrics on } (S, V) \} / \{\text{isometries} \sim \text{identity} (S, V) \}$ 

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# Atlas of the Teichmüller Space of PL Metrics

### Theorem (Troyanov)

Suppose (S, V) is a closed marked surface, the Teichmüller space of polyhedral metrics  $T_{pl}(S, V)$  is homeomorphic to the Euclidean space  $\mathbb{R}^{-3\chi(S-V)}$ .

### Definition (Local Chart of the Teichmüller Space of PL Metrics)

Suppose  $\mathcal{T}$  is a triangulation of (S, V), its edge length function defines a polyhedral metric,

$$\Phi_{\mathcal{T}}: \mathbb{R}^{\mathcal{E}(\mathcal{T})}_{\bigtriangleup} \to T_{\rho}(S, V)$$
(1)

this gives a local chart of the Teichmüller space. Where the domain

$$\mathbb{R}^{\mathcal{E}(\mathcal{T})}_{\triangle} = \left\{ x \in \mathbb{R}^{\mathcal{E}(\mathcal{T})}_{>0} \middle| \text{ for any } e_i, e_j, e_k \text{ form a triangle }, x(e_i) + x(e_j) > x(e_k) \right.$$
(2)

is a convex set, and is injective. We use  $\mathcal{P}_{\mathcal{T}}$  to represent the image of  $\Phi_{\mathcal{T}}$ . Then  $(\mathcal{P}_{\mathcal{T}}, \Phi_{\mathcal{T}}^{-1})$  is a local chart of  $T_{pl}(S, V)$ .

### Atlas of the Teichmüller Space of PL Metrics

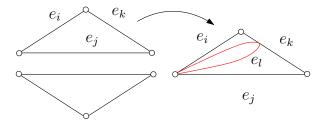


Figure: topological, not geometric triangulation.

If we edge swap  $e_k$  to  $e_l$  ot obtain the new triangulation  $\mathcal{T}'$ . Then under the metric **d**, the topological triangle  $\{e_j, e_l, e_j\}$  doesn't satisfy the triangle inequality. This shows the topological triangulation  $\mathcal{T}'$  is not geometric.

$$\mathcal{P}(\mathcal{T}) \neq T_{pl}(S, V)$$

One chart can't cover the whole Teichmüller space  $T_{pl}(S, V)$ .

#### Definition (Atlas of Teichmüller Space of PL Metrics)

Suppose (S, V) is a closed marked surface, the atlas of  $T_{pl}(S, V)$  consists of local coordinate charts  $(\mathcal{P}_{\mathcal{T}}, \Phi_{\mathcal{T}}^{-1})$ , where  $\mathcal{T}$  exhausts all possible triangulation.

$$\mathcal{A}(T_{pl}(S,V)) = \bigcup_{\mathcal{T}} (\mathcal{P}_{\mathcal{T}}, \Phi_{\mathcal{T}}^{-1}).$$
(3)

#### Lemma (Real Analytic Manifold)

Suppose (S, V) is a closed marked surface, then the Teichmüller space of polyhedral metrics  $T_{pl}(S, V)$  is a real analytic manifold.

# Teichmüller Space of Decorated Hyperbolic Metrics

### Definition (Equivalent decorated hyperbolic metrics)

Two decorated hyperbolic metrics  $(\mathbf{h}, \mathbf{w})$  and  $(\mathbf{h}', \mathbf{w}')$  on a closed marked surface (S, V) are equivalent, if there is an isometric transformation

$$h: (S, V, \mathbf{h}, \mathbf{w}) \rightarrow (S, V, \mathbf{d}', \mathbf{w}'),$$

which is homotopic to the identity map of (S, V), and preserves the horospheres.

#### Definition (Teichmüller Space of Decorated Hyperbolic Metrics)

Given a closed marked surface (S, V),  $\chi(S - V) < 0$ , then all the decorated hyperbolic metric on it form the Teichmüller space:

$$T_D(S, V) = \frac{\{(\mathbf{h}, \mathbf{w}) | (S, V) \text{decorated hyperbolic metrics}\}}{\{\text{isometries} \sim \text{identity of } (S, V) \text{preserving horospheres}\}}$$
(4)

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# Teichmüller Space of Decorated Hyperbolic Metrics

### Definition (Local Chart of the Teichmüller Space)

Suppose T is a triangulation of (S, V), the hyperbolic edge length function determines a decorated hyperbolic metric,

$$\Psi_{\mathcal{T}}: \mathbb{R}^{\mathcal{E}(\mathcal{T})} \to T_D(S, V) \tag{5}$$

which gives a local coordinate of the Teichmüller space. Let  $Q_T$  be the image of  $\Psi_T$ , then  $(Q_T, \Psi_T^{-1})$  form a local chart of  $T_D(S, V)$ .

#### Definition (Atlas of the Teichmüller Space)

Every triangulation of the marked closed surface (S, V) corresponds to a local chart  $(Q_T, \Psi_T^{-1})$ . By exhausting all the possible triangulations, the union of all the local charts forms the atlas:

$$\mathcal{A}(T_D(S,V)) = \bigcup_{\mathcal{T}} \left( \mathcal{Q}_{\mathcal{T}}, \Psi_{\mathcal{T}}^{-1} \right).$$

# Teichmüller Space of Complete Hyperbolic Metrics

### Definition (Equivalent Complete Hyperbolic Metrics)

Two complete hyperbolic metrics **h** and **h'** with finite area on a marked surface (S - V) are equivalent, if there is an isometric transformation

$$h: (S - V, \mathbf{h}) \rightarrow (S - V, \mathbf{h}'),$$

furthermore h is homotopic to the identity automorphism of S - V.

#### Definition (Teichmüller Space of Complete Hyperbolic Metrics)

All the complete hyperbolic metrics with finite area on a marked surface S - V,  $\chi(S - V) < 0$ , form the Teichmüller space,

 $T_{H}(S-V) = \frac{\{\mathbf{h} | \text{complete hyperbolic metrics with finite area on } (S-V)\}}{\{\text{isometries} \sim \text{identity of } (S-V)\}}$ 

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(6)

#### Lemma (Local Coordinates)

Suppose **h** is a complete hyperbolic metric on S - V with finite area, the shear coordinate function is  $s : E(T) \to \mathbb{R}$ , then for any  $v \in V$ , we have the relation

$$\sum_{e \sim v} s(e) = 0. \tag{7}$$

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#### Definition (Local Chart of the Teichmüller Space)

Let  $\mathcal{T}$  be a triangulation of (S, V), its shear coordinates uniquely determines a complete hyperbolic metric with finite area,

$$\Theta_{\mathcal{T}}: \Omega_{\mathcal{T}} \to T_H(S - V)$$
 (8)

this gives local coordinates of the Teichmüller space, where

$$\Omega_{\mathcal{T}} = \left\{ x \in \mathbb{R}^{\mathcal{E}(\mathcal{T})} \Big| \sum_{e \sim v} x(e) = 0, \ \forall v \in V(\mathcal{T}) \right\}$$

Then  $(\Omega_T, \Theta_T^{-1})$  form a local chart of  $T_H(S - V)$ .

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### Definition (Atlas of the Teichmüller Space)

Let  $\mathcal{T}$  be an arbitrary triangulation of (S, V), then  $\mathcal{T}$  corresponds to a local chart  $(\Omega_{\mathcal{T}}, \Theta_{\mathcal{T}}^{-1})$ . By exhausting all possible triangualtions of (S, V), all the local charts form an atlas of the Teichmüller space  $T_H(S - V)$ ,

$$\mathcal{A}(T_{H}(S-V)) = \bigcup_{\mathcal{T}} \left(\Omega_{\mathcal{T}}, \Theta_{\mathcal{T}}^{-1}\right).$$

#### Lemma

Given a closed marked surface (S, V),  $\chi(S - V) < 0$ 

$$T_D(S, V) = T_H(S - V) \times \mathbb{R}_{>0}^{|V|}.$$
 (9)

#### Proof.

Any decorated hyperbolic metric on (S, V, T) can be represented as  $(\mathbf{h}, \mathbf{w})$ , where  $\mathbf{h}$  is a complete hyperbolic metric on S - V with finite area,  $\mathbf{h} \in T_H(S - V)$ ;  $\mathbf{w}$  is the lengths of intersections between the horospheres and the surface.

The Teichmüller space of all PL metrics has a cell decomposition, each cell

$$D_{pl}(\mathcal{T}) = \{ [\mathbf{d}] \in T_{pl}(S, V) | \mathcal{T} \text{ is Delaunay under } \mathbf{d} \}$$

We show  $D_{pl}(\mathcal{T})$  is simply connected. We change the edge length x(e) to Rivin coordinates y(e),  $y(e) = \alpha + \alpha'$ . Then the edge lengths of  $(S, V, T, \mathbf{d})$  are determined by the Rivin's coordinates unique to a scaling,

$$D_{pl}(\mathcal{T}) = \{y(e) \in (0,\pi) | e \in E(\mathcal{T})\} imes \mathbb{R}_{>0}$$

is a convex set.  $D_{pl}$  is simply connected.

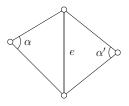


Figure: Rivin coordinates.

### Cell Decomposition of $T_{pl}(S, V)$

The Teichmüller of the PL metrics has the cell decomposition:

$$T_{pl}(S,V) = \bigcup_{\mathcal{T}} D_{pl}(\mathcal{T}).$$

### Cell Decomposition of $T_D(S, V)$

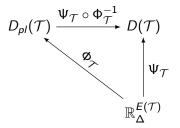
The Teichmüller space of the decorated hyperbolic metrics has the cell decomposition:

$$T_D(S,V) = \bigcup_{\mathcal{T}} D(\mathcal{T}).$$

where the cell

 $D(\mathcal{T}) = \{(\mathbf{d}, \mathbf{w}) \in T_D(S, V) | \mathcal{T} \text{ is Delaunay under } (\mathbf{d}, \mathbf{w}) \}.$ 

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We use Penner's  $\lambda\text{-length}$  to establish the diffeomorphism between two cells,

$$A_{\mathcal{T}} = \Psi_{\mathcal{T}} \circ \Phi_{\mathcal{T}}^{-1} : D_{pl}(\mathcal{T}) \to D(\mathcal{T}), \ x(e) \mapsto 2 \mathrm{ln} x(e)$$

Penner's  $\lambda$ -length maps Euclidean Delaunay triangulation to decorated hyperbolic Delaunay triangulation. Furthermore Delaunay property implies triangle inequality, hence  $A_T$  is a diffeomorphism.

Suppose triangulations  $\mathcal{T}$  and  $\mathcal{T}'$  differ by an edge swap, consider a polyhedral metric  $[d] \in D_{pl}(\mathcal{T}) \cap D_{pl}(\mathcal{T}')$ , then under d, there are four co-circle vertices in  $(\mathcal{T})$  and  $(\mathcal{T})'$ . By Ptolemy equality, we obtain for any  $x \in \Phi_{\mathcal{T}}^{-1}(D_{pl}(\mathcal{T}) \cap D_{pl}(\mathcal{T}'))$ ,

$$\Phi_{\mathcal{T}}^{-1} \circ \Phi_{\mathcal{T}'}(x) = \Psi_{\mathcal{T}}^{-1} \circ \Psi_{\mathcal{T}'}(x)$$

this is equivalent to

$$A_{\mathcal{T}}|_{D_{pl}(\mathcal{T})\cap D_{pl}(\mathcal{T}')} = A_{\mathcal{T}'}|_{D_{pl}(\mathcal{T})\cap D_{pl}(\mathcal{T}')}$$

In this way, we glue the piecewise diffeomorphisms  $A_T$  to form a global diffeomorphism:

$$A: T_{pl}(S, V) \to T_D(S, V), \ A|_{D_{pl}(\mathcal{T})} = A_{\mathcal{T}}|_{D_{pl}(\mathcal{T})}$$

Further proof shows this mapping is globally  $C^1$  diffeomorphic.

### Existence Proof

First, we construct a map:  $F: \Omega_u \to \Omega_K$ ,

$$\Omega_{u} \xrightarrow{\exp} \{p\} \times \mathbb{R}_{>0}^{|V|} \to T_{D}(S, V) \xrightarrow{A^{-1}} T_{pl}(S, V) \xrightarrow{K} \Omega_{K}$$
(10)

where the domain  $\Omega_u$  is the intersection between the discrete conformal factor space and the Euclidean hyperplane

$$\Omega_u = \mathbb{R}^n \cap \left\{ \mathbf{u} \Big| \sum_{i=1}^n u_i = 0 \right\}$$
(11)

the range  $\Omega_K$  is the discrete curvature space,

$$\Omega_{\mathcal{K}} = \left\{ \mathbf{K} \in (-\infty, 2\pi)^n \Big| \sum_{i=1}^n K_i = 2\pi\chi(S) \right\}$$
(12)

both of them are open sets in the Euclidean space  $\mathbb{R}^{n-1}$ . Because  $A: T_{pl}(S, V) \to T_D(S, V)$  is  $C^1$ ,  $K: T_{pl}(S, V) \to \mathbb{R}^n$  is real analytic, hence F is  $C^1$ .

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We show that the map  $F: \Omega_u \to \Omega_K$  is injective. Consider the convexity of the entropy energy

$$\mathcal{E}(\mathbf{u}) = \int^{\mathbf{u}} \sum_{i=1}^{n} K_i du_i.$$

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The Hessian Matrix is the discrete Laplace-Beltrami operator, hence the entropy is strictly convex on the domain  $\Omega_u$ . Furthermore, the domain  $\Omega_u$  is convex, the gradient of the entropy is the current discrete curvature. Hence, the map  $\mathbf{u} \mapsto \nabla \mathcal{E}(\mathbf{u}) = \mathbf{K}(\mathbf{u})$  is injective.

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We then show that the map  $F: \Omega_u \to \Omega_K$  is surjective. This requires domain inviarance theorem.

#### Theorem (Invariance of Domain)

Suppose U is a domain (connected open set) in  $\mathbb{R}^n$ , if  $f : U \to \mathbb{R}^n$  is continuous and injective, then V = f(U) is open, and f is a homeomorphism between U and V.

Because both  $\Omega_u$  and  $\Omega_K$  are all n-1 dimensional open sets, F is continuous and injective, hence  $F(\Omega_u)$  is an open set. And  $F: \Omega_u \to F(\Omega_u)$  is homeomorphic. We need to show  $\Omega_K = F(\Omega_u)$ .

### Existence Proof

Since  $F(\Omega_u)$  is open, we need to show  $F(\Omega_u)$  is closed in  $\Omega_K$ . We take a sequence  $\{x_k\} \subset \Omega_u$ , such that  $x_k$  leaves all the compact sets in  $\Omega_u$ . We need to show  $F(x_k)$  leaves all the compact sets in  $\Omega_K$ . We need the Akiyoshi theorem:

### Theorem (Akiyoshi(2001))

For any complete hyperbolic metric d on S - V with finite area, there exists finite number of isotopy classes of triangulations T, such that

 $[d]\times \mathbb{R}^n_{>0}\bigcap D(\mathcal{T})\neq \emptyset.$ 

Furthermore, there is finite number of triangulations  $\{\mathcal{T}_1, \ldots, \mathcal{T}_k\}$ , such that for any decoration  $\mathbf{w} \in \mathbb{R}^n_{>0}$ , the Delaunay triangulation of (d, w) is isotopic to one of such  $\mathcal{T}_i$ .

By Akiyoshi theorem,  $\{p\} \times \mathbb{R}^n_{>0}$  intersects  $\mathcal{T}_D(S, V)$  at a finite number of cells, hence we can assume the Delaunay triangulation  $\mathcal{T}$  is fixed.

 $\{x_k\}$  leaves all the compact sets in  $\Omega_u$ . By taking subsequences, we may assume that for each vertex  $v_i$ ,  $\lim_k x_i^{(k)} = t_i$  exists in  $[-\infty, +\infty]$ . Due to the normalization that  $\sum_i x_i^{(k)} = 0$  and  $x^{(k)}$  doesn't converge to any vector in  $\Omega_u$ , there exists  $t_i = \infty$  and  $t_j = -\infty$ . We label vertices by black and white. The vertex  $v_i$  is black if and only if  $t_i = -\infty$  and white otherwise.

### Lemma (Coloring)

- **(**) There doesn't exist a triangle  $\tau \in \mathcal{T}$  with exactly two white vertices.
- **2** If  $\Delta v_1 v_2 v_3$  is a triangle in  $\mathcal{T}$  with exactly one white vertex at  $v_1$ , then the inner angle at  $v_1$  converges to 0 as  $k \to \infty$  in the metric  $d_k$ .

# Existence Proof

### Proof.

To see (1), suppose otherwise, there exists a Euclidean triangle of lengths  $a_i e^{u_j^{(n)} + u_k^{(n)}}$ ,  $\{i, j, k\} = \{1, 2, 3\}$ , where  $\lim_n u_i^{(n)} > -\infty$  for i = 2, 3 and  $\lim_{n} u_1^{(n)} = -\infty$ . By the triangle inequality, we have

$$a_2e^{u_1^{(n)}+u_3^{(n)}}+a_3e^{u_1^{(n)}+u_2^{(n)}}>a_1^{u_2^{(n)}+u_3^{(n)}}$$

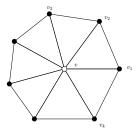
This is the same as

$$a_2e^{-u_2^{(n)}}+a_3e^{-u_3^{(n)}}>a_1^{-u_1^{(n)}}$$

However, the left-hand-side is bounded, the right-hand-side tends to  $\infty$ . The contradiction shows (1) holds.

To see (2), the triangle is similar to one with edge lengths,  $\{a_1e^{-u_1^{(n)}}, a_2e^{-u_2^{(n)}}, a_3e^{-u_3^{(n)}}\},$  converge to  $\{c, \infty, \infty\}$ , hence the angle  $\alpha_1$ tends to 0. 36 / 55

## **Existence** Proof



We now finish the proof of  $F(\Omega_u) = \Omega_k$  as follows. Since the surface S is connected, there exists an edge e whose end points  $v, v_1$  have different colors. Assume v is white and  $v_1$  is black. Let  $v_1, \ldots, v_k$  be the set of all vertices adjacent to v so that  $v, v_i, v_{i+1}$  form vertices of a triangle and let  $v_{k+1} = v_1$ . Now apply above lemma to triangle  $\Delta vv_1v_2$  with v white and  $v_1$  black, we conclude that  $v_2$  must be black. Inductively, we conclude that all  $v_i$ 's, for  $i = 1, 2, \ldots, k$ , are black. By part (2) of the above lemma, we conclude that the curvature of  $d_n$  at v tends to  $2\pi$ . This shows that  $F(\Omega_u^{(n)})$  tends to  $\infty$  of  $\Omega_k$ . Therefore  $F(\Omega_u) = \Omega_k$ ,  $\Box_{\mathcal{O}} = 1$ .

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## **Convergence Theorem**

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### Definition ( $\delta$ -Triangulation)

Given a compact polyhedral surface  $(S, V, \mathbf{d})$ , a triangulation  $\mathcal{T}$  is a  $\delta$ -triangulation,  $\delta > 0$ , if all the inner angles of each face is in the interval  $(\delta, \pi/2 - \delta)$ .

### Definition $((\delta, c)$ Subdivision Sequence)

Given a compact triangulated polyhedral surface  $(S, \mathcal{T}, l^*)$ , a geometric subdivision sequence  $(\mathcal{T}_n, l_n^*)$  of  $(\mathcal{T}, l^*)$  is a  $(\delta, c)$  subdivision sequence, where  $\delta > 0$ , c > 1 are positive numbers, if every  $(\mathcal{T}_n, l_n^*)$  is a  $\delta$ -triangulation, and the edge lengths satisfy

$$I_n^*(e) \in \frac{1}{n}\left(\frac{1}{c},c\right), \ \, orall e \in E(\mathcal{T}_n).$$

In the above definition, polyhedral surfaces can be replaced by general Riemann surfaces, triangulations can be replaced by geodesic triangulations, the lengths are replaced by geodesic lengths, to obtain the so-called  $(\delta, c)$  geodesic subdvision sequence.

### Theorem (Convergence of Discrete Curvature Flow)

Given a curved triangle with a Riemannian metric  $(S, \mathbf{g})$ , three corner angles are  $\pi/3$ . Given a  $(\delta, c)$  geodesic subdivision sequence  $(\mathcal{T}_n, L_n)$ , for any edge  $e \in E(\mathcal{T}_n)$ ,  $L_n(e)$  is geodesic length under the metric  $\mathbf{g}$ . Then there exists discrete conformal factor  $w_n \in \mathbb{R}^{V(\mathcal{T}_n)}$ , for n big enough,  $C_n = (S, \mathcal{T}_n, w_n * L_n)$ , such that

- a.  $C_n$  is isometric to the planar equilateral triangle  $\triangle$ , and  $C_n$  is  $\delta_{\Delta}/2$ -triangulation, where the constant  $\delta_{\Delta}$  doesn't depend on the surface;
- b. Discrete uniformization maps  $\varphi_n : C_n \to \triangle$ , satisfy

$$\lim_{n \to \infty} \| \varphi_n |_{V(\mathcal{T}_n)} - \varphi |_{V(\mathcal{T}_n)} \|_{\infty} = 0,$$
(13)

uniformly converge to the smooth uniformization map  $\varphi: (S, \mathbf{g}) \rightarrow (\triangle, dzd\overline{z}).$ 

#### Lemma

Suppose  $(S, \mathbf{g}_1)$  is a  $C^2$  smooth compact surface, its boundary  $\partial S$  may be non-empty with corners,  $\mathbf{g}_2 = e^{2\mu}\mathbf{g}_1$  is another Riemannian metric, conformal equivalent to the original metric, where the conformal factor  $\mu \in C^2(S)$  is a  $C^2$  smooth function. Then there exists constant  $c = c(S, \mathbf{g}_1, \mu)$ , such that for any geodesic connecting a pair of points p and q, or  $\gamma$  is a boundary curve segment,  $\gamma \subset \partial S$ , we have the estimate

$$\left|l_{\mathbf{g}_2}(\gamma)-e^{rac{\mu(p)+\mu(q)}{2}}l_{\mathbf{g}_1}(\gamma)
ight|\leq c(S,\mathbf{g}_1,\mu)l_{\mathbf{g}_1}^3(\gamma)$$

# Estimate

#### Theorem

Given a compact triangulated polyhedral surface  $(S, \mathcal{T}, I^*)$ ,  $(S, \mathcal{T}_n, I^*_n)$  is a  $(\delta, c)$  geometric subvidision sequence;  $(S, \mathcal{T}_n, I_n)$  is another sequence of polyhedral metrics, satisfy the inequalities:  $|I_n(e) - I^*_n(e)| \le c_0/n^3$ ,  $\forall e \in E(\mathcal{T}_n)$ , where  $c_0 > 0$  is a positive constant, then there exists a constant  $c_1 = c_1(I^*, \delta, c, c_0)$ , and discrete conformal factor  $v_n \in \mathbb{R}^{V(\mathcal{T}_n)}$ , for n big enough,

• 
$$(\mathcal{T}_n, v_n * I_n)$$
 is  $\delta/2$ -triangulation,

Iscrete conformal factor

$$\|v_n\|_{\infty} \leq \frac{c_1(l^*,\delta,c,c_0)}{\sqrt{n}}$$

and we have the estimate

$$|l_n^*(e) - v_n * l_n(e)| \leq rac{c_2(l^*, \delta, c, c_0)}{n\sqrt{n}}, \quad \forall e \in E(\mathcal{T}_n)$$

David Gu (Stony Brook University)

Computational Conformal Geometry

# Planar Equilateral Triangle Subdivision Sequence

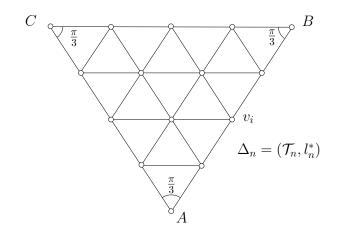


Figure: Planar equivaleteral triangle.

Planar equilateral triangle  $\triangle ABC$ , edge lengths are 1, corner angles are  $\pi/3$ . Every subdivision inserts middle points into the edges. After the *n*-th subdivision, the discrete surface is  $\triangle_n$ , its triangulation is  $\mathcal{T}_n$ , the PL metric is induced by the Euclidean planar metric  $dzd\bar{z}$ , represented as the length functions  $l_n^*$ . We use  $\triangle_n = (\triangle, \mathcal{T}_n, l_n^*)$  to represent this discrete surface, obviously  $\triangle_n$  is a  $(\delta, c)$  subdivision sequence, where  $(\delta_{\triangle}, c_{\triangle}) = (\pi/6 - \varepsilon, 1 - \varepsilon), \varepsilon > 0$  is a arbitrarily small positive number.

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## Surface Geodesics Subdivision Sequence

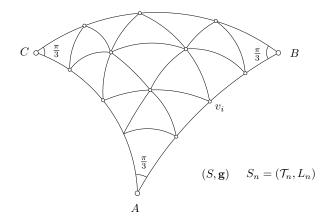


Figure: Smooth surface.

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Given a  $C^2$  smooth surface  $(S, \mathbf{g})$ , with three corner angles A, B, C.  $\partial S$  consists of three smooth curves, at each corner point, the intersection angle is  $\pi/3$ . There is a Riemann mapping  $\varphi : (S, \mathbf{g}) \to \Delta$ , which maps corners to corners, boundary curves to boundary line segments. The conformal factor induced by  $\varphi$  is a smooth bounded function,  $\mu : S \to \mathbb{R}$ ,

$$\mathbf{g}=^{-4\mu} dz dar{z}$$
 .

Simultaniously,  $\varphi$  pulls back the triangulation  $\mathcal{T}_n$  from  $\Delta_n$  to S. We replace every edge on  $\varphi^{-1}(\Delta_n)$  by geodesic segments, to obtain a geodesic triangulation, denoted as  $S_n = (S, \mathbf{g}, \mathcal{T}_n, \mathcal{L}_n)$ , where  $\mathcal{L}_n$  is the geodesic length of the triangulation  $\mathcal{T}_n$ . For any  $\varepsilon > 0$ , there exists  $N(\varepsilon)$ , when  $n > N(\varepsilon)$ ,  $S_n$  is a  $(\delta, c)$  geodesic subdivision sequence,  $(\delta, c) = (\pi/6 - \varepsilon, 1 - \varepsilon)$ .

# **Discretization Sequence**

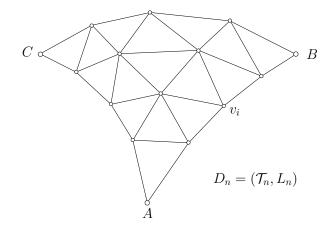


Figure: Discretization.

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We convert smooth geodesic subdivision sequence  $S_n(\mathcal{T}_n, L_n)$  to PL surface  $D_n = (\mathcal{T}_n, L_n)$ . For any face  $t \in \mathcal{T}_n$ , with edges  $\{e_i, e_j, e_k\}$ , we use  $\{L_n(e_i), L_n(e_j), L_n(e_k)\}$  as edge lengths to construct a Euclidean triangle, then isometrically glue these Euclidean triangles. Then  $(D_n, L_n)$  is a  $(\delta, c)$ -subdivision sequence, where  $c = c(S, \mathbf{g}, \mu)$ .

# Approximation Sequence

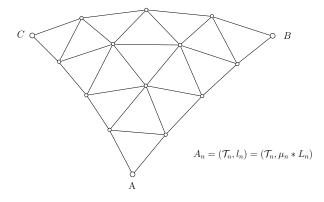


Figure: Approximation sequence.

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Smooth Riemann mapping  $\varphi : (S, \mathbf{g}) \to \Delta$  induces conformal factor  $\mu : S \to \mathbb{R}_{>0}$ ,  $dzd\bar{z} = e^{4\mu}\mathbf{g}$ . We define the discrete conformal factor:  $\mu_n : V(\mathcal{T}_n) \to \mathbb{R}_{>0}$ , for every vertex  $v_i \in \mathcal{T}_n$ ,

$$\mu_n(v_i) = \mu(\varphi^{-1}(v_i)), \quad v_i \in \Delta_n, \quad \varphi^{-1} : \Delta_n \to S.$$

We use  $D_n = (\mathcal{T}_n, L_n)$  to approximate  $(S_n, L_n)$ ,  $\mu_n$  to approximate  $\mu$ , then

$$A_n = (\mathcal{T}_n, \mu * L_n)$$

to approximate  $\Delta_n = (\mathcal{T}_n, l_n^*)$ . By the key lemma, for any  $e \in \mathcal{T}_n$ ,

$$|l_n^*(e) - \mu_n * L_n(e)| \le \frac{c_1}{n^3}, \quad c_1 = c_1(\mathbf{g}, \delta_S, c_S, dz d\bar{z}).$$
 (14)

# Compensation Sequence

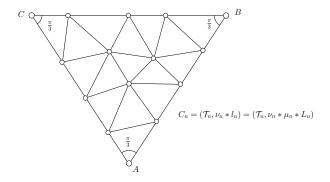


Figure: Compensation sequence.

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By the theorem, consider  $\Delta_n$  and  $A_n$  sequences, there exists discrete conformal factor  $\nu : V(\mathcal{T}_n) \to \mathbb{R}_{>0}$ , such that

• 
$$C_n = (\mathcal{T}_n, \nu_n * (\mu * L_n))$$
 is a  $\delta_{\Delta}/2$  triangulation;

**3**  $K_{\nu_n*\mu_n*L_n} = K_{l_n^*}$ , this implies  $C_n = \Delta$  is a planar equilateral triangle;

**③** the  $L^{\infty}$  norm of the conformal factor

$$\|\nu_n\|_{\infty} \leq \frac{c_2(\mathbf{g}^*, \delta_S, c_1, c_S)}{\sqrt{n}}$$

• for all edges  $e \in E(\mathcal{T}_n, \mathcal{T}_n)$ 

$$|l_n^*(e) - \nu_n * \mu_n * L_n(e)| \leq \frac{c_3(\mathbf{g}^*, \delta_S, c_1, c_S)}{n\sqrt{n}}$$

The outline of the proof is as follows:

 $\alpha_n$ : discretize the smooth surface using geodesic distance  $L_n$ ;  $\beta_n$ : use smooth conformal factor  $\mu_n$  to approximate uniformization map,  $\mu_n * L_n$ and planar Euclidean length  $l_n^*$  differ by  $O(n^{-3})$ ;  $\gamma_n$ : compensate the discrete error to obtain the discrete conformal factor  $\nu_n$ ,  $\nu_n * \mu_n * L_n$  and  $l_n^*$  differ by  $O(n^{-3/2})$ ;  $\varphi_n$ : piecewise linear map, the norm of the Beltrami coefficient of the quasi-conformal map  $\varphi_n$  is less than  $C/\sqrt{n}$ .

#### Proof.

We construct a piece-wise linear map  $\varphi_n : C_n \to \Delta_n$ . Since  $C_n$  and  $\Delta_n$  are equilateral triangles, by reflection, we can extend  $\varphi$  to  $\tilde{\varphi}_n : \mathbb{C} \to \mathbb{C}$ . Since  $C_n$  is a  $\delta_{\Delta}/2$  triangulation, there exists a positive number K > 1,  $\varphi_n$  is a K-quasi-conformal map. We obtain a family of K quasi-conformal maps from the complex plane to itself  $\{\tilde{\varphi}_n\}$ . By the compactness of quasi-conformal maps, there exists a convergent subsequence  $\{\tilde{\varphi}_{n_k}\}$ ,  $\lim_{k\to\infty} \tilde{\varphi}_{n_k} = \tilde{\varphi}$ . Let  $w_n = \mu_n + \nu_n$ , by inequality 14, we obtain

$$\lim_{k\to\infty}\frac{l_n^*(e)}{w_n*L_n(e)}=1.$$

Hence the dilatation of the limit map  $\tilde{\varphi} \ K = 1$ . Hence  $\tilde{\varphi}$  is conformal.