# Abel-Jacobi Theory 

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## Abel-Jacobi Theory

## Smooth Manifold



Figure: A manifold.

## Smooth Manifold

## Definition (Manifold)

A manifold is a topological space $M$ covered by a set of open sets $\left\{U_{\alpha}\right\}$. A homeomorphism $\phi_{\alpha}: U_{\alpha} \rightarrow \mathbb{R}^{n}$ maps $U_{\alpha}$ to the Euclidean space $\mathbb{R}^{n}$. $\left(U_{\alpha}, \phi_{\alpha}\right)$ is called a coordinate chart of $M$. The set of all charts $\left\{\left(U_{\alpha}, \phi_{\alpha}\right)\right\}$ form the atlas of $M$. Suppose $U_{\alpha} \cap U_{\beta} \neq \emptyset$, then

$$
\phi_{\alpha \beta}=\phi_{\beta} \circ \phi_{\alpha}^{-1}: \phi_{\alpha}\left(U_{\alpha} \cap U_{\beta}\right) \rightarrow \phi_{\beta}\left(U_{\alpha} \cap U_{\beta}\right)
$$

is a transition map.

## Riemann Surface

## Definition (Riemann Surface)

A two dimensional manifold $S$ is a Riemann surface, if the chart transition maps

$$
\phi_{\alpha \beta}=\phi_{\beta} \circ \phi_{\alpha}^{-1}: \phi_{\alpha}\left(U_{\alpha} \cap U_{\beta}\right) \rightarrow \phi_{\beta}\left(U_{\alpha} \cap U_{\beta}\right)
$$

are biholomorphic. On each local chart $\left(U_{\alpha}, \varphi_{\alpha}\right)$, we use $z_{\alpha}$ to denote the local complex coordinate. The atlas $\left\{\left(U_{\alpha}, z_{\alpha}\right)\right\}$ is called a conformal structure of the surface $S$.

## Riemann Surface

## Definition (Holomorphic Function)

Suppose $C$ is a Riemann surface, $\left\{\left(U_{i}, z_{i}\right)\right\}$ is a holomorphic coordinate covering. A meromorphic (holomorphic) function on $C$ is given by a family of map $f_{i}: U_{i} \rightarrow \mathbb{C}$, such that
(1) If $U_{i} \cap U_{j} \neq \emptyset$, on $U_{i} \cap U_{j}$ we have

$$
f_{i}=f_{j}
$$

(2) $\forall i, f_{i} \circ z_{i}^{-1}$ is a meromorphic (holomorphic) function.

All the meromorphic functions on $C$ form a field, denoted as $K(C)$, called the meromorphic function field on $C$.

## Riemann Surface

## Definition (Zeros and Poles)

Suppose $C$ is a compact Riemann surface, $f \in K(C), p \in C$. Choose a local coordinates $z$ of the neighborhood of $p$, such that $z(p)=0$, then in the neighborhood

$$
f(z)=z^{\nu} h(z)
$$

where $h(z)$ is a holomorphic function, $h(0) \neq 0, \nu \in \mathbb{Z} . \nu$ is called the order of $f$ at $p$, denoted as $\nu_{p}(f)$. when $\nu_{p}(f)>0$, pis called a zero of $f$, $\nu_{p}(f)$ is called the order of the zero $p$; when $\nu_{p}(f)<0, p$ is called a pole of $f,\left|\nu_{p}(f)\right|$ is called the order of the pole $p$.

## Holomorphic Differential



Figure: Holomorphic 1-form on a genus two surface.

## Riemann Surface

## Definition (Meromorphic Differential)

Suppose $S$ is a Riemann surface with a conformal structure $\left\{\left(U_{\alpha}, z_{\alpha}\right)\right\}$, a complex differential 1-form $\omega$ is called a meromorphic (holomorphic) 1-form (meromorphic differential), if on each local chart $\left(U_{\alpha}, \varphi_{\alpha}\right)$, its local representation is

$$
\omega=f_{\alpha}\left(z_{\alpha}\right) d z_{\alpha}
$$

where $f_{\alpha}$ is a meromorphic (holomorphic) function, and on the other chart $\omega=f_{\beta}\left(z_{\beta}\right) d z_{\beta}$,

$$
f_{\alpha}\left(z_{\alpha}\right)=f_{\beta}\left(z_{\beta}\left(z_{\alpha}\right)\right) \frac{d z_{\beta}}{d z_{\alpha}}
$$

The zeros and poles of $\omega$ are those of $f_{\alpha}$ 's.
All the meromrophic (holomorhic) 1-forms on $C$ is denoted as $K^{1}(C)\left(\Omega^{1}(C)\right)$.

## Residue Theorem

## Definition (Residue)

Let $C$ be a Riemann surface, $\omega \in K^{1}(C), p \in C, \gamma_{p}$ is a small circle around the point $p, \omega$ has no other pole except $p$ ( $p$ itself may be or may be not a pole). Then the residue of $\omega$ at $p$ is defined as

$$
\operatorname{Res}_{p}(\omega)=\frac{1}{2 \pi i} \oint_{\gamma_{p}} \omega
$$

Locally, $p \in U_{j}, \gamma_{p} \subset U_{j}$, we have

$$
\operatorname{Res}_{p}(\omega)=\frac{1}{2 \pi i} \oint_{\gamma_{p}} \omega=\frac{1}{2 \pi i} \oint f_{j}\left(z_{j}\right) d z_{j}=\operatorname{Res}_{p}\left(f_{j}\left(z_{j}\right) d z_{j}\right)
$$

## Residue Theorem

## Theorem (Residue)

Suppose $C$ is a compact Riemann surface, for $\omega \in K^{1}(C)$, we have

$$
\sum_{p \in C} \operatorname{Res}_{p}(\omega)=0
$$

## Proof.

Since $C$ is compact, $\omega$ has finite number of poles on $C$, denoted as $p_{1}, p_{2}, \ldots, p_{m}$. Choose small disks $\Delta_{1}, \Delta_{2}, \ldots, \Delta_{m}$ surrounding these poles. Denote

$$
\Omega=C \backslash \bigcup_{i} \Delta_{i}, \quad \partial \Omega=-\bigcup_{i} \partial \Delta_{i}
$$

By Stokes, we have
$2 \pi i \sum_{p \in C} \operatorname{Res}_{p}(\omega)=2 \pi i \sum_{j=1}^{m} \operatorname{Res}_{p_{j}}(\omega)=\sum_{j=1}^{m} \int_{\partial \Delta_{j}} \omega=-\int_{\partial \Omega} \omega=-\int_{\Omega} d \omega=0$.

## Residue Theorem

## Theorem (Meromorphic Function)

 If $f \in K(C)$ is not a constant function, then$$
\sum_{p \in C} \nu_{p}(f)=0 .
$$

## Proof.

Construct

$$
\omega=\frac{d f}{f} \in K^{1}(C)
$$

then the residue of $\omega$ is zero. Then means

$$
\#\{\text { zeros of } f\}=\#\{\text { poles of } f\}
$$

## Principle Divisor

## Theorem

If $f \in K(C)$ is not a constant, then

$$
\operatorname{deg}(f)=\sum_{p \in C} \nu_{p}(f)=0
$$

## Proof.

The meromorphic function $f$ on $C$ induces a conformal map $f: C \rightarrow \mathbb{S}^{2}$, suppose the mapping degree is $k$, then the preimages of the south pole are the zeros of $f$, the preimages of the north pole are the poles of $f$. The number of zeros equals to the mapping degree $k$, the number of poles equals to the mappping degree $k$ as well.

## Jacobi Variety

Suppose $C$ is a $g \geq 1$ compact Riemann surface. $H_{1}(C, \mathbb{Z})$ is a rank $2 g$ free Abel group. Choose a canonical basis of $H_{1}(C, \mathbb{Z})\left\{\gamma_{1}, \gamma_{2}, \cdots, \gamma_{2 g}\right\}$,

$$
\gamma_{i} \cdot \gamma_{g+i}=1, \quad \gamma_{g+i} \cdot g_{i}=-1
$$

and the other algebraic intersection numbers are zeros. $\left\{\omega_{1}, \omega_{2}, \cdots, \omega_{g}\right\}$ is a set of basis of $\Omega^{1} C$,

## Definition (Period Vector)

For each $\gamma_{i}$,

$$
\pi_{j}=\left(\begin{array}{c}
\int_{\gamma_{j}} \omega_{1} \\
\int_{\gamma_{j}} \omega_{2} \\
\vdots \\
\int_{\gamma_{j}} \omega_{g}
\end{array}\right) \in \mathbb{C}^{g} \quad(j=1,2, \ldots, 2 g)
$$

## Hyperbolic Geodesic



## Period Matrix

## Definition (Period Matrix)

The matrix

$$
\Pi:=\left(\pi_{1}, \pi_{2}, \cdots, \pi_{2 g}\right)_{g \times 2 g}
$$

is called the period matrix of the Riemann surface.

## Definition (Jacobi Variety)

The period vectors generate a lattice

$$
\Lambda:=\left\{\sum_{j=1}^{2 g} m_{j} \pi_{j} \mid m_{j} \in \mathbb{Z}\right\} \quad \subset \mathbb{C}^{g}
$$

The quotient space $\mathbb{C}^{g} / \Lambda$ is a $g$ dimensional complex torus, and called the Jacobi variety of $C$, denoted as $J(C)$.

## Riemann Bilinear Relation

Suppose $\gamma \subset C$ is a closed loop, slice $C$ along $\gamma$ to obtain $\bar{C}=C \backslash\{\gamma\}$. $\partial \bar{C}=\gamma^{+}-\gamma^{-}$. Set a function $f: \bar{C} \rightarrow \mathbb{R}$, such that $\left.f\right|_{\gamma^{+}}=+1$ and $\left.f\right|_{\gamma^{-}}=0$. The $\omega_{\gamma}=d f$ is a closed 1-form on $C$, which is called the 1-form corresponding to $\gamma$, such that for any loop $\tau$,

$$
\tau \cdot \gamma=\int_{\tau} \omega_{\gamma}
$$

Suppose $\left\{a_{1}, b_{1}, a_{2}, b_{2}, \cdots, a_{g}, b_{g}\right\}$ is a set of canonical basis of $H_{1}(C, \mathbb{Z})$, $\alpha_{k}$ is corresponding to $b_{k},-\beta_{k}$ corresponding to $a_{k}$, then

$$
\begin{aligned}
& a_{k} \cdot b_{k}=\int_{a_{k}} \alpha_{k}=\iint \alpha_{k} \wedge \beta_{k}=1 \\
& b_{k} \cdot a_{k}=-\int_{b_{k}} \beta_{k}=-\iint \alpha_{k} \wedge \beta_{k}=-1
\end{aligned}
$$

Namely, the period of $\alpha_{k}$ along $a_{k}$ is 1 , the period of $\beta_{k}$ along $b_{k}$ is 1 . The other integrations equal to zero.

## Riemann Bilinear Relation

## Lemma

$\left(\alpha_{1}, \cdots, \alpha_{g}, \beta_{1}, \cdots, \beta_{g}\right)$ is a basis of $H_{\Delta}^{1}(C, \mathbb{R})$. For any closed 1-form $\omega$, we have the decomposition:

$$
\omega=\sum_{i=1}^{g} A_{i} \alpha_{i}+\sum_{i=1}^{g} B_{i} \beta_{i}+d f
$$

where

$$
A_{i}=\int_{a_{i}} \omega, \quad B_{j}=\int_{b_{j}} \omega .
$$

## Lemma

Suppose $\theta$ and $\omega$ are closed 1-forms, then

$$
\iint_{C} \theta \wedge \omega=\sum_{i=1}^{g}\left[\int_{a_{i}} \theta \int_{b_{i}} \omega-\int_{a_{i}} \omega \int_{b_{i}} \theta\right]
$$

## Riemann Bilinear Relation

Assume the $A$-period of $\theta$ is $\left(A_{1}, \cdots, A_{g}\right)$, the $B$-period of $\theta$ is $\left(B_{1}, \cdots, B_{g}\right)$, the $A$-period of $\omega$ is $\left(A_{1}^{\prime}, \cdots, A_{g}^{\prime}\right)$, the $B$-period of $\omega$ is $\left(B_{1}^{\prime}, \cdots, B_{g}^{\prime}\right)$, then

$$
\theta=\sum_{i=1}^{g} A_{i} \alpha_{i}+\sum_{j=1}^{g} B_{j} \beta_{j}+d f, \omega=\sum_{i=1}^{g} A_{i}^{\prime} \alpha_{i}+\sum_{j=1}^{g} B_{j}^{\prime} \beta_{j}+d h,
$$

Note that $d(f \theta)=d f \wedge d \theta+f d^{2} \theta$ and

$$
\int_{C} d f \wedge \theta=\int_{\partial C} f \theta=0 \quad \iint_{C} \alpha_{i} \wedge \beta_{i}=1
$$

the others are 0 , by direct computation

$$
\iint_{C} \theta \wedge \omega=\sum_{i=1}^{g}\left(A_{i} B_{i}^{\prime}-A_{i}^{\prime} B_{i}\right)=\sum_{i=1}^{g}\left[\int_{a_{i}} \theta \int_{b_{i}} \omega-\int_{a_{i}} \omega \int_{b_{i}} \theta\right] .
$$

## Riemann Bilinear Relation

## Theorem (Riemann Bilinear Relation I)

Suppose $\varphi$ and $\varphi^{\prime}$ are holomorphic 1-forms. The A-period and B-period for $\varphi$ are $A_{i}$ and $B_{i}$, those for $\varphi^{\prime}$ are $A_{i}^{\prime}$ and $B_{i}^{\prime},(1 \leq i \leq g)$, then

$$
\sum_{i=1}^{g}\left(A_{i} B_{i}^{\prime}-B_{i} A_{i}^{\prime}\right)=0
$$

## Proof.

$$
\begin{equation*}
0=\iint \varphi \wedge \varphi^{\prime}=\sum_{i=1}^{g}\left(A_{i} B_{i}^{\prime}-A_{i}^{\prime} B_{i}\right) \tag{1}
\end{equation*}
$$

## Riemann Bilinear Relation

## Theorem (Riemann Bilinear Relation II)

Suppose $\varphi$ is a holomorphic 1-forms. The $A$-period and B-period for $\varphi$ are $A_{i}$ and $B_{i}$, then

$$
\sqrt{-1} \sum_{i=1}^{g}\left(A_{i} \bar{B}_{i}-B_{i} \bar{A}_{i}\right) \geq 0
$$

## Proof.

$$
\begin{equation*}
\|\varphi\|=(\varphi, \varphi)=i \iint \varphi \wedge \bar{\varphi}=\sum_{i=1}^{g}\left(A_{i} \bar{B}_{i}-A_{i} \bar{B}_{i}\right) \geq 0 \tag{2}
\end{equation*}
$$

## Period Matrix

## Theorem (Period Matrix)

Suppose $C$ is a compact Riemann surface, the period matrix $\Pi$ under a canonical basis of $H_{1}(C, \mathbb{Z})$ and a basis of $\Omega^{1}(C)$ is

$$
\Pi_{g \times 2 g}=\left(A_{g \times g}, B_{g \times g}\right),
$$

then we have
(1) $A B^{T}=B A^{T}$
(2) $\sqrt{-1}\left(A \bar{B}^{T}-B \bar{A}^{T}\right)$ is a Hermite positive definite matrix.

## Period Matrix

## Proof.

$$
\begin{array}{r}
A=\left(\begin{array}{cccc}
\int_{a_{1}} \varphi_{1} & \int_{a_{2}} \varphi_{1} & \cdots & \int_{a_{g}} \varphi_{1} \\
\int_{a_{1}} \varphi_{2} & \int_{a_{2}} \varphi_{2} & \cdots & \int_{a_{g}} \varphi_{2} \\
\vdots & \vdots & & \vdots \\
\int_{a_{1}} \varphi_{g} & \int_{a_{2}} \varphi_{g} & \cdots & \int_{a_{g}} \varphi_{g}
\end{array}\right) B=\left(\begin{array}{cccc}
\int_{b_{1}} \varphi_{1} & \int_{b_{2}} \varphi_{1} & \cdots & \int_{b_{g}} \varphi_{1} \\
\int_{b_{1}} \varphi_{2} & \int_{b_{2}} \varphi_{2} & \cdots & \int_{b_{g}} \varphi_{2} \\
\vdots & \vdots & & \vdots \\
\int_{b_{1}} \varphi_{g} & \int_{b_{2}} \varphi_{g} & \cdots & \int_{b_{g}} \varphi_{g}
\end{array}\right) \\
\left(A B^{T}\right)_{i, j}=\sum_{k=1}^{g} \int_{a_{k}} \varphi_{i} \int_{b_{k}} \varphi_{j} \quad\left(B A^{T}\right)_{i, j}=\sum_{k=1}^{g} \int_{b_{k}} \varphi_{i} \int_{a_{k}} \varphi_{j}
\end{array}
$$

By Riemann bilinear relation:

$$
\sum_{k=1}^{g}\left(\int_{a_{k}} \varphi_{i} \int_{b_{k}} \varphi_{j}-\int_{b_{k}} \varphi_{i} \int_{a_{k}} \varphi_{j}\right)=0,
$$

## Period Matrix

## Proof.

Let $\omega=\lambda_{1} \varphi_{1}+\lambda_{2} \varphi_{2}+\cdots+\lambda_{g} \varphi_{g}$, then

$$
\begin{aligned}
(\omega, \omega) & =\sqrt{-1} \int \omega \wedge \bar{\omega}= \\
& =\left(\begin{array}{llll}
\lambda_{1} & \lambda_{2} & \cdots & \lambda_{g}
\end{array}\right) \sqrt{-1}\left(A \bar{B}^{T}-B \bar{A}^{T}\right)\left(\begin{array}{c}
\bar{\lambda}_{1} \\
\bar{\lambda}_{2} \\
\vdots \\
\bar{\lambda}_{g}
\end{array}\right) \\
& \geq 0 .
\end{aligned}
$$

Hence $\sqrt{-1}\left(A \bar{B}^{T}-B \bar{A}^{T}\right) \geq 0$. $\square$

## Period Matrix

We can change the basis of $\Omega^{1}(C)$ by $A^{-T}$ to obtain the normalized period matrix

$$
\Pi=(\lg Z)
$$

then the Riemann bilinear relation becomes
(1) $Z=Z^{T}$;
(2) The imginary part of $Z \operatorname{lmg}(Z)$ is a real positive definite matrix.

## Period Matrix

## Theorem (Torelli)

Two compact Riemann surfaces $C$ and $C^{\prime}$ are conformal equivalent, if and only if they share the same normalized period matrix under approproate canonical homology basis.

## Problem (Schotty)

Suppose $Z=Z^{\top}$, and the imaginary part of $Z$ is positive definite, under what other conditions such that $\left(I_{g} Z\right)$ is a period matrix of some Riemann surface ?

## Divisor

## Definition (Divisor)

Suppose $C$ is a compact Riemann surface, a divisor is a finite form of sum

$$
D=m_{1} p_{1}+m_{2} p_{2}+\cdots+m_{l} p_{l}
$$

where $m_{j} \in \mathbb{Z}, p_{j} \in C(j=1,2, \ldots, l)$. The degree of $D$ is defined as

$$
\operatorname{deg}(D)=\sum_{j=1}^{\prime} m_{j}
$$

All the divisors under the addition form an Abelian group, the so-called divisor group.

## Principle Divisor

## Definition (Principle Divisor)

Suppose $C$ is a compact Riemann surface, $f \in K(C)$ is a meromorphic function, the divisor of $f$ is defined by

$$
(f)=\sum_{p \in C} \nu_{p}(f) p
$$

which is called a principle divisor.

## Definition (Zero Degree Divisor Group)

Suppose $C$ is a compact Riemann surface, $\operatorname{Div}(C)$ is the divisor group of $C$, then

$$
\operatorname{Div}^{0}(C):=\{D \in \operatorname{Div}(C): \operatorname{deg} D=0\}
$$

## Abel-Jacobi Map

## Definition (Abel-Jacobi Map)

Suppose $C$ is a compact Riemann surface, choose a base point $q \in C$, the Abel-Jacobi map

$$
\mu: \operatorname{Div}(C) \rightarrow J(C)
$$

is given by

$$
\mu(D)=\left(\begin{array}{c}
\sum_{i=1}^{k} \int_{q}^{p_{i}} \omega_{1} \\
\sum_{i=1}^{k} \int_{q}^{p_{i}} \omega_{2} \\
\vdots \\
\sum_{i=1}^{k} \int_{q}^{p_{i}} \omega_{g-1} \\
\sum_{i=1}^{k} \int_{q}^{p_{i}} \omega_{g}
\end{array}\right) / \Lambda
$$

where $D=\sum_{i=1}^{k} n_{i} p_{i} \in \operatorname{Div}(C)$.

## Abel-Jacobi Theorem

## Theorem (Abel)

The homomorphism sequence

$$
K^{*}(C) \xrightarrow{()} \operatorname{Div}^{0}(C) \xrightarrow{\mu} J(C) \longrightarrow 0
$$

is exact, namely

$$
\operatorname{Img}()=\operatorname{Ker} \mu
$$

and $\mu$ is surjective.

## Abel-Jacobi Theorem

## Definition (Picard variety)

The quotient group

$$
\operatorname{Pic}(C):=\frac{\operatorname{Div}^{0}(C)}{\operatorname{lmg}()}
$$

is called the Picard variety of $C$.
Theorem (Abel)
The Abel-Jacobi map $\mu$ induces an isomorphism

$$
\operatorname{Pic}(C) \xrightarrow{\sim} J(C) .
$$

## Abel-Jacobi Theorem

## Lemma

$\operatorname{Img}() \subset$ Ker $\mu$, namely, for any $f \in K^{*}(C)$, denote $D=(f)$, then

$$
\mu(D)=0
$$

## Lemma

ker $\mu \subset \operatorname{Img}()$, namely, if $\mu(D)=0$, where $D \in \operatorname{Div}^{0}(C)$, then there exists an $f \in K^{*}(C)$, such that

$$
(f)=D
$$

## Lemma

The Abel-Jacobi map $\mu: \operatorname{Div}^{0}(C) \rightarrow J(C)$ is surjective.

## Proof for $\mu((f))=0$

Assume $f \in K^{*}(C)$, for any $t \in \mathbb{C} \cup\{\infty\}$, let

$$
D_{t}=f^{-1}(t) \in \operatorname{Div}(C)
$$

Obvious

$$
D=(f)=f^{-1}(0)-f^{-1}(\infty)=D_{0}-D_{\infty}
$$

we are going to prove $\mu\left(D_{t}\right)=$ const, $\in \mathbb{C} \cup\{\infty\}$, then

$$
\mu(D)=\mu\left(D_{0}\right)-\mu\left(D_{\infty}\right)=0
$$

this proves the lemma. In order to prove $\mu\left(D_{t}\right)=$ const, we consider its derivative

$$
\frac{d}{d t} \mu\left(D_{t}\right)=\frac{d}{d t}\left(\begin{array}{c}
\sum_{j=1} \int_{q}^{p_{j}(t)} \omega_{1} \\
\vdots \\
\sum_{j=1} \int_{q}^{p_{j}(t)} \omega_{g}
\end{array}\right)
$$

## Proof for $\mu((f))=0$



Figure: Proof for $\mu((f))=0$

## Proof for $\mu((f))=0$

For $t_{0} \in \mathbb{S}^{2}$, if $f^{-1}\left(t_{0}\right)$ has no branching point, then there exists a disk $\Delta \subset \mathbb{S}^{2}$ surrounding $t_{0}$, and $n$ disks $\Delta_{1}, \Delta_{2}, \cdots, \Delta_{n} \subset C$ surrounding $p_{1}\left(t_{0}\right), p_{2}\left(t_{0}\right), \cdots, p_{n}\left(t_{0}\right)$, such that for any $j=1,2, \cdots, n$,

$$
f: \Delta_{j} \rightarrow \Delta
$$

is biholomorphic. So we can use $z(p)=f(p)$ as the local coordinates of $\Delta_{j}$. Assume in this coordinates,

$$
\omega_{\alpha}=h_{\alpha} j(z) d z
$$

then

$$
\begin{aligned}
\frac{d}{d t} \int_{q}^{p_{j}(t)} \omega_{\alpha} & =\frac{d}{d t} \int_{q}^{p_{j}\left(t_{0}\right)} \omega_{\alpha}+\frac{d}{d t} \int_{p_{j}\left(t_{0}\right)}^{p_{j}(t)} \omega_{\alpha} \\
& =\frac{d}{d t} \int_{q}^{p_{j}\left(t_{0}\right)} \omega+\frac{d}{d t} \int_{t_{0}}^{t} h_{\alpha j}(z) d z=h_{\alpha}(t) .
\end{aligned}
$$

## Proof for $\mu((f))=0$

For $t_{0} \in \mathbb{S}^{2}$, if $f^{-1}\left(t_{0}\right)$ has no branching point, then there exists a disk $\Delta \subset \mathbb{S}^{2}$ surrounding $t_{0}$, and $n$ disks $\Delta_{1}, \Delta_{2}, \cdots, \Delta_{n} \subset C$ surrounding $p_{1}\left(t_{0}\right), p_{2}\left(t_{0}\right), \cdots, p_{n}\left(t_{0}\right)$, such that for any $j=1,2, \cdots, n$,

$$
f: \Delta_{j} \rightarrow \Delta
$$

is biholomorphic. So we can use $z(p)=f(p)$ as the local coordinates of $\Delta_{j}$. Assume in this coordinates,

$$
\omega_{\alpha}=h_{\alpha} j(z) d z
$$

then

$$
\begin{aligned}
\frac{d}{d t} \int_{q}^{p_{j}(t)} \omega_{\alpha} & =\frac{d}{d t} \int_{q}^{p_{j}\left(t_{0}\right)} \omega_{\alpha}+\frac{d}{d t} \int_{p_{j}\left(t_{0}\right)}^{p_{j}(t)} \omega_{\alpha} \\
& =\frac{d}{d t} \int_{q}^{p_{j}\left(t_{0}\right)} \omega+\frac{d}{d t} \int_{t_{0}}^{t} h_{\alpha j}(z) d z=h_{\alpha}(t) .
\end{aligned}
$$

## Proof for $\mu((f))=0$

On the other hand, in the neighborhood of $p_{j}(t)$, on the selected local coordinates on $\Delta_{j}$, we construct the meromorophic 1-form:

$$
\frac{\omega_{\alpha}}{f-t}=\frac{h_{\alpha j}(z) d z}{z-t}
$$

By direct computation

$$
2 \pi \sqrt{-1} \operatorname{Res}_{p_{j}(t)} \frac{\omega_{\alpha}}{f-t}=\oint_{\partial \Delta_{j}} \frac{\omega_{\alpha}}{f-t}=\oint_{\partial \Delta_{j}} \frac{h_{\alpha j}(z) d z}{z-t}=2 \pi \sqrt{-1} h_{\alpha j}(t)
$$

By the meromorphic differential residue theorem, we have

$$
\frac{d}{d t} \mu\left(D_{t}\right)=\frac{d}{d t} \sum_{j=1}^{n} \int_{q}^{p_{j}(t)} \omega_{\alpha}=\sum_{j=1}^{n} h_{\alpha j}(t)=\sum_{j=1}^{n} \operatorname{Res}_{p_{j}(t)} \frac{\omega_{\alpha}}{f-t}=0
$$

## Proof for $\mu((f))=0$

We use $R$ to represent the set of the branching points of $f$, then $\mu\left(D_{t}\right)$ is holomorphic outside the finite set $f(R)$, and

$$
\frac{d}{d t} \mu\left(D_{t}\right)=0
$$

It is obvious that $\mathbb{S}^{2} \backslash f(R)$ is connected, therefore at $t \in \mathbb{S}^{2} \backslash f(R)$ we have

$$
\mu\left(D_{t}\right)=\text { const }
$$

by Riemann extension theorem, we have $\mu\left(D_{t}\right)=$ const on the whole sphere $\mathbb{S}^{2}=\mathbb{P}^{1}$, hence

$$
\mu((f))=\mu\left(D_{0}\right)-\mu\left(D_{\infty}\right)=0 .
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

If $D \in \operatorname{Div}^{0}(C), \mu(D)=0$, we would like to find a meromorphic function $f \in K^{*}(C)$, such that $(f)=D$. Assume

$$
D=\sum_{i=1}^{k} n_{i} p_{i} \in \operatorname{Div}^{0}(C)
$$

if there is $f \in K^{*}(C)$, such that $(f)=D$, let

$$
\varphi=\frac{1}{2 \pi \sqrt{-1}} \frac{d f}{f} \in K^{1}(C)
$$

Then $\varphi$ must satisfiy
a) $(\varphi)_{\infty}=\sum_{i=1}^{k} p_{i}, \varphi$ only has simple poles
b) $\operatorname{Res}_{p_{i}} \varphi=\frac{n_{i}}{2 \pi \sqrt{-1}}, \quad n_{i} \in \mathbb{Z}$;
c) $\int_{\gamma_{i}} \varphi \in \mathbb{Z}$

## Proof for Ker $\mu \subset \operatorname{Img}()$

Eqn. (3) item c) holds, since

$$
\int_{\gamma_{i}} \varphi=\frac{1}{2 \pi \sqrt{-1}} \int_{\gamma_{i}} \frac{d f}{f}=\frac{1}{2 \pi \sqrt{-1}} \int d(\sqrt{-1} \arg f) \in Z
$$

## Lemma (Meromorphic Differential)

If $\varphi \in K^{1}(C)$, satisfying Eqn. (3). Assume $q$ is a fixed based point on $C$, let

$$
f(p)=\exp \left(2 \sqrt{-1} \pi \int_{q}^{p} \varphi\right)
$$

the integration path doesn't go through any pole of $\varphi$, then $f$ is a meromorphic function on $C$, satisfying

$$
(f)=\sum_{i=1}^{k} n_{i} p_{i}=D
$$

where $p_{i}, n_{i}$ are given in Eqn. (3) a) and b).

## Proof for Ker $\mu \subset \operatorname{Img}()$

Note that, based on Residue theorem $\sum_{i=1}^{k} n_{i}=0$, namely $D \in \operatorname{Div}^{0}(C)$.

## Proof.

Choose two paths $\gamma$ and $\gamma^{\prime}$ from $q$ to $p$, such that

$$
\gamma-\gamma^{\prime}=\sum_{i=1}^{2 g} n_{i} \gamma_{i}
$$

therefore

$$
\int_{\gamma} \varphi-\int_{\gamma^{\prime}} \varphi=\sum_{i=1}^{2 g} n_{i} \int_{\gamma_{i}} \varphi \in \mathbb{Z}
$$

therefore

$$
\exp \left(2 \pi \sqrt{-1} \int_{\gamma} \varphi\right)=\exp \left(2 \pi \sqrt{-1} \int_{\gamma^{\prime}} \varphi\right)
$$

therefore $f(p)$ is independent of the choice of the integration path, $f(p)$ is a well defined function on $C$.

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

Since $\varphi$ satisfies Eqn (3) a), $f$ is holomorphic on $C$ excepts on $p_{i}$ 's. In a neighborhood of $p_{i}$ with local coordinates $z, z\left(p_{i}\right)=0$, then

$$
\varphi(z)=\frac{n_{i}}{2 \pi \sqrt{-1}} \frac{d z}{z}+h(z) d z
$$

where $h(z)$ is holomorphic. Choose another point $p_{0}\left(p_{0} \neq p_{i}\right)$ in the neighborhood of $p_{i}$, suppose $z\left(p_{0}\right)=z_{0}$, then

$$
\begin{aligned}
f(z) & =\exp \left(2 \sqrt{-1} \pi \int_{q}^{p} \varphi\right)=\exp \left(2 \sqrt{-1} \pi\left(\int_{q}^{p_{0}} \varphi+\int_{p_{0}}^{p} \varphi\right)\right) \\
& =\exp \left(2 \sqrt{-1} \pi\left(\int_{q}^{p_{0}} \varphi+\int_{z_{0}}^{z} \frac{n_{i}}{2 \sqrt{-1} \pi} \frac{d z}{z}+\int_{z_{0}}^{z} h(z) d z\right)\right)
\end{aligned}
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

$=\exp \left(2 \sqrt{-1} \pi\left(\int_{q}^{p_{0}} \varphi-\frac{n_{i}}{2 \sqrt{-1} \pi} \ln z_{0}+-\frac{n_{i}}{2 \sqrt{-1} \pi} \ln z+\int_{z_{0}}^{z} h(z) d z\right)\right)$
$=c z^{n_{i}} H(z)$,
where

$$
c=\exp \left(2 \sqrt{-1} \pi\left(\int_{q}^{p_{0}} \varphi-\frac{n_{i}}{2 \sqrt{-1} \pi} \ln z_{0}\right)\right)
$$

is a non-zero constant,

$$
H(z)=\exp \left(2 \sqrt{-1} \pi \int_{z_{0}}^{z} h(z) d z\right)
$$

is a non-zero holomorphic function. Hence $(f)=\sum_{i=1}^{k} n_{i} p_{i}=D$.

## Proof for Ker $\mu \subset \operatorname{Img}()$

## Definition (Abelian Differential of The Third Kind)

If $\varphi \in K^{1}(C)$ has at most simple poles, then $\varphi$ is called a third type of differential. For any $p, q \in C, p \neq q, \varphi=\varphi_{p q} \in K^{1}(C)$ is called a third type of elementary differential, if

$$
(\varphi)_{\infty}=p+q
$$

and

$$
\operatorname{Res}_{p} \varphi=\frac{1}{2 \sqrt{-1} \pi}, \quad \operatorname{Res}_{q} \varphi=-\frac{1}{2 \sqrt{-1} \pi} .
$$

## Theorem (Existence of Abelian Differential of the Third Kind)

For any $p, q \in C, p \neq q$, there is a normal Abelian differential of the third kind $\varphi_{p q} \in K^{1}(C)$, such that $(\varphi)_{\infty}=p+q$ and

$$
\operatorname{Res}_{p} \varphi=(2 \sqrt{-1} \pi)^{-1}, \quad \operatorname{Res}_{q} \varphi=-(2 \sqrt{-1} \pi)^{-1} .
$$

## Abel Differential of the Third Type

## Proof.

Set the divisor $D=-p-q$, then by Riemann-Roch formula

$$
\operatorname{dim} /(-D)=\operatorname{dimi}(D)+d(D)+1-g,
$$

$-D \geq 0$, so $f \in I(-D)$ must be holomorphic, therefore $f \equiv$ const, $(f)=0$, but $0+D<0$, hence $\operatorname{dim} /(-D)=0$. Therefore

$$
0=\operatorname{dim} i(D)-2+1-g \Longrightarrow \operatorname{dim} i(D)=g+1
$$

Therefore we can pick $\omega \in i(D)$, then $\omega$ has poles at $p$ and $q$ only.

## Proof for Ker $\mu \subset \operatorname{Img}()$

## Proof.

For any divisor

$$
D=\sum_{i=1}^{k} p_{i}-\sum_{i=1}^{k} q_{i} \in \operatorname{Div}^{0}(C)
$$

( $p_{i}$ or $q_{i}$ may be repeated), there are $k$ normal Abelian differentials of the 3rd kind $\varphi_{1}, \varphi_{2}, \cdots, \varphi_{k}$, where $\varphi_{i}$ has simple poles at $p_{i}$ and $q_{i}$ with residues

$$
\operatorname{Res}_{p_{i}} \varphi_{i}=(2 \sqrt{-1} \pi)^{-1} \quad \operatorname{Res}_{q_{i}} \varphi_{i}=-(2 \sqrt{-1} \pi)^{-1} .
$$

Let

$$
\varphi=\varphi_{1}+\varphi_{2}+\cdots+\varphi_{k} .
$$

Choose canonical basis of $H_{1}(C, \mathbb{Z}) \gamma_{1}, \gamma_{2}, \cdots, \gamma_{2 g}$, which do not go through any pole of $\varphi ; \omega_{1}, \omega_{2}, \cdots, \omega_{g}$ is a basis of $\Omega^{1}(C)$, such that the period matrix is normalized to be (I Z).

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

Let

$$
\varphi^{\prime}=\varphi-\sum_{\alpha=1}^{g}\left(\int_{\gamma_{\alpha}} \varphi\right) \omega_{\alpha}
$$

Then $\varphi^{\prime}$ has the same poles and residues as $\varphi$, and the periods of $\varphi^{\prime}$ on $\gamma_{j}$ 's are zeros, $\pi_{j}\left(\varphi^{\prime}\right)=0$, for $j=1,2, \cdots, g$.

## Bilinear Relation between I and III Abel Differentials

## Lemma (Bilinear Relation between I and III Abel Differentials)

Suppose $\omega \in \Omega^{1}(C)$ is a holomorphic 1-form, then

$$
\begin{equation*}
\sum_{i=1}^{k} \int_{q_{i}}^{p_{i}} \omega=\sum_{i=1}^{g} \pi_{i}(\omega) \pi_{g+i}\left(\varphi^{\prime}\right) \tag{4}
\end{equation*}
$$

## Proof.

Suppose the fundamental polygon is

$$
\Omega=C-\bigcup_{i=1}^{2 g} \gamma_{i}
$$

choose a base point $b \in \Omega$, define a holomorphic function by integrating $\omega$ inside $\Omega$,

$$
\nu(p):=\int_{b}^{p} \omega \quad(p \in \Omega) .
$$

## Bilinear Relation between I and III Abel Differentials

## continued.

Then $\nu \varphi^{\prime}$ is a meromorphic differential, whose poles are the same as $\varphi^{\prime}$, by Residue theorem

$$
2 \sqrt{-1} \pi \sum_{i=1}^{k}\left(\operatorname{Res}_{p_{i}}\left(\nu \varphi^{\prime}\right)+\operatorname{Res}_{q_{i}}\left(\nu \varphi^{\prime}\right)\right)=\int_{\partial \Omega} \nu \varphi^{\prime}
$$

The left hand side equals to

$$
\sum_{i=1}^{k}\left(\nu\left(p_{i}\right)-\nu\left(q_{i}\right)\right)=\sum_{i=1}^{k} \int_{q_{i}}^{p_{i}} \omega
$$

The right hand side is $\left(\pi_{i}\left(\varphi^{\prime}\right)=0, i=1, \ldots, g\right)$

$$
\int_{\partial \Omega} \nu \varphi^{\prime}=\sum_{i=1}^{g}\left(\pi_{i}(\omega) \pi_{g+i}\left(\varphi^{\prime}\right)-\pi_{i}\left(\phi^{\prime}\right) \pi_{g+i}(\omega)\right)=\sum_{i=1}^{g} \pi_{i}(\omega) \pi_{g+i}\left(\varphi^{\prime}\right)
$$

## Bilinear Relation between I and III Abel Differentials



Figure: $\int_{a_{1}} \nu \varphi+\int_{a_{1}^{-1}} \nu \varphi=-\pi_{b_{1}}(\omega) \pi_{a_{1}}(\varphi), \nu=\int \omega$.

## Bilinear Relation between I and III Abel Differentials

## continued.

$$
\int_{\partial \Omega} \nu \varphi^{\prime}=\sum_{i=1}^{g}\left(\int_{\gamma_{i}} \nu \varphi^{\prime}+\int_{\gamma_{i}^{-1}} \nu \varphi^{\prime}+\int_{\gamma_{g+i}} \nu \varphi^{\prime}+\int_{\gamma_{g+i}^{-1}} \nu \varphi^{\prime}\right) .
$$

Choose $p \in \gamma_{i}$, the same point $p^{\prime} \in \gamma_{i}^{-1}$, then

$$
\begin{gathered}
\int_{\gamma_{i}} \nu \varphi^{\prime}+\int_{\gamma_{i}^{-1}} \nu \varphi^{\prime}=\int_{\gamma_{i}}\left(\nu(p)-\nu\left(p^{\prime}\right)\right) \varphi^{\prime}=-\pi_{g+i}(\omega) \pi_{i}\left(\varphi^{\prime}\right) . \\
\nu(p)-\nu\left(p^{\prime}\right)=\int_{p^{\prime}}^{p} \omega=\int_{p^{\prime}}^{q} \omega-\int_{\gamma_{g+i}} \omega+\int_{q}^{p} \omega=-\int_{\gamma_{g+i}} \omega=-\pi_{g+i}(\omega) .
\end{gathered}
$$

similarly

$$
\int_{\gamma_{g+i}} \nu \varphi^{\prime}+\int_{\gamma_{g+i}^{-1}} \nu \varphi^{\prime}=\int_{\gamma_{g+i}}\left(\nu(p)-\nu\left(p^{\prime}\right)\right) \varphi^{\prime}=\pi_{i}(\omega) \pi_{g+i}\left(\varphi^{\prime}\right)
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

By Eqn. (4), let $\omega=\omega_{\alpha}, \alpha=1,2, \cdots, g$

$$
\sum_{i=1}^{k} \int_{q_{i}}^{p_{i}} \omega_{\alpha}=\sum_{i=\beta}^{g} \pi_{\beta}\left(\omega_{\alpha}\right) \pi_{g+\beta}\left(\varphi^{\prime}\right)
$$

Since the period matrix id $(I Z), \pi_{\beta}\left(\omega_{\alpha}\right)=\delta_{\alpha \beta}$, the right hand side is $\pi_{g+\alpha}\left(\varphi^{\prime}\right)$. The left hand side is

$$
(\mu(D))_{\alpha}=\sum_{i=1}^{g} \int_{q}^{p_{i}} \omega_{\alpha}-\sum_{i=1}^{g} \int_{q}^{q_{i}} \omega_{\alpha}=\sum_{i=1}^{g} \int_{q_{i}}^{p_{i}} \omega_{\alpha}=0(\bmod \wedge)
$$

We obtain left hand side becomes $(\alpha=1,2, \cdots, g)$

$$
\sum_{\beta=1}^{g}\left(m_{\beta} \int_{\gamma_{\beta}} \omega_{\alpha}+m_{g+\beta} \int_{\gamma_{g+\beta}} \omega_{\alpha}\right)=m_{\alpha}+\sum_{\beta=1}^{g} m_{g+\beta} \int_{\gamma_{g+\beta}} \omega_{\alpha}
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

where $m_{\beta}, \beta=1,2, \cdots, 2 g$ are integers independent of $\alpha$. By Riemann bilinear relation $Z^{T}=Z$, we have

$$
\int_{\gamma_{g+\beta}} \omega_{\alpha}=\int_{\gamma_{g+\alpha}} \omega_{\beta} .
$$

The LHS becomes $m_{\alpha}+\sum_{\beta=1}^{g} m_{g+\beta} \int_{\gamma_{g+\alpha}} \omega_{\beta}$, the RHS is $\pi_{g+\alpha}\left(\varphi^{\prime}\right)$, hence

$$
\pi_{g+\alpha}\left(\varphi^{\prime}\right)=m_{\alpha}+\sum_{\beta=1}^{g} m_{g+\beta} \int_{\gamma_{g+\alpha}} \omega_{\beta}
$$

Then we define

$$
\varphi^{\prime \prime}:=\varphi^{\prime}-\sum_{\beta=1}^{g} m_{g+\beta} \omega_{\beta},
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

## Proof.

The $\varphi^{\prime \prime}$ has the same poles and residues as $\varphi^{\prime}$, so as $\varphi$,

$$
\left(\varphi^{\prime \prime}\right)_{\infty}=\sum_{i=1}^{k} p_{i} \quad \operatorname{Res}_{p_{i}} \varphi^{\prime \prime}=\frac{n_{i}}{2 \sqrt{-1 \pi}} .
$$

Now $\alpha=1,2, \cdots, g$

$$
\begin{aligned}
\pi_{\alpha}\left(\varphi^{\prime \prime}\right) & =\pi_{\alpha}\left(\varphi^{\prime}\right)-\sum_{\beta=1}^{g} m_{g+\beta} \pi_{\alpha}\left(\omega_{\beta}\right) \\
& =0-\sum_{\beta=1}^{g} m_{g+\beta} \delta_{\alpha \beta}=-m_{g+\alpha} \\
\pi_{g+\alpha}\left(\varphi^{\prime \prime}\right) & =\pi_{g+\alpha}\left(\varphi^{\prime}\right)-\sum_{\beta=1}^{g} m_{g+\beta} \pi_{g+\alpha}\left(\omega_{\beta}\right)=m_{\alpha}
\end{aligned}
$$

## Proof for Ker $\mu \subset \operatorname{Img}()$

## continued.

Since $\varphi^{\prime \prime}$ satisfies all three conditions in Eqn. (4), by the lemma of Meromrophic differential, we construct the meromorphic function

$$
f(p)=\exp \left(2 \sqrt{-1} \pi \int_{q}^{p} \varphi^{\prime \prime}\right)
$$

then

$$
(f)=D
$$

Hence $\operatorname{Ker} \mu \subset \operatorname{Img}()$. Therefore $\operatorname{Ker} \mu=\operatorname{Img}()$.

## Jacobi Theorem

## Lemma (Special Holomorphic Differential Basis)

Suppose $C$ is a compact genus $g$ Riemann surface, $(U, z)$ is a local coordinate chart of $C$, then there are $g$ distinct points $p_{1}, p_{2}, \cdots, p_{g}$ in $U$, and a basis of $\Omega^{1}(C)$ holomorphic differentials, such that the matrix

$$
\left(\begin{array}{cccc}
f_{1}\left(p_{1}\right) & f_{1}\left(p_{2}\right) & \cdots & f_{1}\left(p_{g}\right) \\
f_{2}\left(p_{1}\right) & f_{2}\left(p_{2}\right) & \cdots & f_{2}\left(p_{g}\right) \\
\vdots & \vdots & & \vdots \\
f_{g}\left(p_{1}\right) & f_{g}\left(p_{2}\right) & \cdots & f_{g}\left(p_{g}\right)
\end{array}\right)
$$

is non-degenerated, where $f_{i} d z$ is the local representation of $\varphi_{i}$.

## Jacobi Theorem

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f_{2}\left(p_{1}\right) & f_{2}\left(p_{2}\right) & \cdots & f_{2}\left(p_{g}\right) \\
\vdots & \vdots & & \vdots \\
f_{g}\left(p_{1}\right) & f_{g}\left(p_{2}\right) & \cdots & f_{g}\left(p_{g}\right)
\end{array}\right)
$$

is non-degenerated, where $f_{i} d z$ is the local representation of $\varphi_{i}$.

## Jacobi Theorem

## Proof.

Choose a non-zero holomorphic 1 -form $\varphi_{1}$, since $\varphi_{1} \not \equiv 0$ in $U$, there is a point $p_{1} \in U$, such that $\varphi_{1}\left(p_{1}\right) \neq 0$. By Riemann-Roch, let $D=p_{1}$

$$
\operatorname{dim} /\left(-p_{1}\right)=\operatorname{dimi}\left(p_{1}\right)+\operatorname{deg}\left(p_{1}\right)+1-g,
$$

suppose $f \in K(C),(f) \geq-p_{1}$. Any meromorphic (non-holomorphic) function must have multiple poles, so $f$ is holomorphic, $f \equiv$ const, so $I\left(-p_{1}\right)=1$.

$$
1=i\left(p_{1}\right)+1+1-g \Longrightarrow \operatorname{dimi}\left(p_{1}\right)=g-1
$$

We can choose a holomorphic 1-form $\varphi_{2} \in i\left(p_{1}\right)$, such that at some point $p_{2} \in U$,

$$
\varphi_{2}\left(p_{2}\right) \neq 0
$$

## Jacobi Theorem

## continued.

Since $\operatorname{dimi}\left(p_{1}\right)=\operatorname{dimi}\left(p_{2}\right)=g-1$, and $\operatorname{dim} \Omega^{1}(C)=g$, we have

$$
\Longrightarrow \operatorname{dimi}\left(p_{1}\right) \cap i\left(p_{2}\right)=i\left(p_{1}+p_{2}\right)=(g-1)+(g-1)-g=g-2 .
$$

This shows $\operatorname{dimi}\left(p_{1}+p_{2}\right)=g-2$, we can choose another holomorphic 1-form $\varphi_{3} \in i\left(p_{1}+p_{2}\right)$, such that $\varphi_{3}$ is non-zero at some point $p_{3} \in U$, $\varphi_{3}\left(p_{3}\right) \neq 0$. By repeating this procedure, we can obtain $g$ points $p_{1}, p_{2}, \cdots, p_{g} \in U$ and $g$ non-zero holomorphic 1-forms $\varphi_{1}, \varphi_{2}, \cdots, \varphi_{g}$, such that

$$
\varphi_{i}\left(p_{j}\right)=0, j=1,2, \cdots, i-1 ; \varphi_{i}\left(p_{i}\right) \neq 0
$$

If in $U, \varphi_{i}=f_{i} d z(i=1,2, \cdots, g)$, then the matrix

$$
\left(f_{i}\left(p_{j}\right)\right)_{g \times g}
$$

is triangular, and the diagonal elements are non-zeros. Therefore the matrix is non-degenerated, $\left\{\varphi_{i}\right\}$ form a basis of $\Omega^{1}(C)$.

## Special Holomorphic Differential Basis

$$
\left(\begin{array}{cccccc}
f_{1}\left(p_{1}\right) & f_{1}\left(p_{2}\right) & f_{1}\left(p_{3}\right) & \cdots & f_{1}\left(p_{g-1}\right) & f_{1}\left(p_{g}\right) \\
0 & f_{2}\left(p_{2}\right) & f_{2}\left(p_{3}\right) & \cdots & f_{2}\left(p_{g-1}\right) & f_{2}\left(p_{g}\right) \\
0 & 0 & f_{3}\left(p_{3}\right) & \cdots & f_{3}\left(p_{g-1}\right) & f_{3}\left(p_{g}\right) \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & 0 & f_{g}\left(p_{g}\right)
\end{array}\right)
$$

## Jacobi Theorem

Suppose $p_{1}, p_{2}, \cdots, p_{g}$ are $g$ points in the lemma of special holomorphic differential basis, $C^{g}:=C \times C \times, \cdots, \times C$, define

$$
\Psi: C^{g} \rightarrow \operatorname{Pic}(C), \quad \Psi\left(x_{1}, x_{2}, \cdots, x_{g}\right)=\sum_{i=1}^{g}\left(x_{i}-p_{i}\right) \quad \bmod \mathcal{P}
$$

where $\mathcal{P}$ is the set of principle divisors. Denote the composition map $\mu \circ \Psi$ as $J$.

$$
J: C^{g} \xrightarrow{\psi} \operatorname{Pic}(C) \xrightarrow{\mu} J(C) .
$$

## Theorem (Jacobi)

The map $\Psi: C^{g} \rightarrow \operatorname{Pic}(C)$ is surjective, $\mu: \operatorname{Pic}(C) \rightarrow J(C)$ is an isomorphism, hence $J: C^{g} \rightarrow J(C)$ is surjective.

## Jacobi Theorem

## Proof.

Suppose $D$ is a zero degree divisor. Consider the degree $g$ divisor,

$$
D^{\prime}=D+p_{1}+p_{2}+\cdots+p_{g}
$$

By Riemann-Roch formula, we have

$$
\operatorname{dim} /\left(-D^{\prime}\right)=\operatorname{dim} i\left(D^{\prime}\right)+d\left(D^{\prime}\right)+1-g \geq d\left(D^{\prime}\right)+1-g=1
$$

therefore there is a non-zero meromorphic function $f \in I\left(-D^{\prime}\right)$, $(f)+D^{\prime} \geq 0 . \operatorname{deg}\left((f)+D^{\prime}\right)=\operatorname{deg}((f))+\operatorname{deg}(D)+g=g$, hence

$$
(f)+D^{\prime}=x_{1}+x_{2}+\cdots+x_{g}, \quad x_{i} \in C, i=1,2, \cdots, g
$$

Namely $(f)+D=\sum_{i=1}^{g}\left(x_{i}-p_{i}\right)=\Psi\left(x_{1}, x_{2}, \cdots, x_{g}\right)$. This means $\Psi\left(x_{1}, x_{2}, \cdots, x_{g}\right)=[D] \in \operatorname{Pic}(C)$, namely $\Psi$ is surjective.

## Jacobi Theorem

## continued.

By Abel theorem, $\mu$ is injective. In order to show $\mu$ is isomorphic, it is surficient to show the image of $\mu$ contains an open set of $[0] \in J(C)$, in turn, we only need to show the image of $J=\mu \circ \Psi$ contains such an open set. Select $\left\{\varphi_{i}\right\}$ as the set of holomorphic 1 -form basis in lemma of special holomorphic differential basis. Choose disjoint small disks $B_{i} \subset U$ centered at $p_{i}$, the local coordinate on $B_{i}$ is $z$. In each $B_{i}$, choose $z_{i} \in B_{i}$, then

$$
\lambda=\left(z_{1}, z_{2}, \cdots, z_{g}\right) \in C^{g} .
$$

The local representation of $J$ is

$$
J\left(z_{1}, z_{2}, \cdots, z_{g}\right)=\left(\sum_{j=1}^{g} \int_{p_{j}}^{z_{j}} f_{1} d z, \sum_{j=1}^{g} \int_{p_{j}}^{z_{j}} f_{2} d z, \cdots, \sum_{j=1}^{g} \int_{p_{j}}^{z_{j}} f_{g} d z\right)
$$

where the integration paths are contained in each disk $B_{i}$ 's.

## Jacobi Theorem

## continued.

The $i$-th component of $F$ is $F_{i}$, then

$$
\frac{\partial F_{i}}{\partial z_{j}}=f_{i}\left(z_{j}\right)
$$

According to lemma of special holomorphic differential basis, the Jacobi matrix of $J$ at $\left(p_{1}, p_{2}, \cdots, p_{g}\right)$ is non-degenerated. By inverse mapping theorem, we know the image of $J$ contains an open set. This completes the proof.

