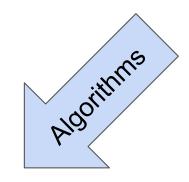
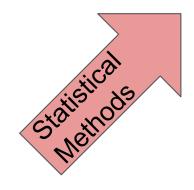
# "Hadoop": A Distributed Architecture, FileSystem, & MapReduce

Stony Brook University CSE545 - Spring 2019

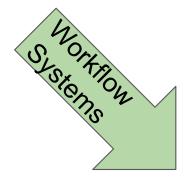


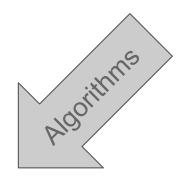


## Big Data Analytics

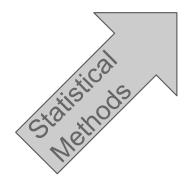


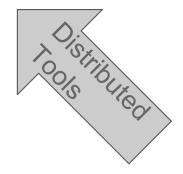


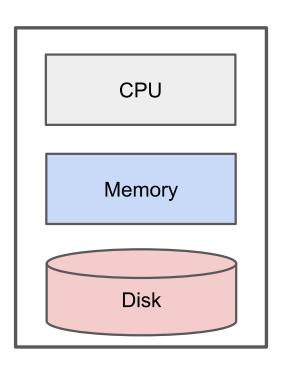


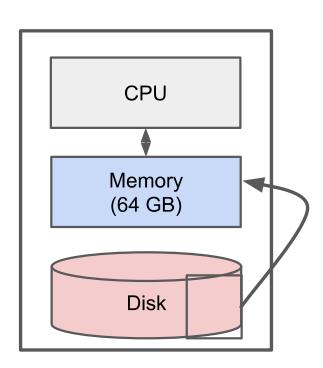


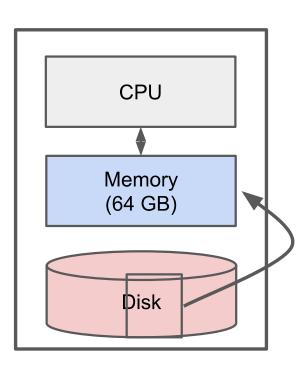
## Big Data Analytics

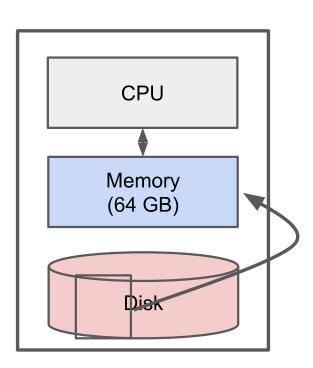








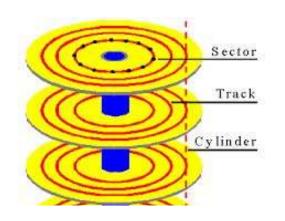




#### **IO** Bounded

Reading a word from disk versus main memory: 10<sup>5</sup> slower!

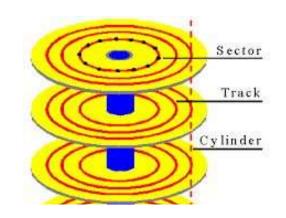
Reading many contiguously stored words is faster per word, but fast modern disks still only reach 150MB/s for sequential reads.



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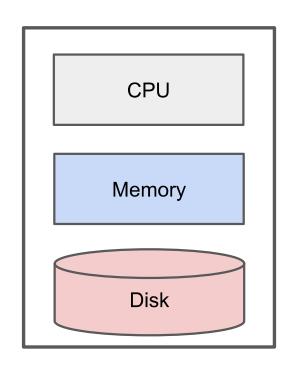
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IO Bound: biggest performance bottleneck is reading / writing to disk.

starts around 100 GBs: ~10 minutes just to read 200 TBs: ~20,000 minutes = 13 days

## Classical Big Data Analysis



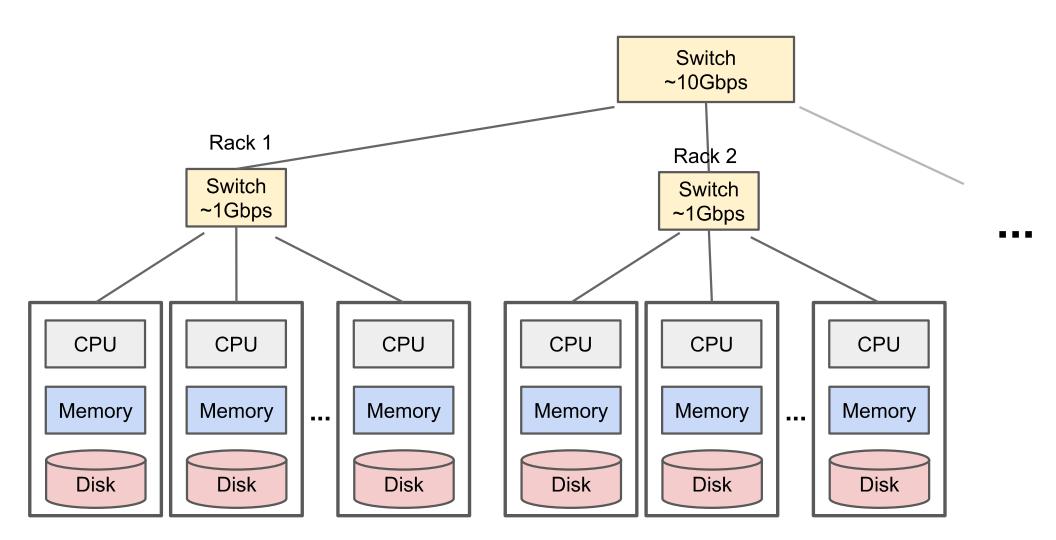
Classical focus: efficient use of disk. e.g. Apache Lucene / Solr

Classical limitation: Still bounded when needing to process all of a large file.

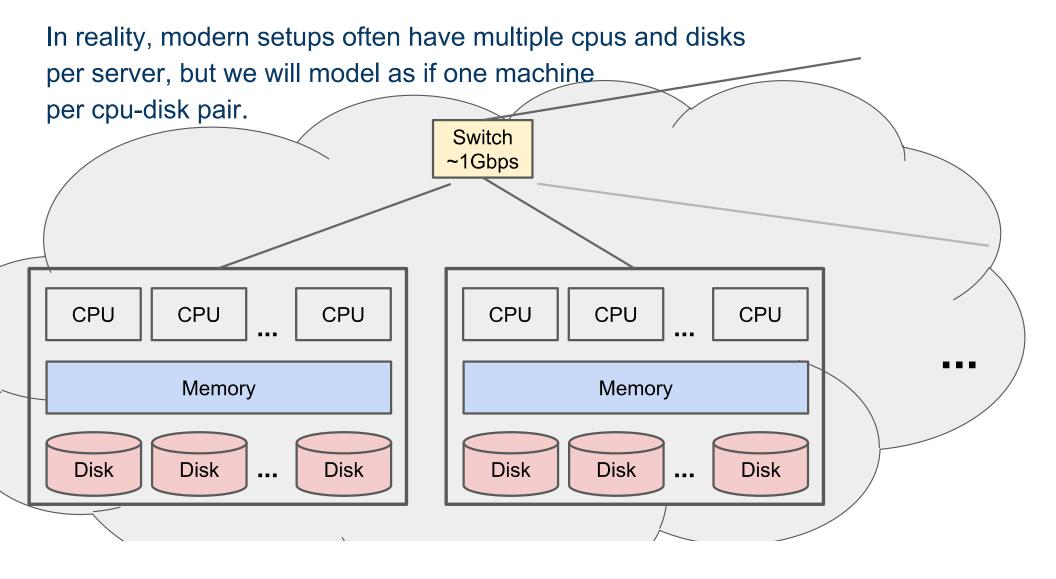
#### **IO** Bound

How to solve?

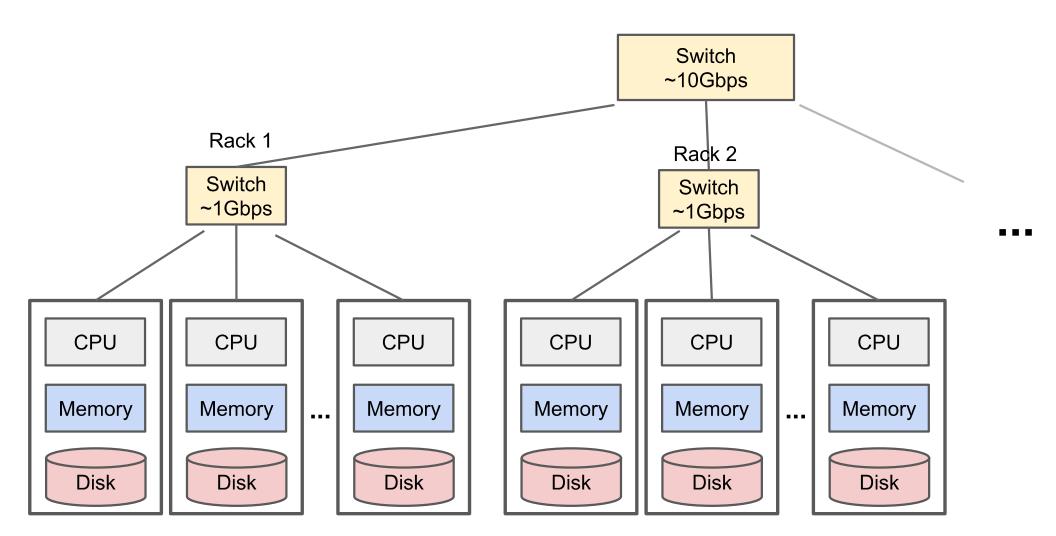
#### Distributed Architecture (Cluster)



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- Nodes fail
   1 in 1000 nodes fail a day
- Network is a bottleneck
   Typically 1-10 Gb/s throughput

3. Traditional distributed programming is often ad-hoc and complicated

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MapReduce Accomplishes

#### Distributed File System

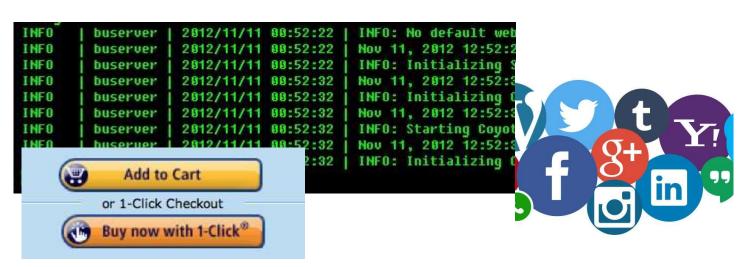
The effectiveness of MapReduce is in part simply due to use of a distributed filesystem!

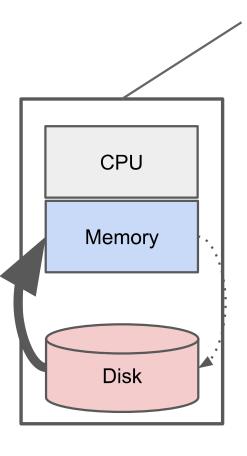
#### Characteristics for Big Data Tasks

Large files (i.e. >100 GB to TBs)

Reads are most common

No need to update in place (append preferred)

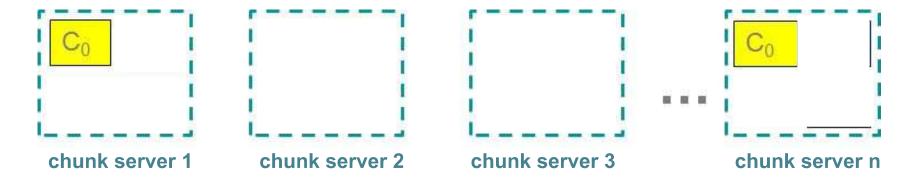


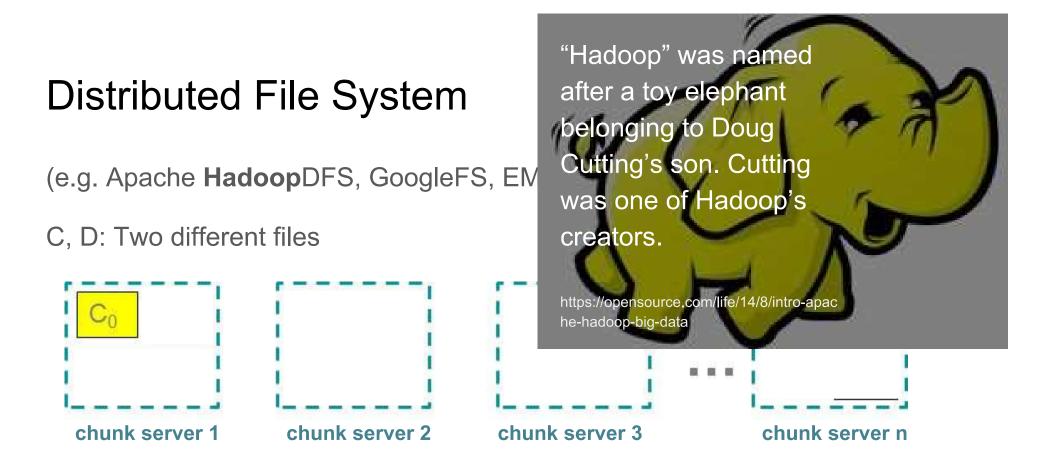


## Distributed File System

(e.g. Apache HadoopDFS, GoogleFS, EMRFS)

C, D: Two different files

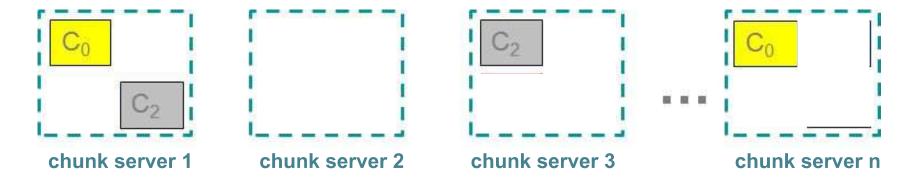




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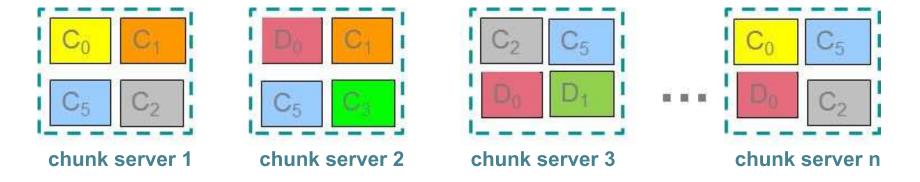
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## Distributed File System

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C, D: Two different files



#### Components of a Distributed File System

#### **Chunk servers (on Data Nodes)**

File is split into contiguous chunks

Typically each chunk is 16-64MB

Each chunk replicated (usually 2x or 3x)

Try to keep replicas in different racks

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#### Name node (aka master node)

Stores metadata about where files are stored

Might be replicated or distributed across data nodes.

#### **Client library for file access**

Talks to master to find chunk servers

Connects directly to chunk servers to access data

Nodes fail
 1 in 1000 nodes fail a day
 Duplicate Data (Distributed FS)



- Network is a bottleneck
   Typically 1-10 Gb/s throughput
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noun.1 - A style of programming

```
input chunks => map tasks | group_by keys | reduce tasks => output "|" is the linux "pipe" symbol: passes stdout from first process to stdin of next. E.g. counting words:
```

tokenize(document) | sort | uniq -c

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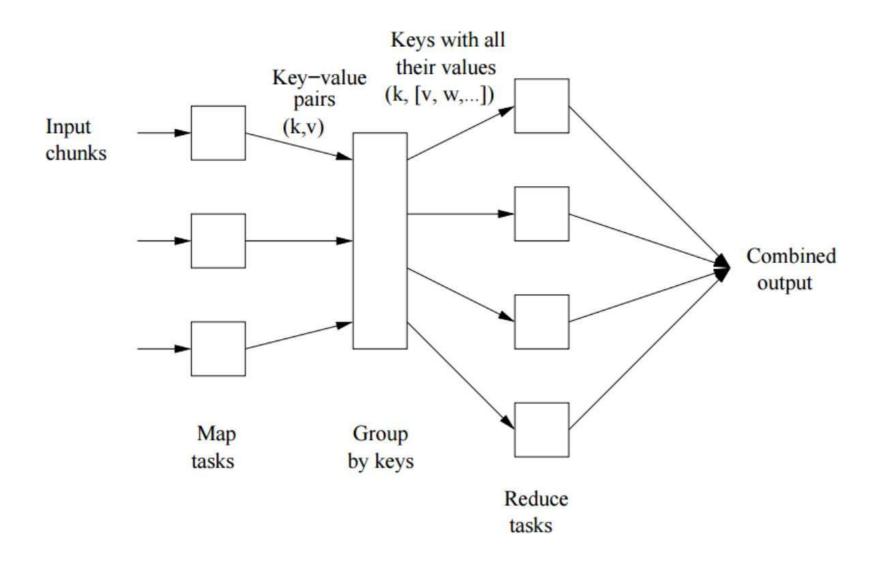
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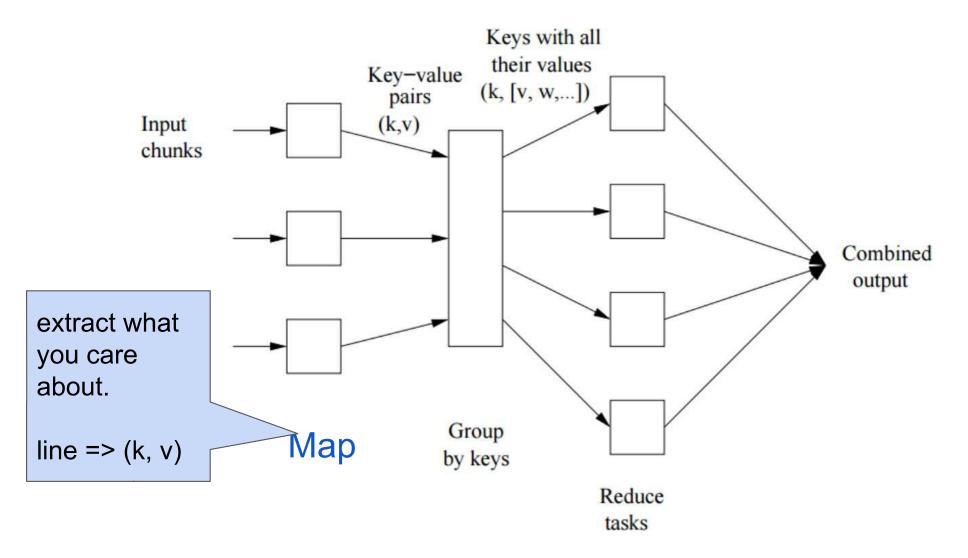
E.g. counting words:

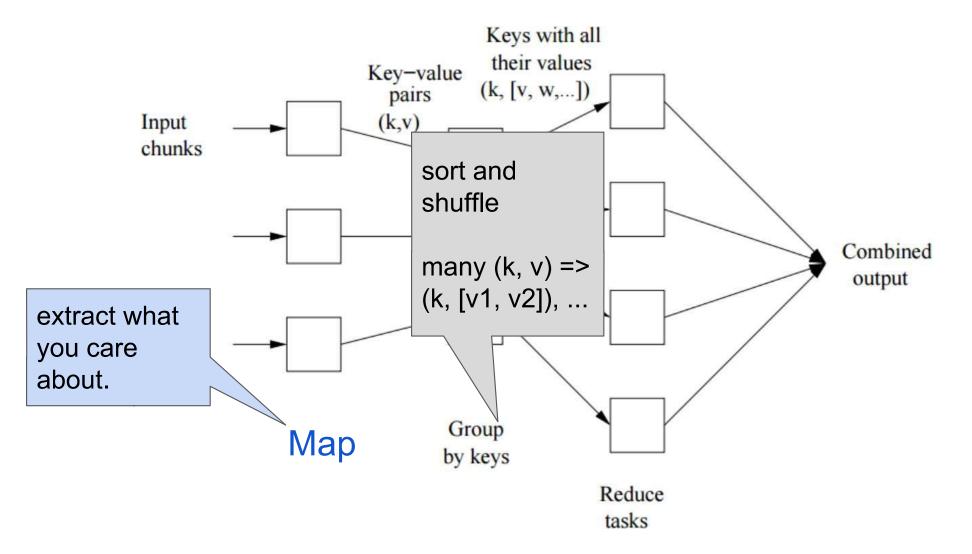
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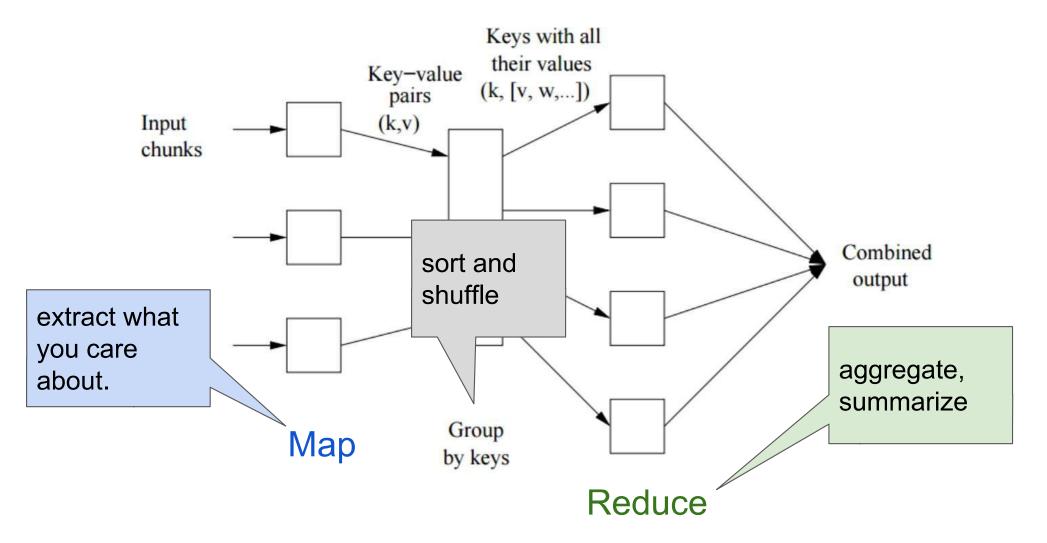
noun.2 - A system that distributes MapReduce style programs across a distributed file-system.

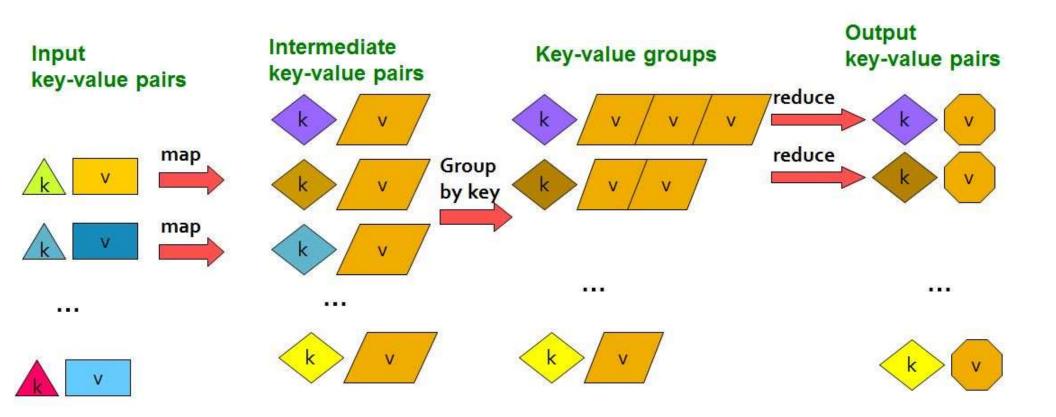
(e.g. Google's internal "MapReduce" or apache.hadoop.mapreduce with hdfs)



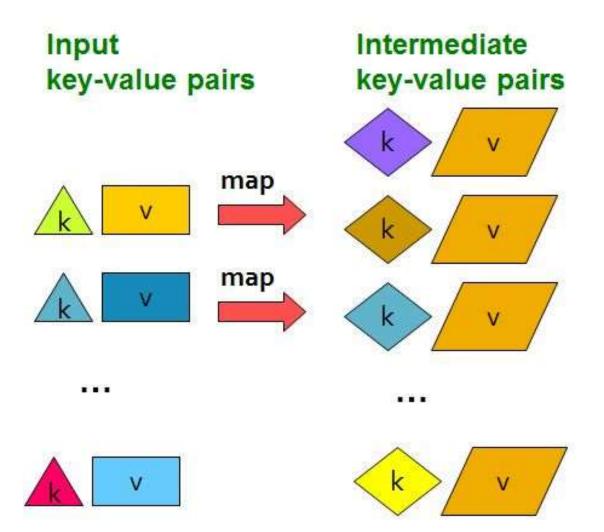




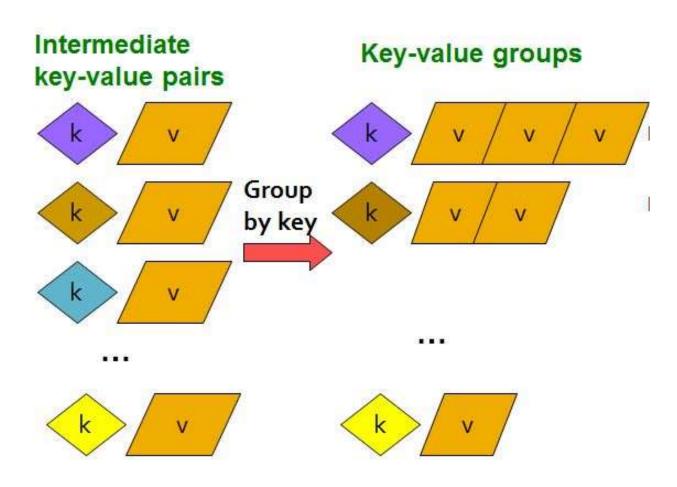




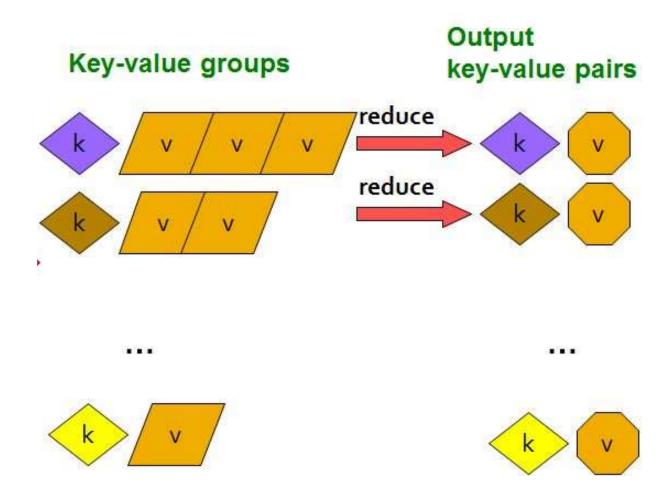
#### The Map Step



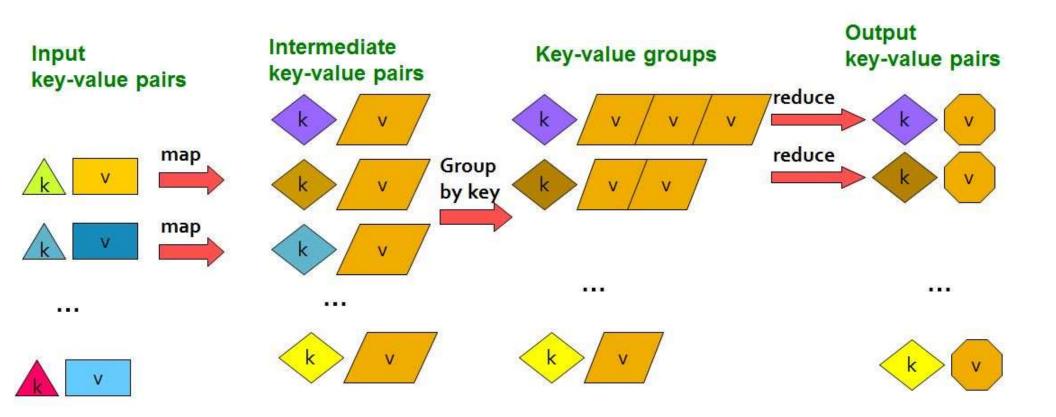
#### The Sort / Group By Step



# The Reduce Step



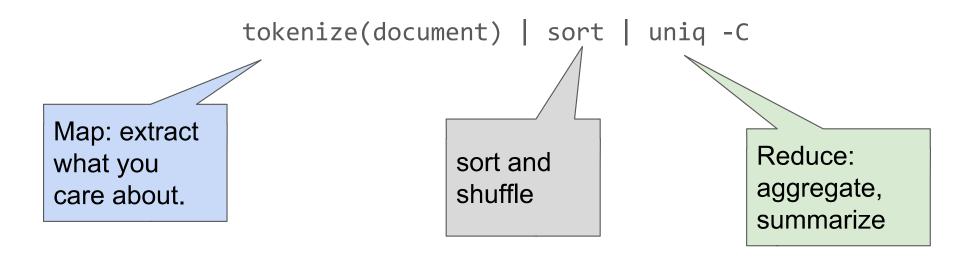
# What is MapReduce?



(Leskovec at al., 2014; http://www.mmds.org/)

# What is MapReduce?

tokenize(document) | sort | uniq -C



The crew of the space shuttle Endeavor recently returned to Earth as ambassadors, harbingers of a new era of space exploration. Scientists at NASA are saying that the recent assembly of the Dextre bot is the first step in a long-term space-based partnership. man/mache "The work we're doing now -- the robotics we're doing -- is what we're going to

**Big document** 

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# Provided by the programmer

#### MAP:

Read input and produces a set of key-value pairs

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(The, 1)
(crew, 1)
(of, 1)
(the, 1)
(space, 1)
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(Endeavor, 1)
(recently, 1)

**Big document** 

(key, value)

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Collect all pairs with same key

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Collect all values belonging to the key and output

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(crew, 1) (crew, 1) (space, 1) (the, 1) (the, 1) (the, 1) (shuttle, 1) (recently, 1)

(key, value)

(crew, 2) (space, 1) (the, 3) (shuttle, 1) (recently, 1)

(key, value)

(The, 1) (crew, 1) (of, 1)(the, 1) (space, 1) (shuttle, 1) (Endeavor, 1) (recently, 1)

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#### Chunks

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#### Big document

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(crew, 1)

(space, 1)

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(key, value)

(crew, 2) (the, 3)

```
@abstractmethod
def map(k, v):
    pass

@abstractmethod
def reduce(k, vs):
    pass
```

# Example: Word Count (version 1)

```
def map(k, v):
    for w in tokenize(v):
        yield (w,1)

def reduce(k, vs):
    return len(vs)
```

# Example: Word Count (version 1)

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def map(k, v):
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        yield (w,1)

def tokenize(s):
        #simple version
        return s.split(' ')
```

```
def reduce(k, vs):
    return len(vs)
```

# Example: Word Count (version 2)

```
def map(k, v):
    counts = dict()
    for w in tokenize(v):
        try:
                                       counts each word within the chunk
            counts[w] += 1
                                       (try/except is faster than
        except KeyError:
                                       "if w in counts")
            counts[w] = 1
    for item in counts.iteritems():
        yield item
def reduce(k, vs):
                                   sum of counts from different chunks
    return sum(vs)
```

# Challenges for IO Cluster Computing

- Nodes fail
   1 in 1000 nodes fail a day
   Duplicate Data (Distributed FS)
- Network is a bottleneck
   Typically 1-10 Gb/s throughput (Sort & Shuffle)
   Bring computation to nodes, rather than data to nodes.
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   Stipulate a programming system that can easily be distributed

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Select

**Project** 

Union, Intersection, Difference

**Natural Join** 

Grouping

Select

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**Natural Join** 

Grouping

#### Select

 $R(A_1, A_2, A_3, ...)$ , Relation R, Attributes  $A_*$ 

return only those attribute tuples where condition C is true

yield (t, t)

#### Select

```
R(A_1, A_2, A_3, ...), Relation R, Attributes A_* return only those attribute tuples where condition C is true def map(k, v): #v is list of attribute tuples for t in v:

if t satisfies C:
```

```
def reduce(k, vs):
   For each v in vs:
      yield (k, v)
```

#### **Natural Join**

Given  $R_1$  and  $R_2$  return  $R_{join}$  -- union of all pairs of tuples that match given attributes.

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```
def map(k, v): #k \in {R1, R2}, v is (R_1 = (A, B), R_2 = (B, C)); B are matched attributes
  if k == "R1":
        (a, b) = v
        yield (b, (R_1, a))
  if k == "R2":
        (b, c) = v
        yield (b, (R_2, c))
```

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attributes
                          def reduce(k, vs):
   if k=="R1":
       (a, b) = v
                               r1, r2 = [], []
       yield (b, (R_1, a))
                               for (S, x) in vs: #separate rs
   if k=="R2":
                                   if S == r1: r1.append(x)
       (b,c) = v
                                   else: r2.append(x)
       yield (b,(R_2,c))
                               for a in r1: #join as tuple
                                   for each c in r2:
                                       yield (R_{ioin}, (a, k, c)) #k is
```

.



#### MAP:

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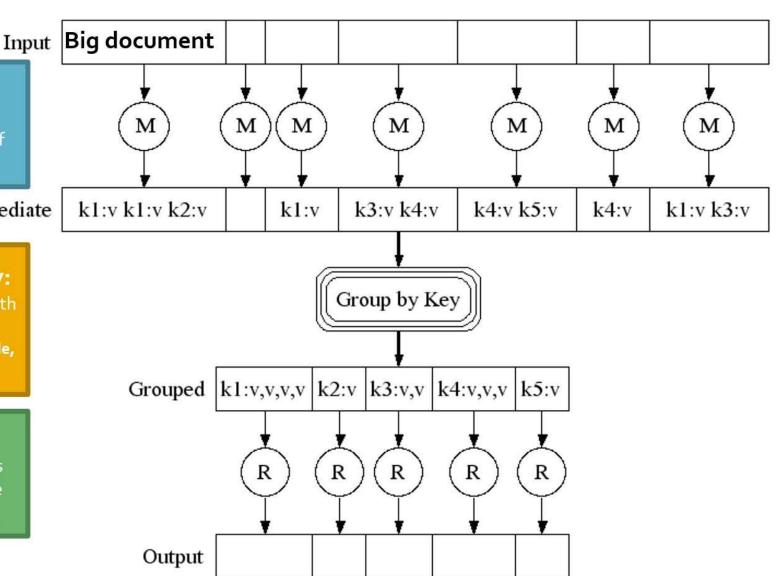
Intermediate

#### Group by key:

same key (Hash merge, Shuffle, Sort, Partition)

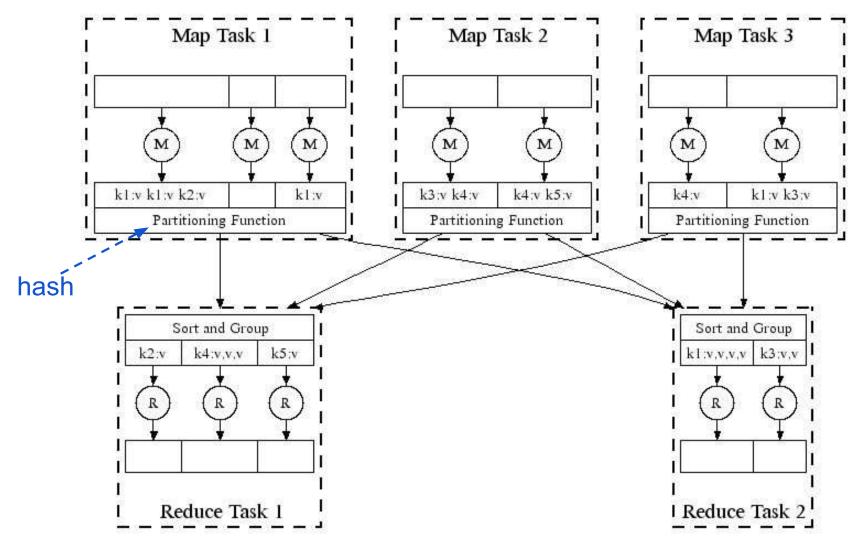
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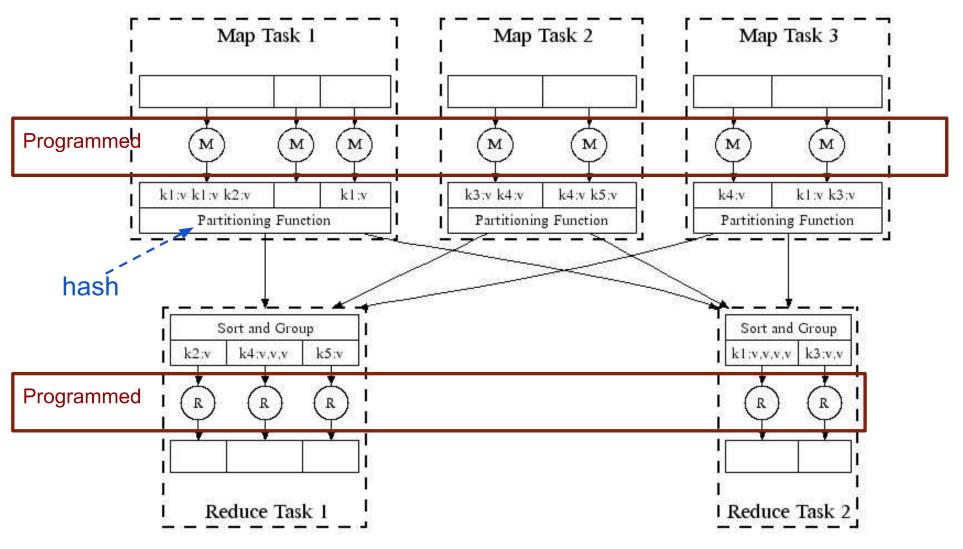
J. Leskovec, A. Rajaraman, J. Ullman: Mining of Massive Datasets, http://www.mmds.org

### Data Flow: In Parallel



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DFS → Map → Map's Local FS → Reduce → DFS

#### MapReduce system handles:

- Partitioning
- Scheduling map / reducer execution
- Group by key
- Restarts from node failures
- Inter-machine communication

DFS MapReduce DFS

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DFS  $\Longrightarrow$  MapReduce  $\Longrightarrow$  DFS  $\Longrightarrow$  MapReduce  $\Longrightarrow$  DFS

Skew: The degree to which certain tasks end up taking much longer than others.

#### Handled with:

- More reducers than reduce tasks
- More reduce tasks than nodes

Key Question: How many Map and Reduce jobs?

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M: map tasks, R: reducer tasks

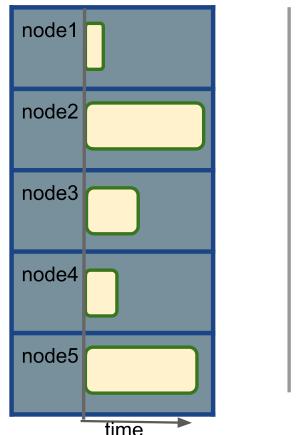
A: If possible, one chunk per map task

and  $M \gg |\text{nodes}| \approx |\text{cores}|$ (better handling of node failures, better load balancing)

R < M

(reduces number of parts stored in DFS)

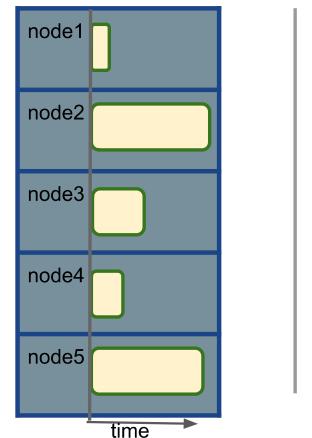
version 1: few reduce tasks (same number of reduce tasks as nodes)



time
Reduce tasks represented by
time to complete task
(some tasks take much longer)

#### Reduce Task

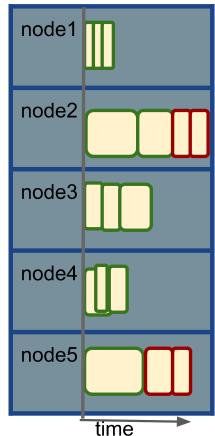
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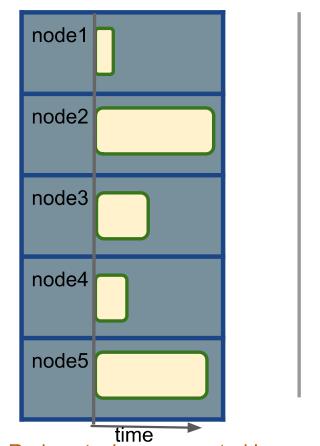


version 2: more reduce tasks (more reduce tasks than nodes)

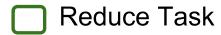


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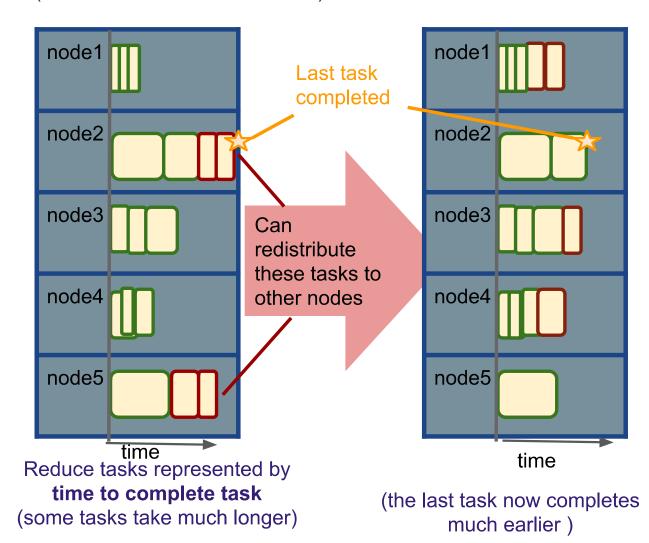
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Reduce tasks represented by time to complete task (some tasks take much longer)



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- (1) Computation: Map + Reduce + System Tasks
- (2) Communication: Moving (key, value) pairs

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Ultimate Goal: wall-clock Time.



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# (1) Computation: Map + Reduce + System Tasks

Mappers and reducers often single pass O(n) within node

System: sort the keys is usually most expensive

 Even if map executes on same node, disk read usually dominates

In any case, can add more nodes

# How to assess performance?

(1) Computation: Map + Reduce + System Tasks

# (2) Communication: Moving key, value pairs

Often dominates computation.

- Connection speeds: 1-10 gigabits per sec;
- HD read: 50-150 gigabytes per sec
  - Even reading from disk to memory typically takes longer than operating on the data.

# How to assess performance?

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Communication Cost = input size + (sum of size of all map-to-reducer files)
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  - Even reading from disk to memory typically takes longer than operating on the data.
  - Output from reducer ignored because it's either small (finished summarizing data) or being passed to another mapreduce job.

# Example: Natural Join

R, S: Relations (Tables)  $R(A, B) \bowtie S(B, C)$ 

Communication Cost = input size + (sum of size of all map-to-reducer files)

DFS \(\sigma\) \(\sigm

# **Example: Natural Join**

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```

```
 \text{def reduce(k, vs):} \\  r1, \ r2 = [], [] \\  \text{def map(k, v):} \\  \text{if k=="R1":} \\  (a, b) = v \\   \text{yield } (b, (R_1, a)) \\  \text{if k=="R2":} \\  (b, c) = v \\   \text{yield } (b, (R_2, c)) \\  \end{array}   \text{for a in r1: #join as tuple} \\  \text{for each } c \text{ in r2:} \\   \text{yield } (R_{join}, (a, k, c)) \text{ #k is}
```

# **Example: Natural Join**

R, S: Relations (Tables)  $R(A, B) \bowtie S(B, C)$ 

```
Communication Cost = input size + (sum of size of all map-to-reducer files)
```

```
= |R1| + |R2| + (|R1| + |R2|)
                           def reduce(k, vs):
= O(|R1| + |R2|)
                               r1, r2 = [], []
def map(k, v):
                               for (rel, x) in vs: #separate rs
    if k=="R1":
                                   if rel == 'R': r1.append(x)
       (a, b) = v
                                   else: r2.append(x)
       yield (b,(R_1,a))
                               for a in r1: #join as tuple
    if k=="R2":
                                   for each c in r2:
       (b,c) = v
                                      yield (R_{ioin}, (a, k, c)) #k is
       yield (b,(R_2,c))
```

**Exercise:** 

Calculate Communication Cost for "Matrix Multiplication with One MapReduce Step" (see MMDS section 2.3.10)

# Last Notes: Further Considerations for MapReduce

- Performance Refinements:
  - Backup tasks (aka speculative tasks)
    - Schedule multiple copies of tasks when close to the end to mitigate certain nodes running slow.
  - Combiners (like word count version 2 but done via reduce)
    - Run reduce right after map from same node before passing to reduce
    - Reduces communication cost
  - Override partition hash function

E.g. instead of hash(url) use hash(hostname(url))