

MIC-GPU: High-Performance Computing for Medical Imaging on Programmable Graphics Hardware (GPUs)

CUDA Programming Environment

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Setup CUDA

Compute Unified Device Architecture

- Check hardware compatibility: http://www.nvidia.com/object/cuda_gpus.html
- Driver, Toolkit (4.0) and SDK http://www.nvidia.com/object/cuda_get.html
- Toolkit includes:
 - Compiler
 - Development tools
 - Libraries for scientific computation (CUBLAS, CUFFT, CUSPARSE, CURAND, etc.)
 - User guides and documents

Compilation and Linking

Any source file containing CUDA language extensions must be compiled with NVCC

NVCC is a compiler

- Compile device code
- Invoking the necessary compilers for host code like, g++, cl, ...

Any executable with CUDA code requires dynamic libraries:

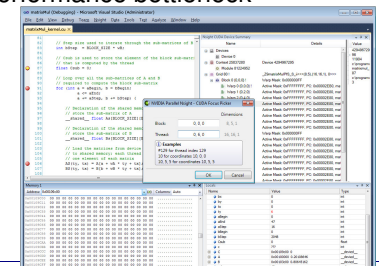
- The CUDA runtime library (**cuda**) OR
- The CUDA core library (**cuda**)

Development Tools

Parallel Nsight (Windows)

- Visual Studio Based GPU Development Environment
<http://developer.nvidia.com/object/nsight.html>
- Debug CUDA C/C++ source code directly on the GPU
- Use the familiar Visual Studio Locals, Watches, Memory and Breakpoints windows
- Integrated analysis tool to isolate performance bottleneck

CUDA-GDB debugger
for Linux and MacOS



Visual Profiler

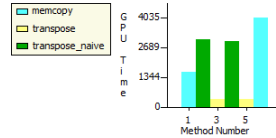
Method	GPU Time	CPU Time	Occupancy	grid size X	grid size Y	block size X	block size Y	block size Z	static shared memory per block	registers per thread	mem transfer size (bytes)	ran	gld coalesced	gdt uncoalesced	gdt coalesced	branch	instructions
1. memcpy	1573.92	4390.85									4194304						
2. transpose_naive	3041.92	3062.27	1	256	16	16	16	16	32	6		8192	262144	0	2048	32591	
3. transpose_naive	341.92	364.64	1	256	16	16	16	16	1120	8		8192	0	32768	10240	42873	
4. transpose_naive	2945.89	2959.24	1	256	16	16	16	16	32	6		8192	262144	0	2048	32479	
5. transpose	343.808	356.759	1	256	16	16	16	16	1120	8		8192	0	32768	10240	43116	
6. memcpy	4094.91	4880.18									4194304	1					

A graphical profiling tool to measure and benchmark performance

tracks events with hardware counters on signals in the chip

Fine Tuning Performance by watching the following metric

- Coalescing
- Occupancy
- Branch diversity
- Instruction throughput
- Computing / Data transfer ratio
- Share memory and register per thread



CUDA Libraries

CUBLAS (BLAS = Basic Linear Algebra Subprograms)

level1 (scalar, vector, vector-vector)

level2 (matrix-vector) , level3 (matrix-matrix)

```
void cublasSsymv(char uplo, int n, float alpha, const float *A, int lda, const float *x, int incx, float beta, float *y, int incy)
```

performs the matrix-vector operation where alpha and beta are single-precision scalars, and x and y are n-element single-precision vectors. A is a symmetric n*n matrix that consists of single-precision elements and is stored in either upper or lower storage mode

CUBLAS Example

Compute a vector's L2 norm

$$|x| := \sqrt{x_1^2 + \dots + x_n^2}$$

- Single precision
- Double precision

```
float cublasSnrm2 (int n, const float *x, int incx)
```

```
double cublasDnrm2 (int n, const double *x, int incx)
```

```
cublasInit();
float *h_A;
h_A = (float*)malloc(n * sizeof(h_A[0]));
...
cublasAlloc(n, sizeof(d_A[0]), (void**)&d_A);
cublasSetVector(n, sizeof(h_A[0]), h_A, 1, d_A, 1);
float norm2result=cublasSnrm2 (n, d_A, 1);
cublasFree (d_A); free (h_A);
cublasShutdown();
```

initialize library

initialize vector

data transfer

compute norm

Wrap-up

CUDA Libraries (3rd party)

MAGMA (porting from LAPACK to GPU+multicore architectures)

CULA (3rd party implementation of LAPACK)

PyCUDA (CUDA via Python)

Thrust (C++ template for CUDA, open source)

Jasper for DWT (Discrete wavelet transform)

OpenViDIA for computer vision

CUDPP for radix sort

Thrust: Introduction

Offers

- STL compatible containers (vector, list, map)
- ~50 algorithm (reduction, prefix sum, sorting)
- Rapid prototyping

Container

- Hides cudaMalloc & cudaMemcpy
- Iterators behave like pointer

Thrust Example: Sorting

```

thrust::host_vector<int> h_vec(16*1024*1024);
thrust::generate(h_vec.begin(), h_vec.end(), rand);
thrust::device_vector<int> d_vec = h_vec;
thrust::sort(d_vec.begin(), d_vec.end());
thrust::copy(d_vec.begin(), d_vec.end(), h_vec.begin());

```

Annotations:

- generate 16M random numbers on the host
- transfer data to the device
- sort data on the device
- transfer data back to host

Thrust: Operators

```

thrust::device_vector<int> i_vec = ...
thrust::device_vector<float> f_vec = ...

thrust::reduce(i_vec.begin(), i_vec.end(), 0, thrust::plus<int>());
thrust::reduce(f_vec.begin(), f_vec.end(), 0.0f, thrust::plus<float>());
thrust::reduce(i_vec.begin(), i_vec.end(), 0, thrust::maximum<int>());

```

Annotations:

- declare storage
- sum of integers (equivalent calls)
- sum of floats (equivalent calls)
- maximum of integers

Thrust Example: Vector L2 Norm

More like C++

$$\|x\| := \sqrt{x_1^2 + \dots + x_n^2}$$

```

template <typename T> struct square
{
  __host__ __device__
  T operator()(const T& x) const {
    return x * x;
  }
};

square<float> unary_op;
plus<float> binary_op;
float init = 0;

device_vector<float> A(3);
A[0] = 20; A[1] = 30; A[2] = 40;
float norm = sqrt(transform_reduce(A.begin(), A.end(), unary_op, init, binary_op));

```

Annotations:

- define transformation f(x) -> x^2
- setup arguments
- initialize vector
- compute norm

NVIDIA CUDA Zone:

- http://www.nvidia.com/object/cuda_home.html
- Lots of information and code examples
- NVIDIA CUDA Programming Guide

GPGPU community:

- <http://www.gpgpu.org>
- User forums, tutorials, papers
- Good source: conference tutorials
<http://www.gpgpu.org/developer/index.shtml#conference-tutorial>

- 1:30 – 1:45: Introduction
- 1:45 – 2:00: Parallel programming primer
- 2:00 – 2:15: GPU hardware
- 2:15 – 3:00: CUDA API, threads level optimization
Coffee Break
- 3:30 – 4:00: CUDA memory optimization
- 4:00 – 4:15: CUDA programming environment
- 4:15 – 4:45: Parallelism in medical image (Klaus)
- 4:45 – 5:25: CT reconstruction examples (Eric + Ziyi)
- 5:25 – 5:30: Closing remarks (Klaus)