

CSE 638: Advanced Algorithms

Lectures 2, 3 & 4

(Analytical Modeling of Parallel Algorithms)

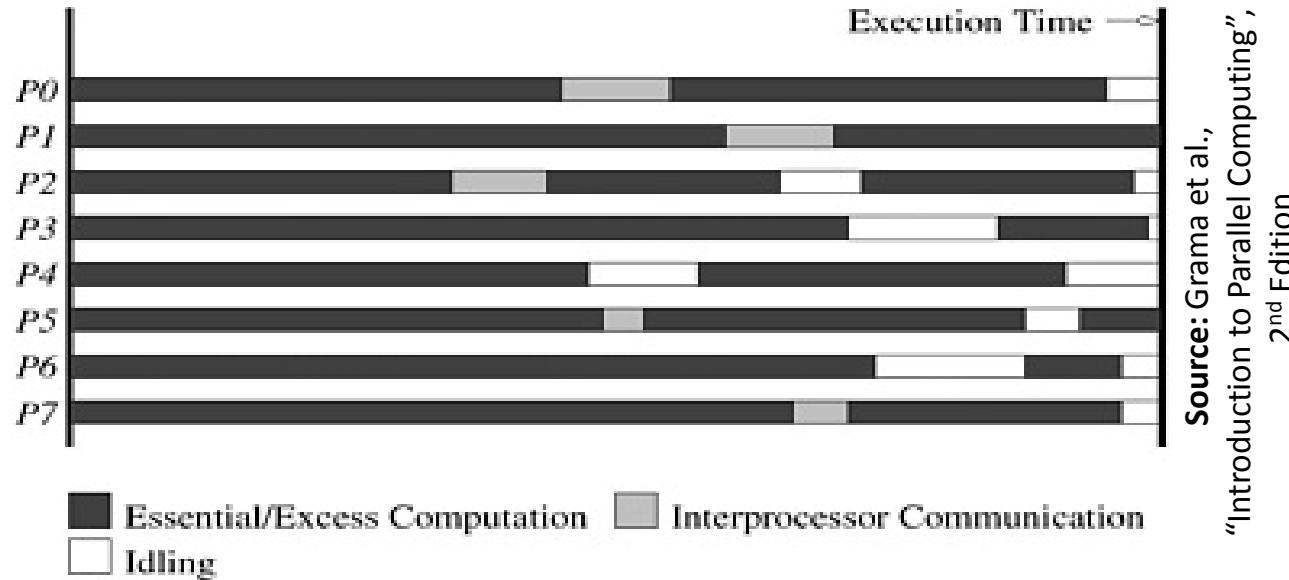
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Spring 2013

Parallel Execution Time & Overhead



Source: Grama et al.,
"Introduction to Parallel Computing",
2nd Edition

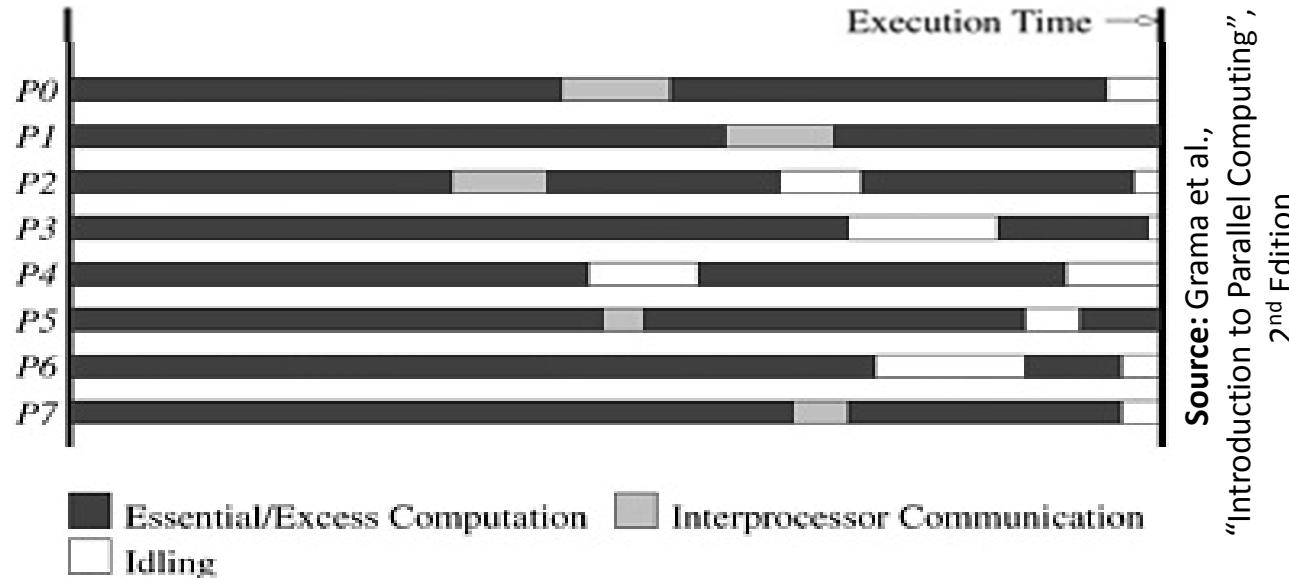
Parallel running time on p processing elements,

$$T_P = t_{end} - t_{start},$$

where, t_{start} = starting time of the processing element
that starts first

t_{end} = termination time of the processing element
that finishes last

Parallel Execution Time & Overhead

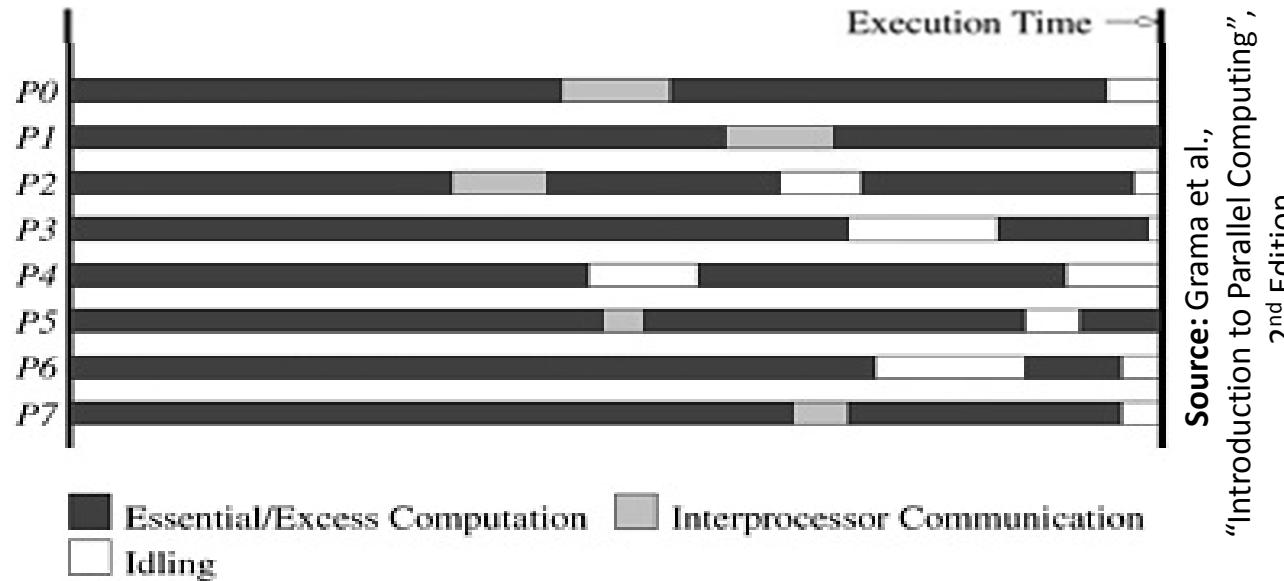


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Sources of overhead (w.r.t. serial execution)

- Interprocess interaction
 - Interact and communicate data (e.g., intermediate results)
- Idling
 - Due to load imbalance, synchronization, presence of serial computation, etc.
- Excess computation
 - Fastest serial algorithm may be difficult/impossible to parallelize

Parallel Execution Time & Overhead



Source: Grama et al.,
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Overhead function or total parallel overhead,

$$T_o = pT_p - T,$$

where, p = number of processing elements

T = time spent doing useful work

(often execution time of the fastest serial algorithm)

Speedup

Let T_p = running time using p identical processing elements

$$\text{Speedup, } S_p = \frac{T_1}{T_p}$$

Theoretically, $S_p \leq p$ (why?)

Perfect or linear or ideal speedup if $S_p = p$

Speedup

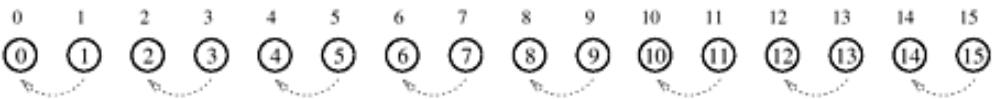
Consider adding n numbers using n identical processing elements.

Serial runtime, $T_1 = \Theta(n)$

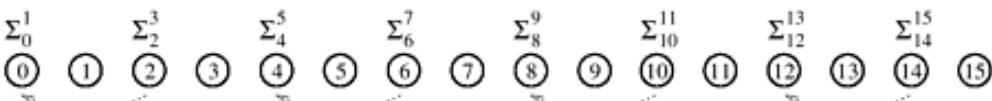
Parallel runtime, $T_n = \Theta(\log n)$

$$\text{Speedup, } S_n = \frac{T_1}{T_n} = \Theta\left(\frac{n}{\log n}\right)$$

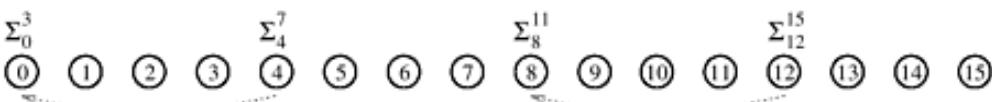
Speedup not ideal.



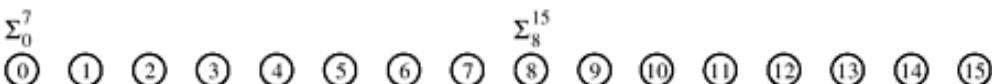
(a) Initial data distribution and the first communication step



(b) Second communication step



(c) Third communication step



(d) Fourth communication step



(e) Accumulation of the sum at processing element 0 after the final communication

Superlinear Speedup

Theoretically, $S_p \leq p$

But in practice *superlinear speedup* is sometimes observed,
that is, $S_p > p$ (why?)

Reasons for superlinear speedup

- Cache effects
- Exploratory decomposition

Superlinear Speedup (Cache Effects)

Let cache access latency = 2 ns

DRAM access latency = 100 ns

Suppose we want solve a problem instance that executes k FLOPs.

With 1 Core: Suppose cache hit rate is 80%.

If the computation performs 1 FLOP/memory access, then each FLOP will take $2 \times 0.8 + 100 \times 0.2 = 21.6$ ns to execute.

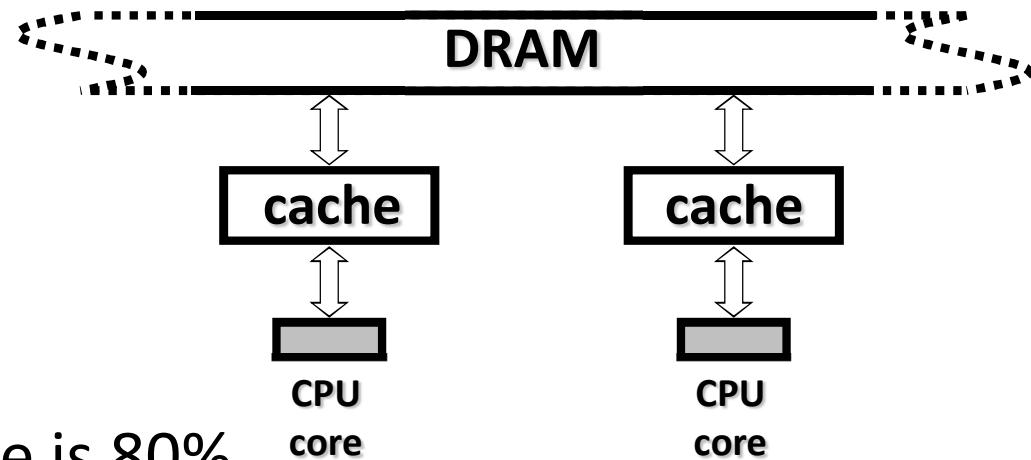
With 2 Cores: Cache hit rate will improve. (why?)

Suppose cache hit rate is now 90%.

Then each FLOP will take $2 \times 0.9 + 100 \times 0.1 = 11.8$ ns to execute.

Since now each core will execute only $k / 2$ FLOPs,

$$\text{Speedup, } S_2 = \frac{k \times 21.6}{(k/2) \times 11.8} \approx 3.66 > 2!$$



Superlinear Speedup (Due to Exploratory Decomposition)

Consider searching an array of $2n$ unordered elements for a specific element x .

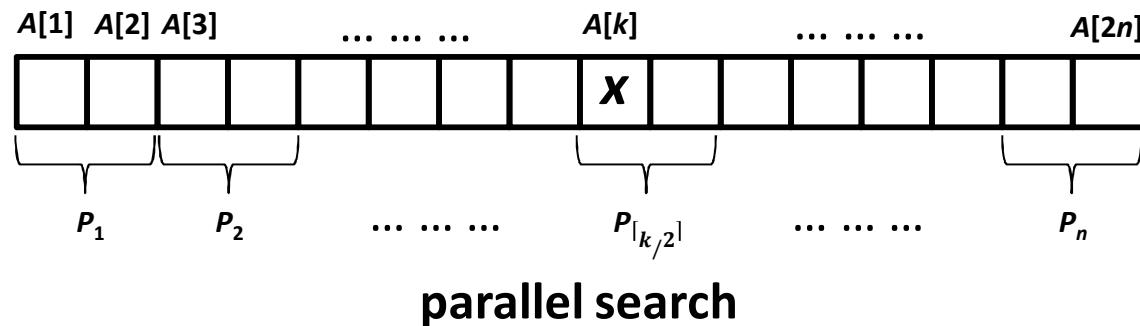
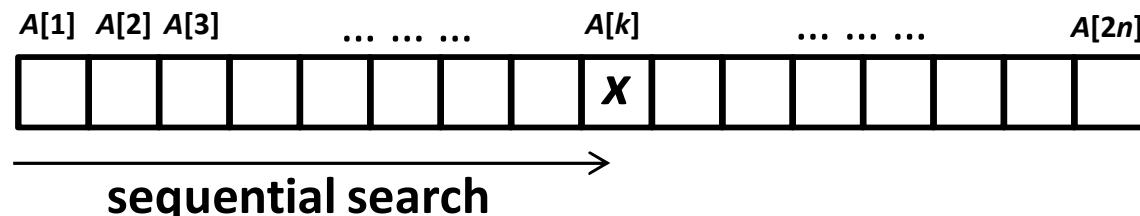
Suppose x is located at array location $k > n$ and k is odd.

Serial runtime, $T_1 = k$

Parallel running time with n processing elements, $T_n = 1$

Speedup, $S_n = \frac{T_1}{T_n} = k > n$

Speedup is superlinear!



Parallelism & Span Law

We defined, T_p = runtime on p identical processing elements

Then span, T_∞ = runtime on an infinite number of identical processing elements

Parallelism, $P = \frac{T_1}{T_\infty}$

Parallelism is an upper bound on speedup, i.e., $S_p \leq P$ (why?)

Span Law

$$T_p \geq T_\infty$$

Work Law

The cost of solving (or work performed for solving) a problem:

On a Serial Computer: is given by T_1

On a Parallel Computer: is given by pT_p

Work Law

$$T_p \geq \frac{T_1}{p}$$

Work Optimality

Let T_s = runtime of the optimal or the fastest known serial algorithm

A parallel algorithm is *cost-optimal* or *work-optimal* provided

$$pT_p = \Theta(T_s)$$

Our algorithm for adding n numbers using n identical processing elements is clearly not work optimal.

Adding n Numbers Work-Optimality

We reduce the number of processing elements which in turn increases the granularity of the subproblem assigned to each processing element.

Suppose we use p processing elements.

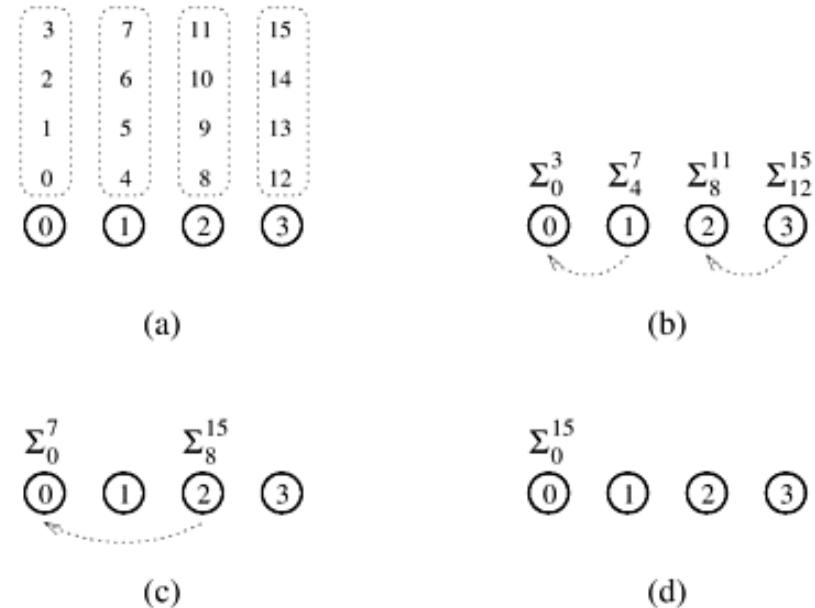
First each processing element locally

adds its $\frac{n}{p}$ numbers in time $\Theta\left(\frac{n}{p}\right)$.

Then p processing elements adds these p partial sums in time $\Theta(\log p)$.

Thus $T_p = \Theta\left(\frac{n}{p} + \log p\right)$, and $T_s = \Theta(n)$.

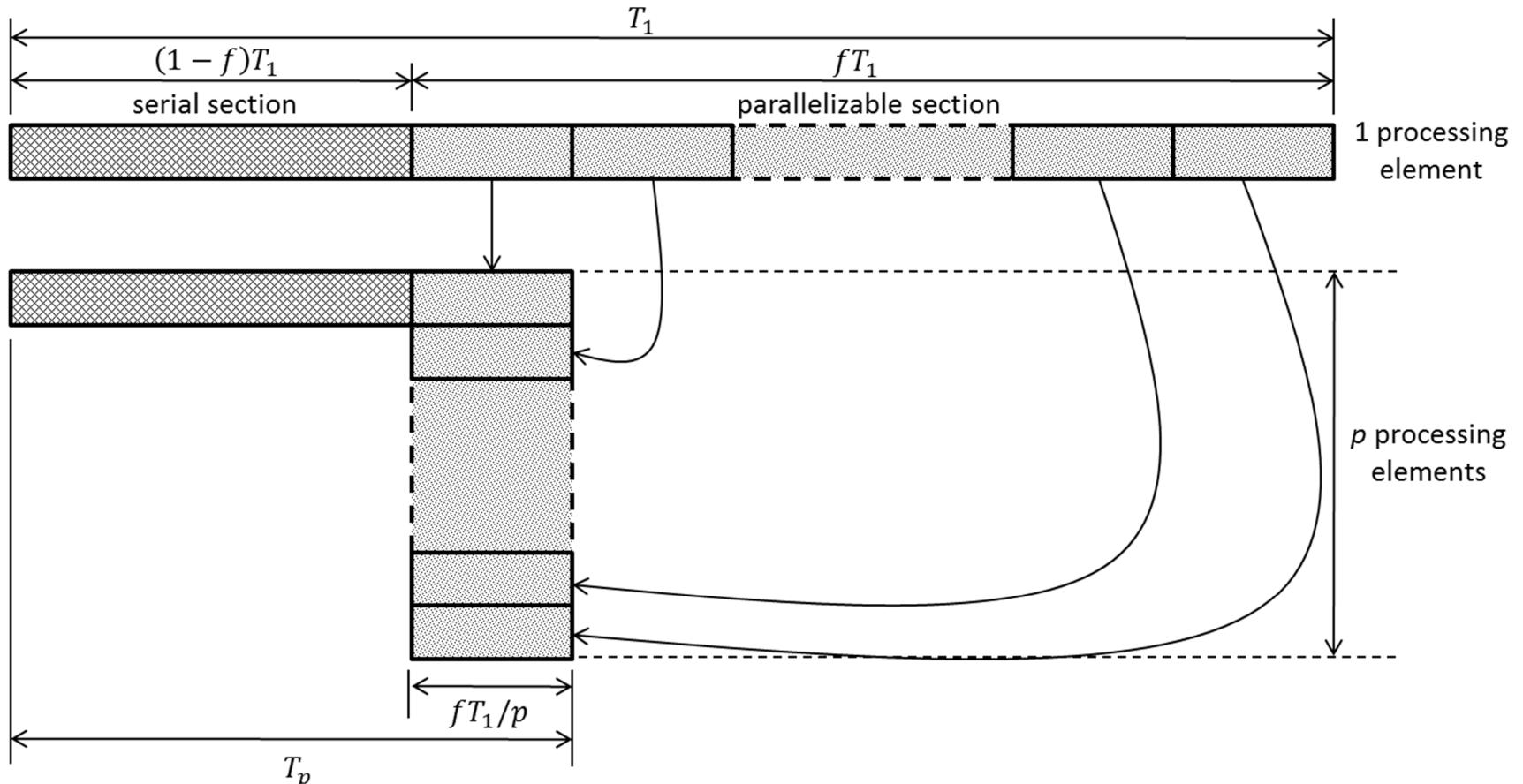
So the algorithm is work-optimal provided $n = \Omega(p \log p)$.



Source: Grama et al.,
“Introduction to Parallel Computing”, 2nd Edition

Scaling Laws

Scaling of Parallel Algorithms (Amdahl's Law)



Suppose only a fraction f of a computation can be parallelized.

Then parallel running time, $T_p \geq (1 - f)T_1 + f \frac{T_1}{p}$

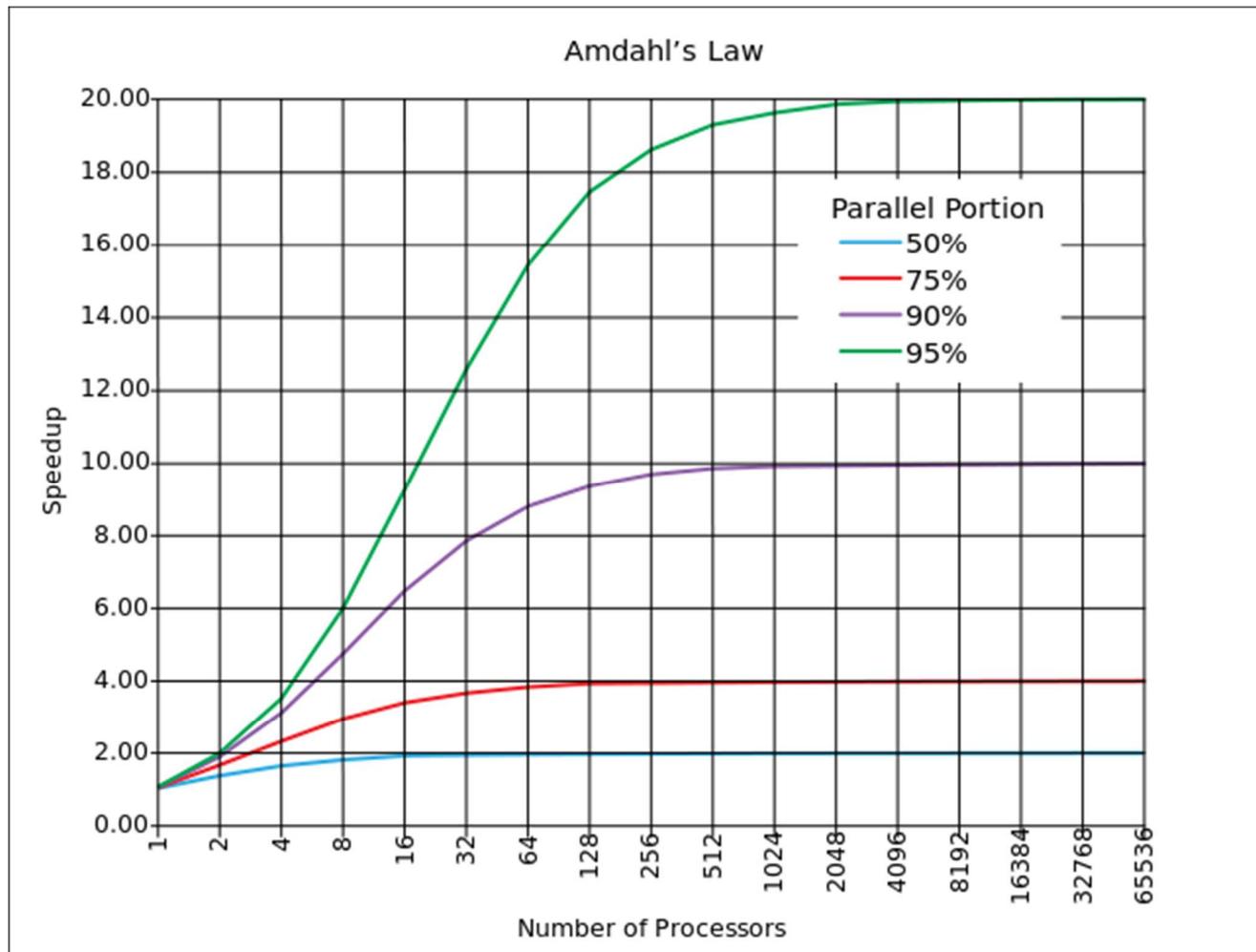
$$\text{Speedup, } S_p = \frac{T_1}{T_p} \leq \frac{p}{f+(1-f)p} = \frac{1}{(1-f)+\frac{f}{p}} \leq \frac{1}{1-f}$$

Scaling of Parallel Algorithms

(Amdahl's Law)

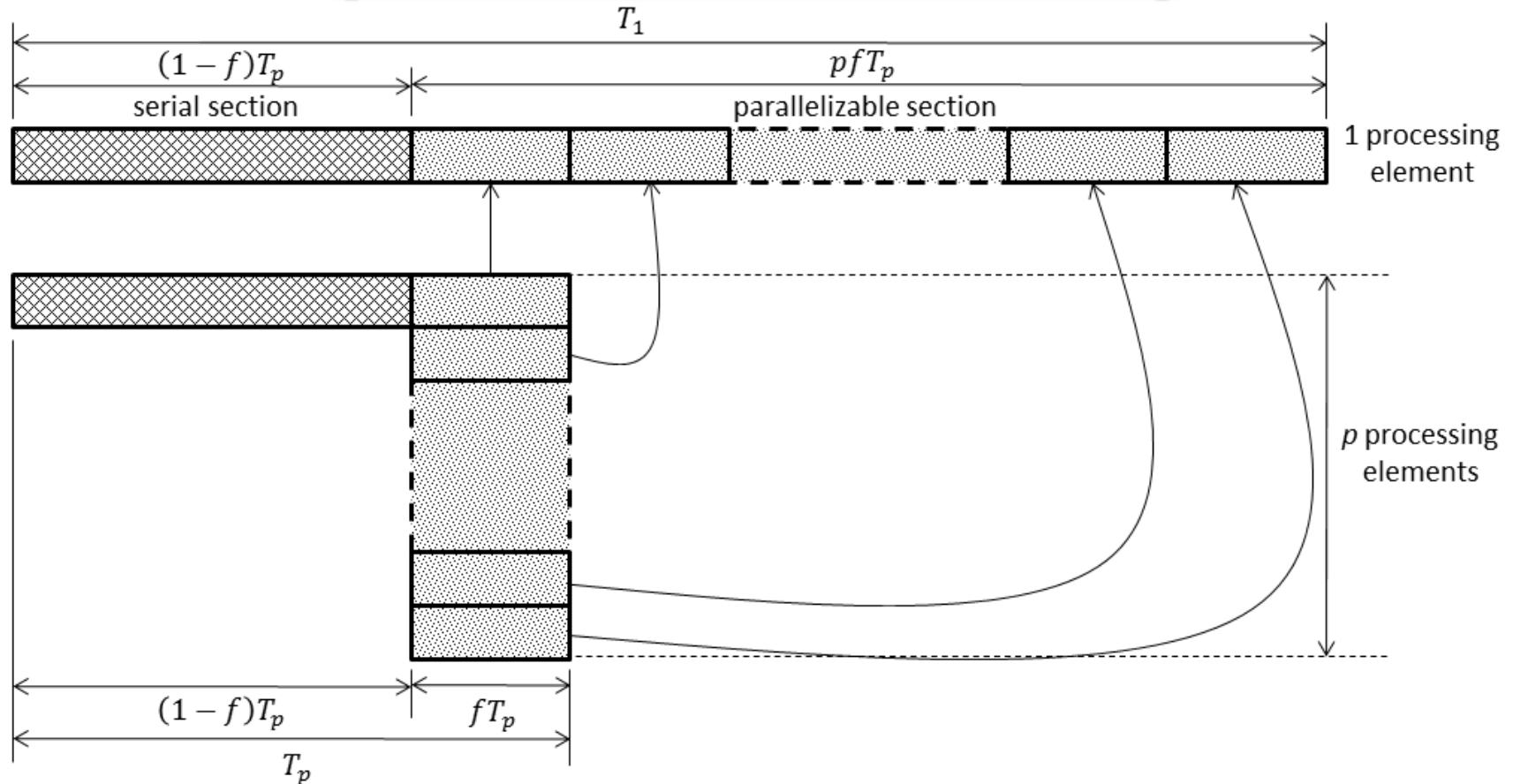
Suppose only a fraction f of a computation can be parallelized.

$$\text{Speedup, } S_p = \frac{T_1}{T_p} \leq \frac{1}{(1-f)+\frac{f}{p}} \leq \frac{1}{1-f}$$



Source: Wikipedia

Scaling of Parallel Algorithms (Gustafson-Barsis' Law)



Suppose only a fraction f of a computation was parallelized.

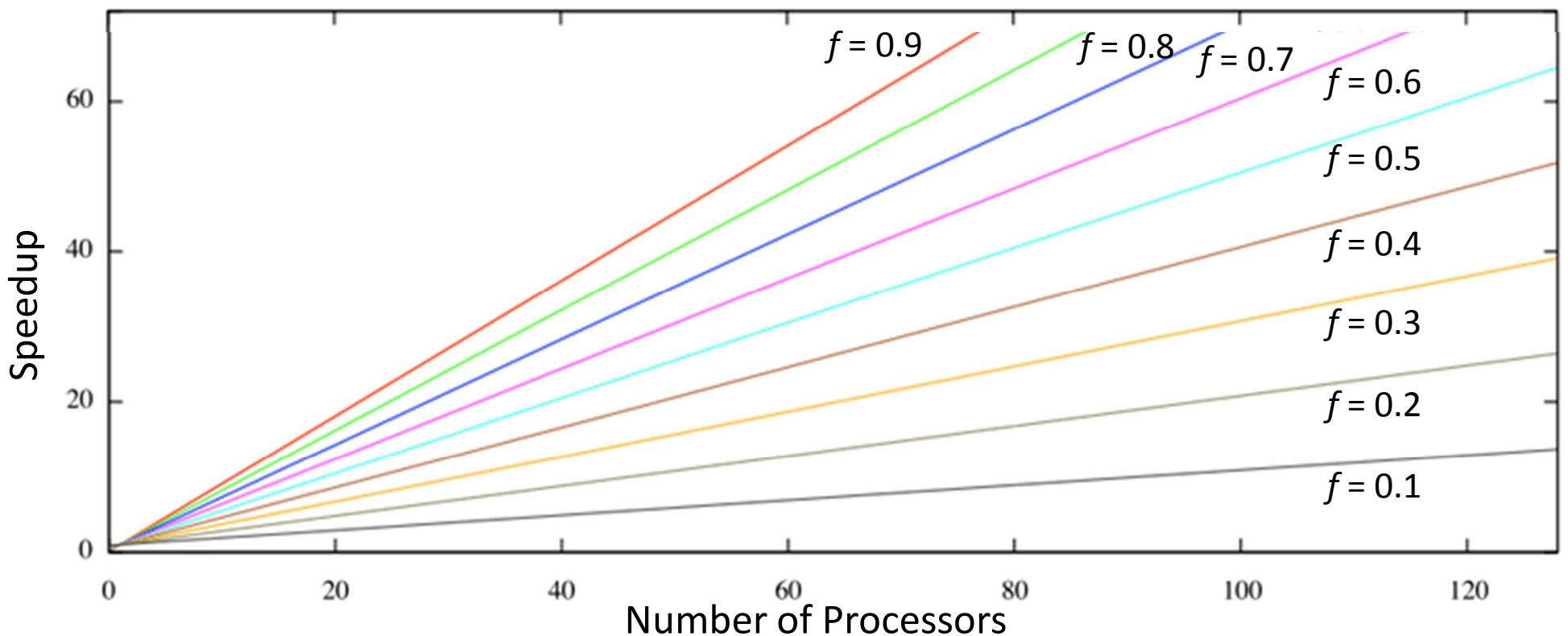
Then serial running time, $T_1 = (1 - f)T_p + p f T_p$

$$\text{Speedup, } S_p = \frac{T_1}{T_p} = \frac{(1-f)T_p + pfT_p}{T_p} = 1 + (p - 1)f$$

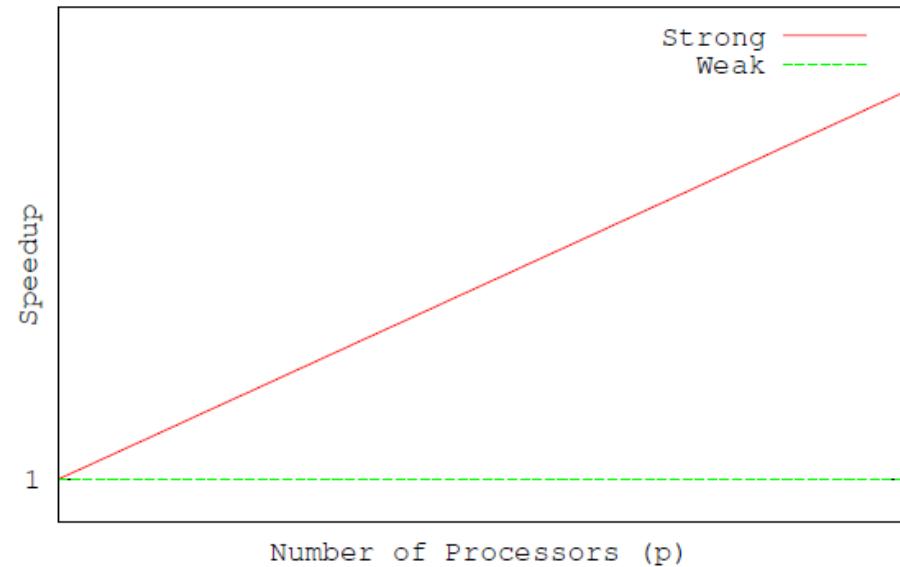
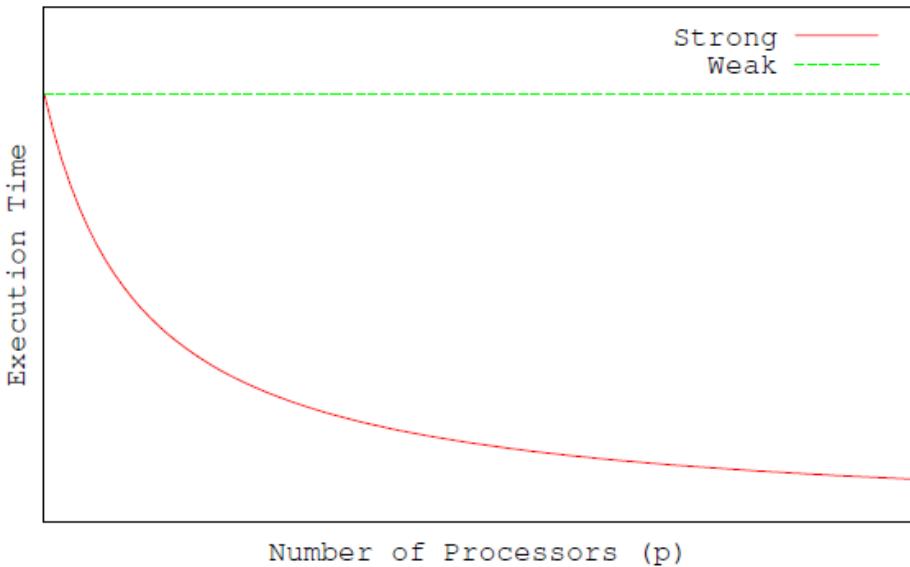
Scaling of Parallel Algorithms (Gustafson-Barsis' Law)

Suppose only a fraction f of a computation was parallelized.

$$\text{Speedup, } S_p = \frac{T}{T_p} \leq \frac{T_1}{T_p} = \frac{(1-f)T_p + pfT_p}{T_p} = 1 + (p - 1)f$$



Strong Scaling vs. Weak Scaling



Strong Scaling

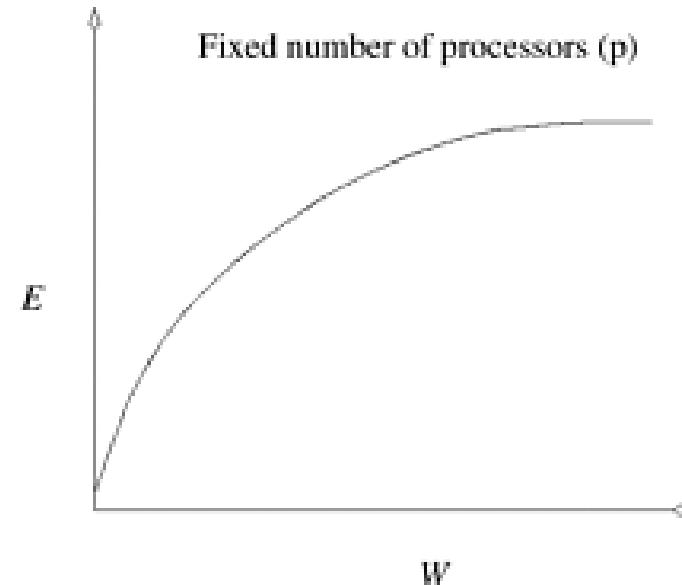
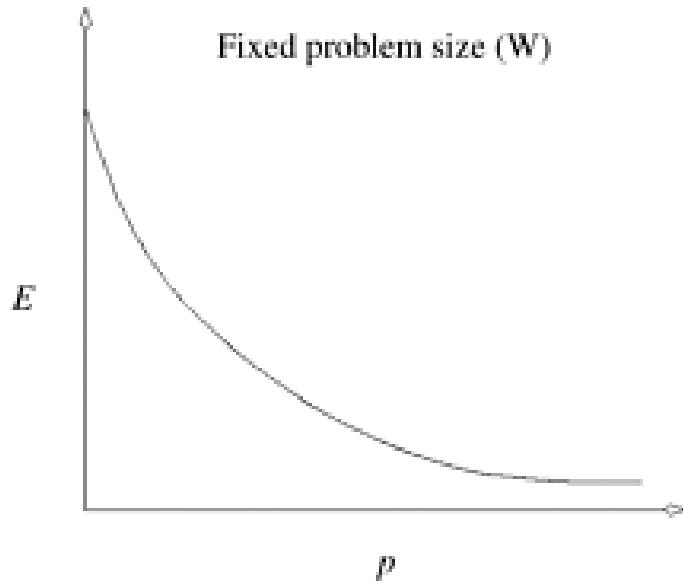
How T_p (or S_p) varies with p when the problem size is fixed.

Weak Scaling

How T_p (or S_p) varies with p when the problem size per processing element is fixed.

Scalable Parallel Algorithms

$$\text{Efficiency, } E_p = \frac{S_p}{p} = \frac{T_1}{pT_p}$$



Source: Grama et al.,
“Introduction to Parallel Computing”,
2nd Edition

A parallel algorithm is called *scalable* if its efficiency can be maintained at a fixed value by simultaneously increasing the number of processing elements and the problem size.

Scalability reflects a parallel algorithm's ability to utilize increasing processing elements effectively.

Scalable Parallel Algorithms

In order to keep E_p fixed at a constant k , we need

$$E_p = k \Rightarrow \frac{T_1}{pT_p} = k \Rightarrow T_1 = kpT_p$$

For the algorithm that adds n numbers using p processing elements:

$$T_1 = n \text{ and } T_p = \frac{n}{p} + 2 \log p$$

So in order to keep E_p fixed at k , we must have:

$$n = kp \left(\frac{n}{p} + 2 \log p \right) \Rightarrow n = \frac{2k}{1 - k} p \log p$$

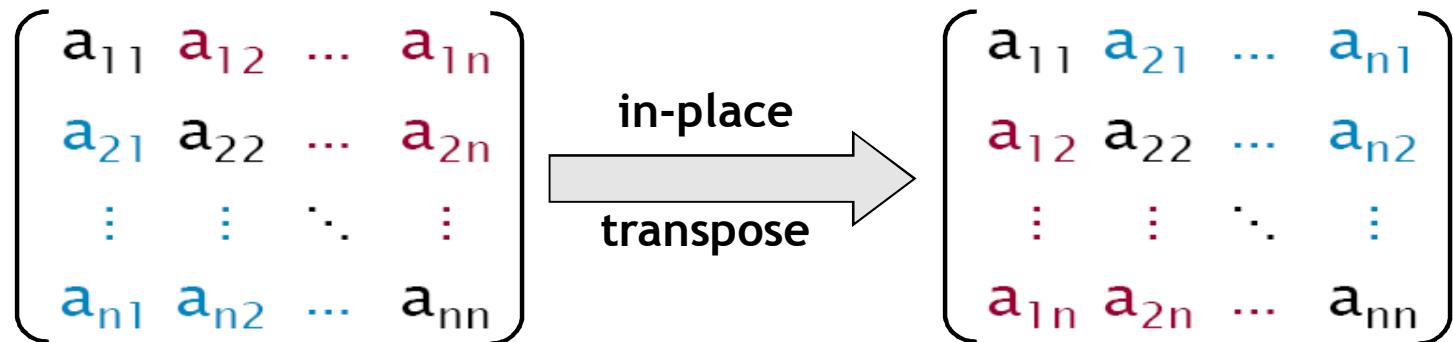
<i>n</i>	<i>p = 1</i>	<i>p = 4</i>	<i>p = 8</i>	<i>p = 16</i>	<i>p = 32</i>
64	1.0	0.80	0.57	0.33	0.17
192	1.0	0.92	0.80	0.60	0.38
320	1.0	0.95	0.87	0.71	0.50
512	1.0	0.97	0.91	0.80	0.62

Fig: Efficiency for adding n numbers using p processing elements

Source: Grama et al., "Introduction to Parallel Computing", 2nd Edition

Greedy Scheduling Theorem

Loop Parallelism (Data Parallelism)



```
for ( int i = 1; i < n; ++i )
    for ( int j = 0; j < i; ++j )
    {
        double t = A[ i ][ j ];
        A[ i ][ j ] = A[ j ][ i ];
        A[ j ][ i ] = t;
    }
```

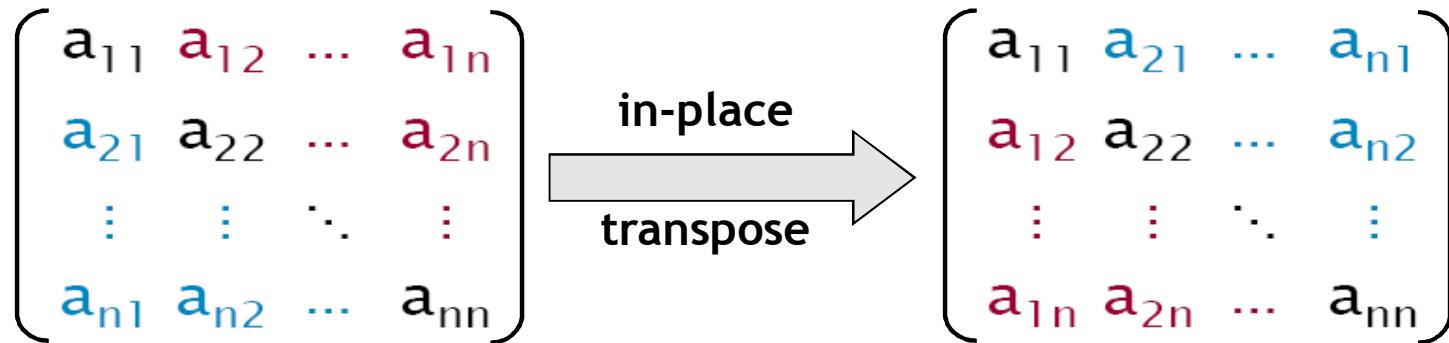
Allows all iterations of the loop
to be executed in parallel.

Serial Code

```
parallel for ( int i = 1; i < n; ++i )
    for ( int j = 0; j < i; ++j )
    {
        double t = A[ i ][ j ];
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    }
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Parallel Code

Loop Parallelism (Data Parallelism)



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        A[ j ][ i ] = t;
    }
```

Parallel Code

Nested Parallelism (Task Parallelism)

$$nC_r = {}^{n-1}C_{r-1} + {}^{n-1}C_r$$

```
int comb ( int n, int r )
{
    if ( r > n ) return 0;
    if ( r == 0 || r == n ) return 1;

    int x, y;

    x = comb( n - 1, r - 1 );
    y = comb( n - 1, r );

    return ( x + y );
}
```

Control cannot pass this point until all spawned children have returned.

Serial Code

Grant permission to execute the called (spawned) function in parallel with the caller.

```
int comb ( int n, int r )
{
    if ( r > n ) return 0;
    if ( r == 0 || r == n ) return 1;

    int x, y;

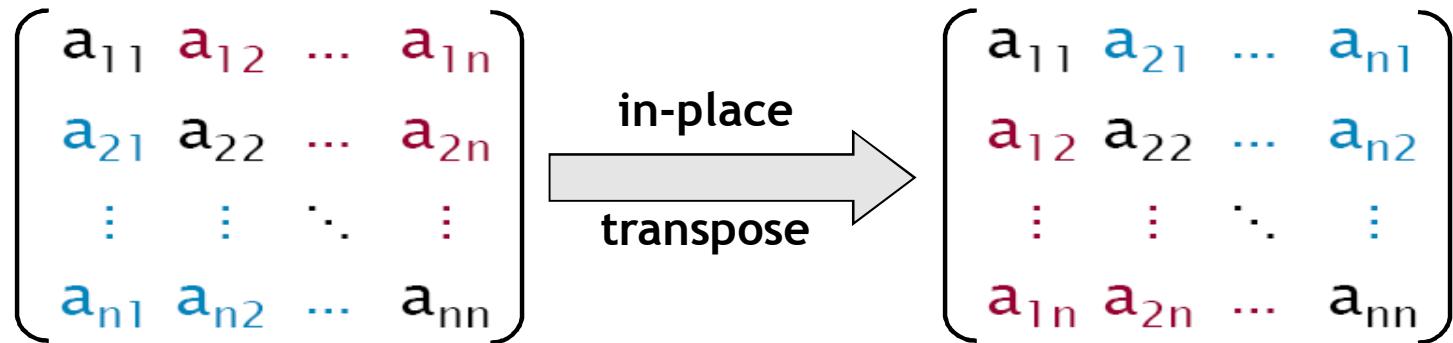
    x = spawn comb( n - 1, r - 1 );
    y = comb( n - 1, r );

    sync;

    return ( x + y );
}
```

Parallel Code

Loop Parallelism (Data Parallelism)



```
for ( int i = 1; i < n; ++i )
    for ( int j = 0; j < i; ++j )
    {
        double t = A[ i ][ j ];
        A[ i ][ j ] = A[ j ][ i ];
        A[ j ][ i ] = t;
    }
```

Allows all iterations of the loop to be executed in parallel.

Can be converted to spawns and syncs using recursive divide-and-conquer.

Serial Code

```
parallel for ( int i = 1; i < n; ++i )
    for ( int j = 0; j < i; ++j )
    {
        double t = A[ i ][ j ];
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    }
```

Parallel Code

Parallel Execution Model

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Parallel Execution Model

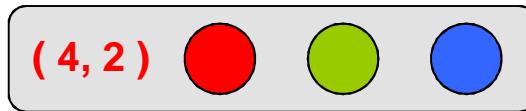
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}
```

1



Parallel Execution Model

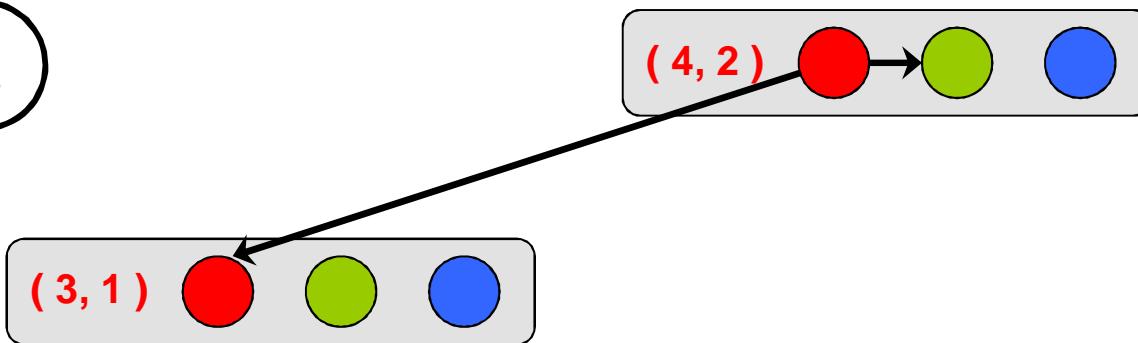
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    sync;

    return ( x + y );
}
```

2



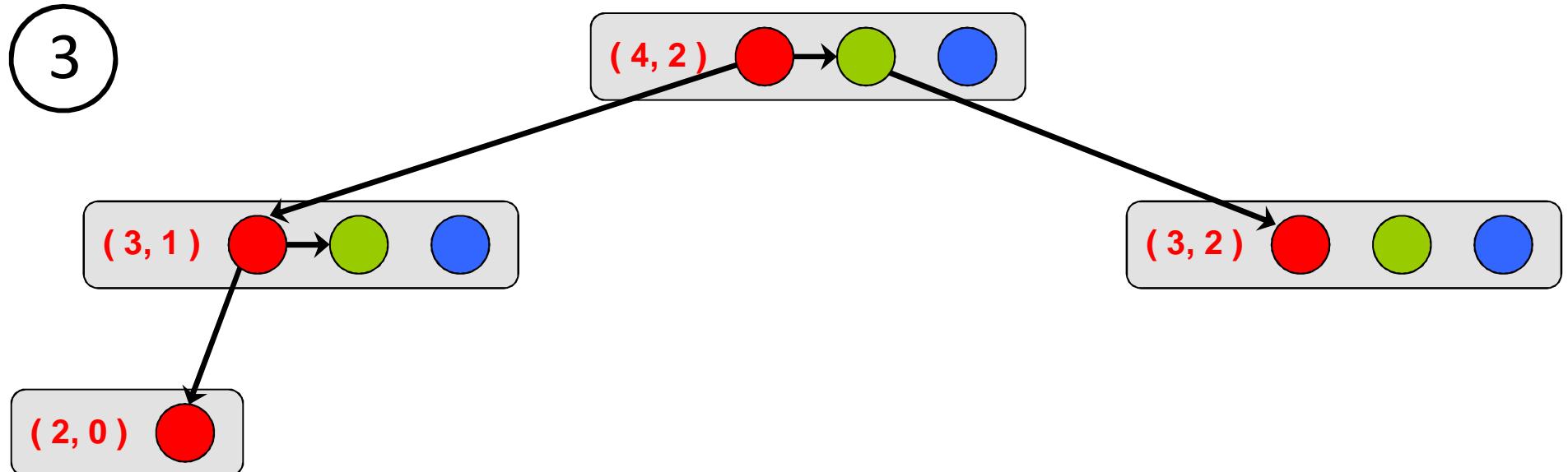
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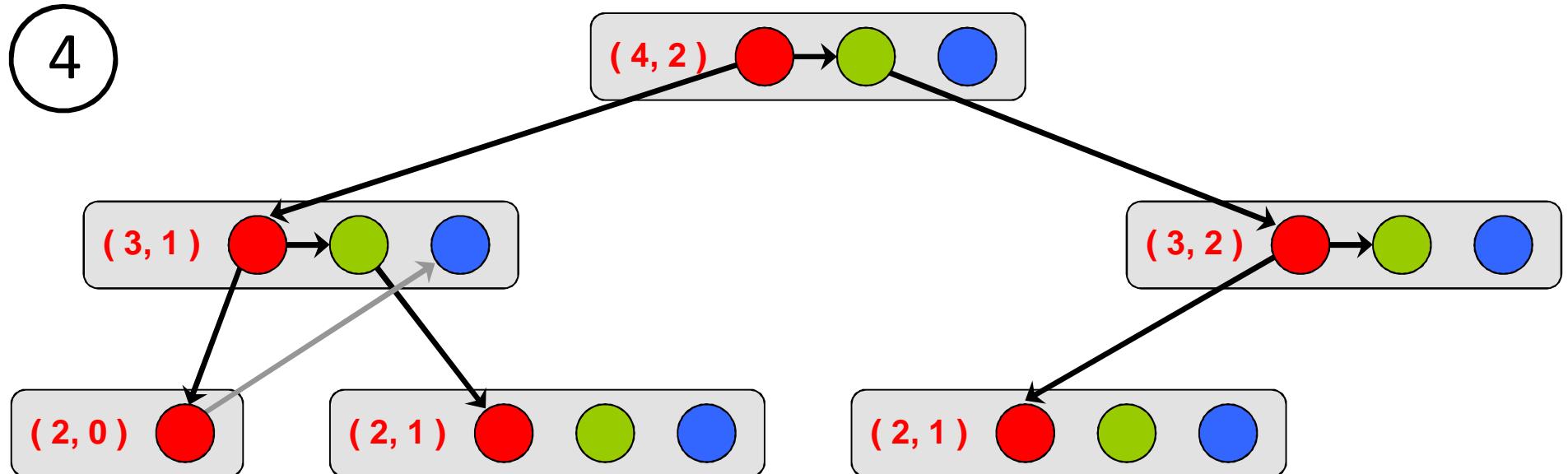
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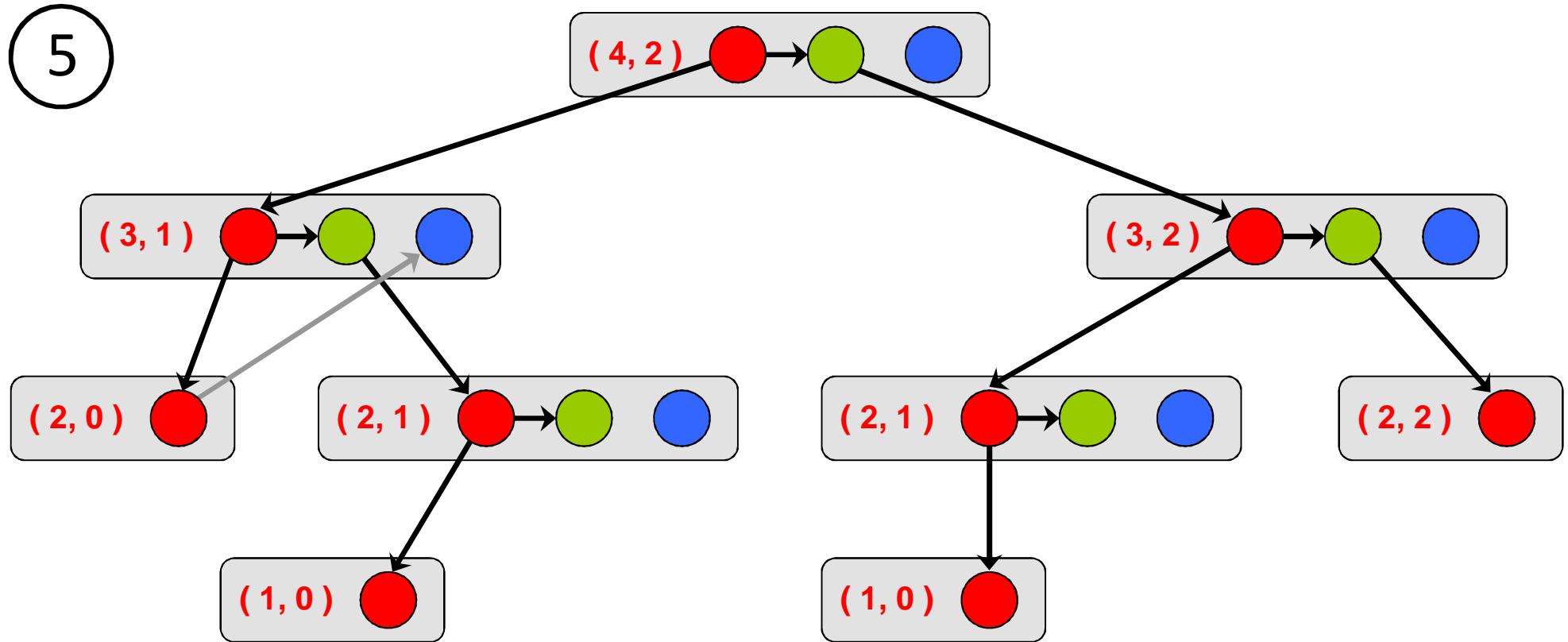
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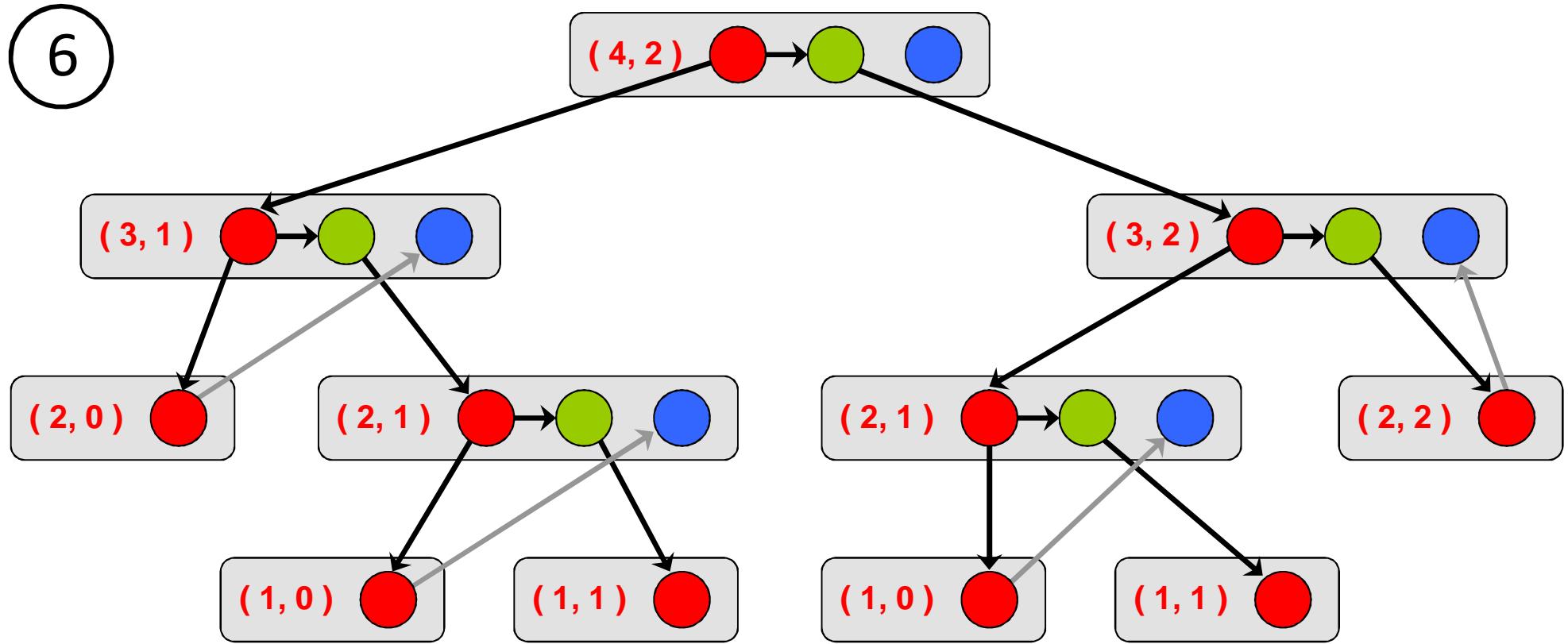
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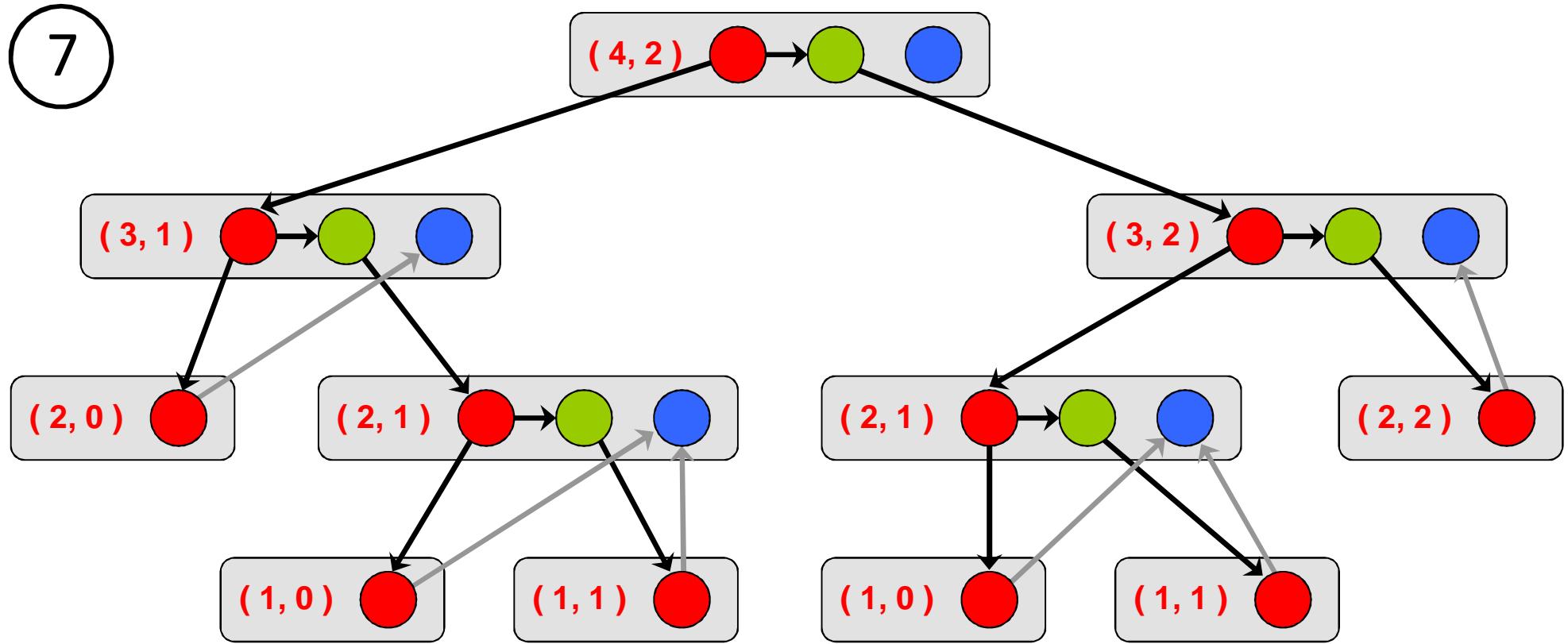
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Parallel Execution Model

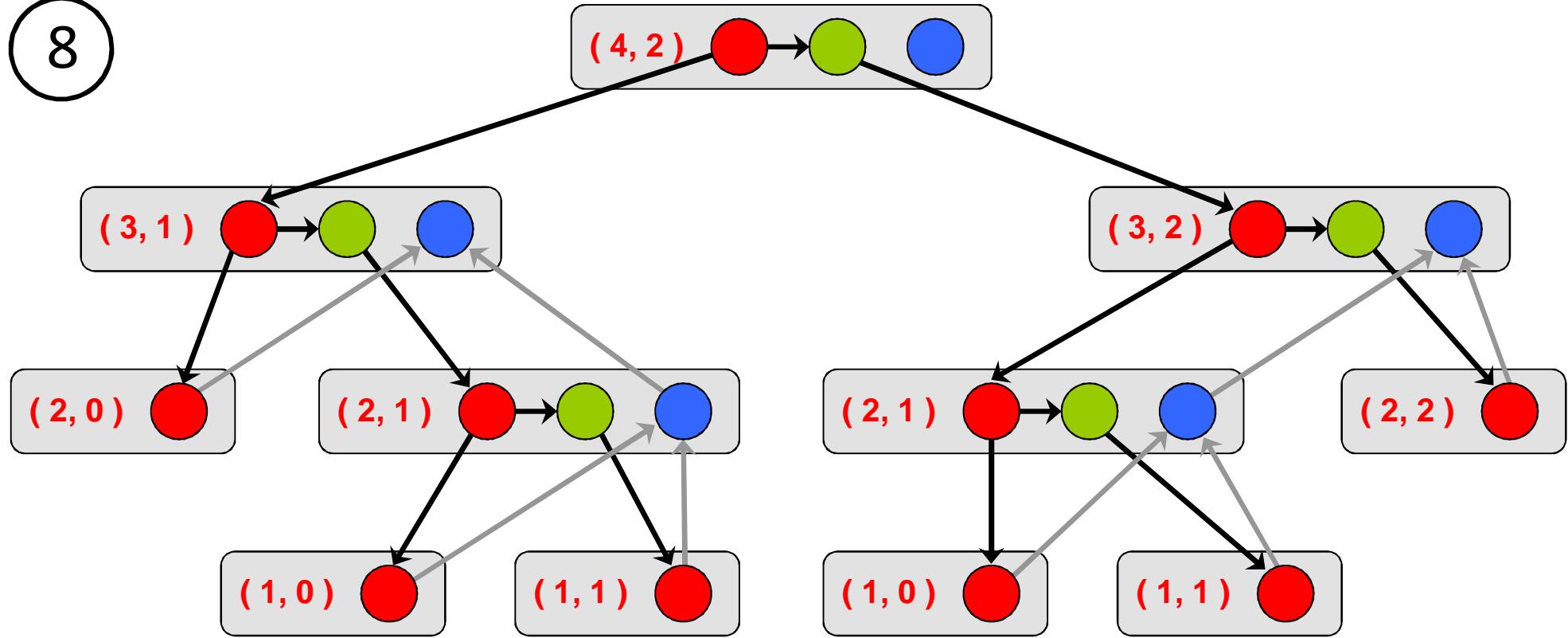
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    sync;

    return ( x + y );
}
```

8



Parallel Execution Model

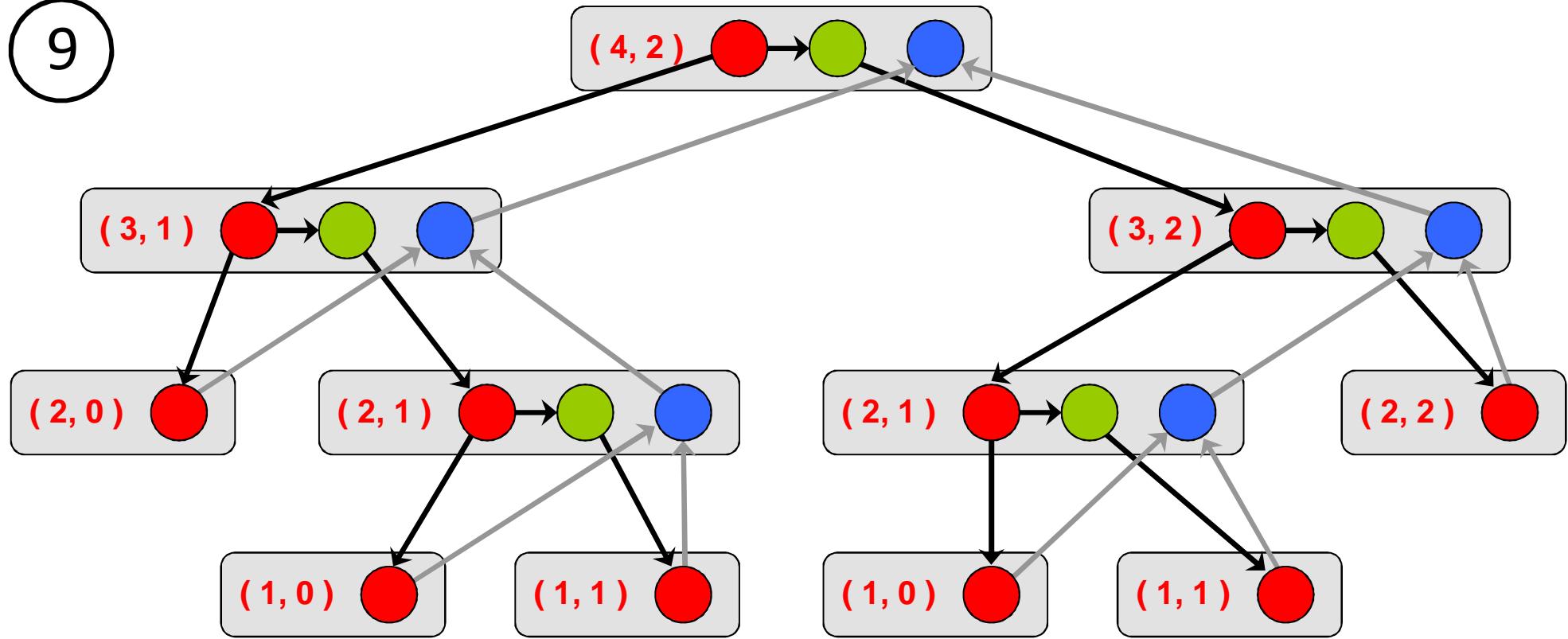
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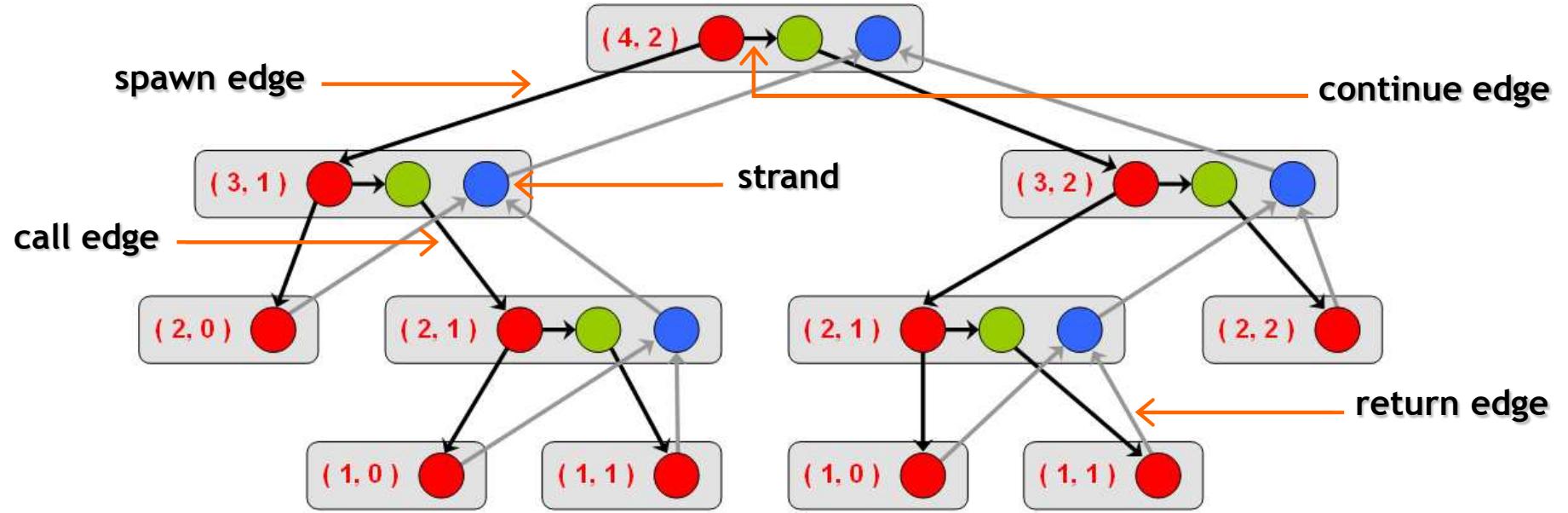
    sync;

    return ( x + y );
}
```

9

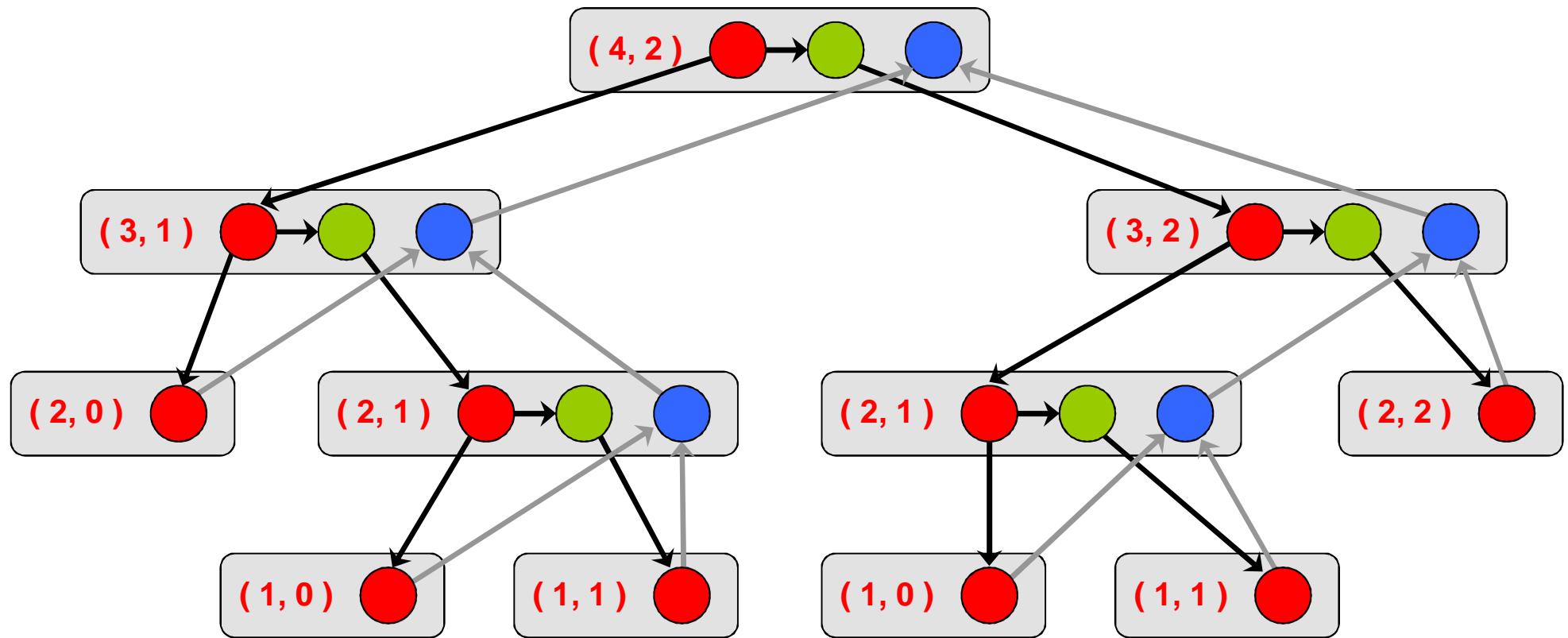


Computation DAG



- A parallel instruction stream is represented by a DAG $G = (V, E)$.
- Each vertex $v \in V$ is a *strand* – a maximal sequence of instructions ending with a spawn, sync or return (implicit or explicit).
- Each edge $e \in E$ is a *spawn*, *call*, *continue* or *return* edge.

Parallelism in $\text{comb}(4, 2)$



work: $T_1 = \# \text{nodes in the DAG} = 21$

span: $T_\infty = \# \text{nodes on the longest path in the DAG} = 9$

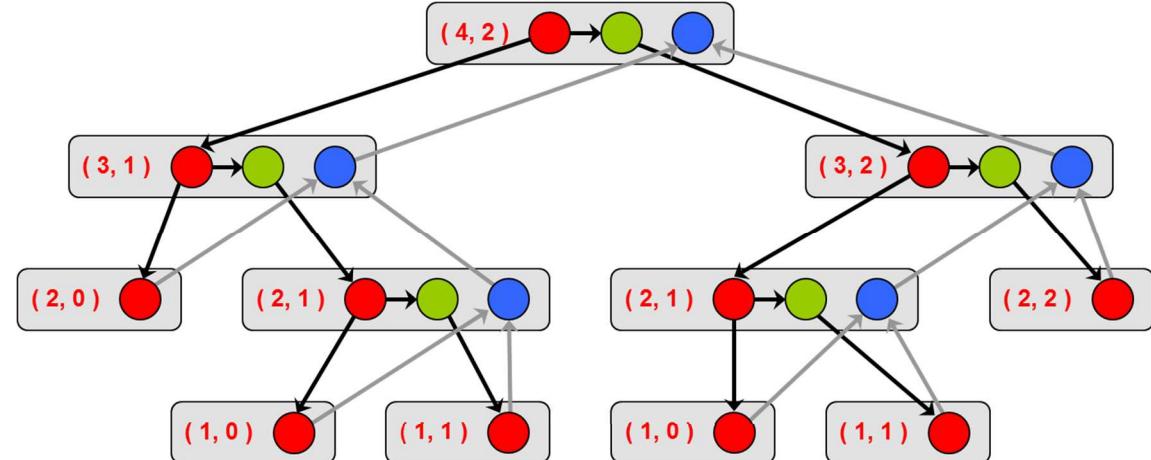
Critical path

parallelism = $T_1 / T_\infty = 21 / 9 \approx 2.33$

Only marginal performance gains with more than 2 cores!

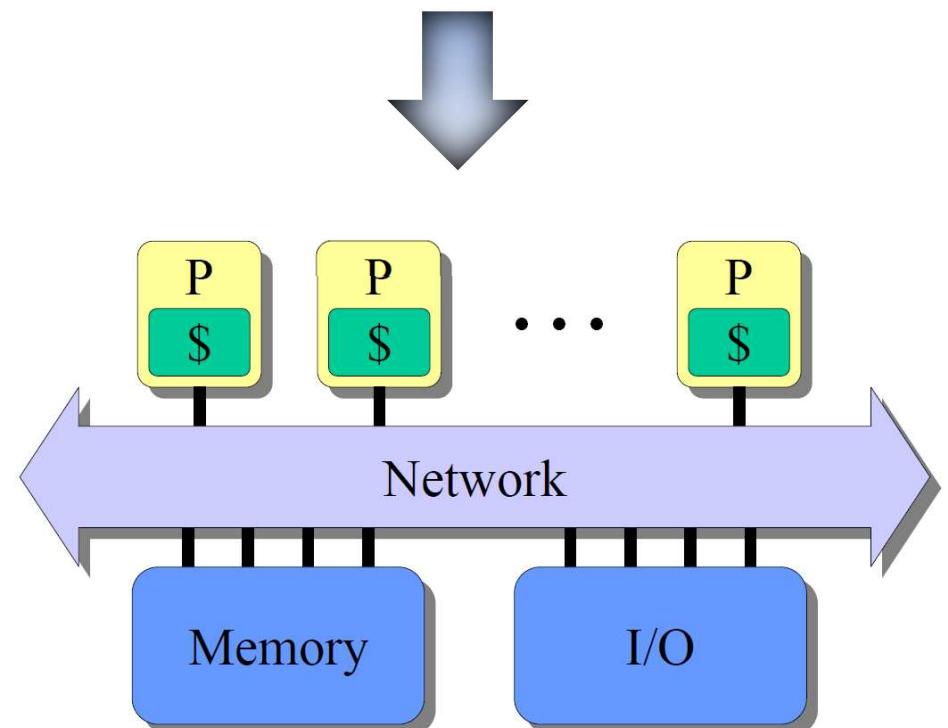
Scheduler

A *runtime/online scheduler* maps tasks to processing elements dynamically at runtime.



The map is called a *schedule*.

An *offline scheduler* prepares the schedule prior to the actual execution of the program.



Greedy Scheduling

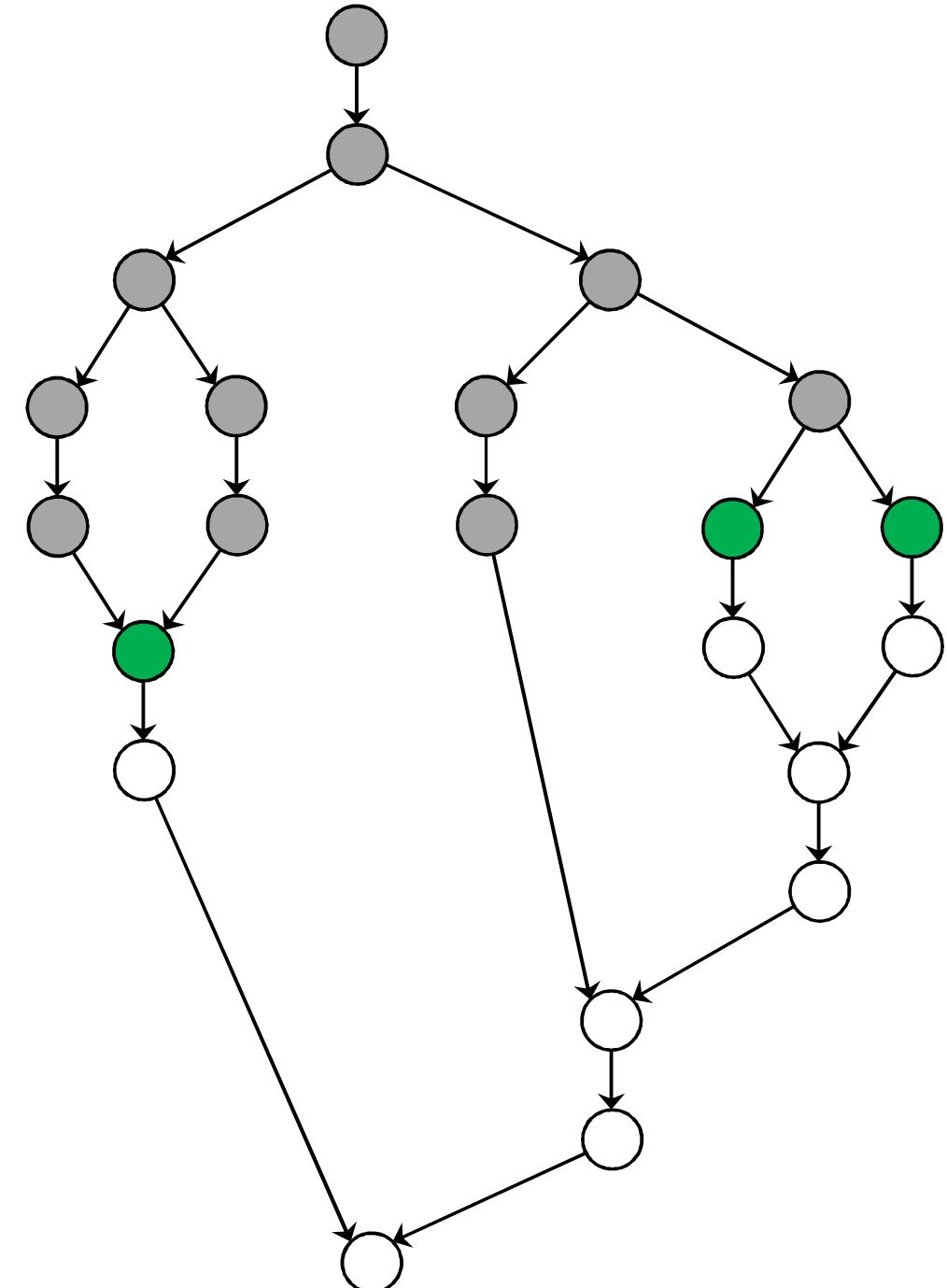
A strand / task is called *ready* provided all its parents (if any) have already been executed.

● executed task

● ready to be executed

○ not yet ready

A *greedy scheduler* tries to perform as much work as possible at every step.



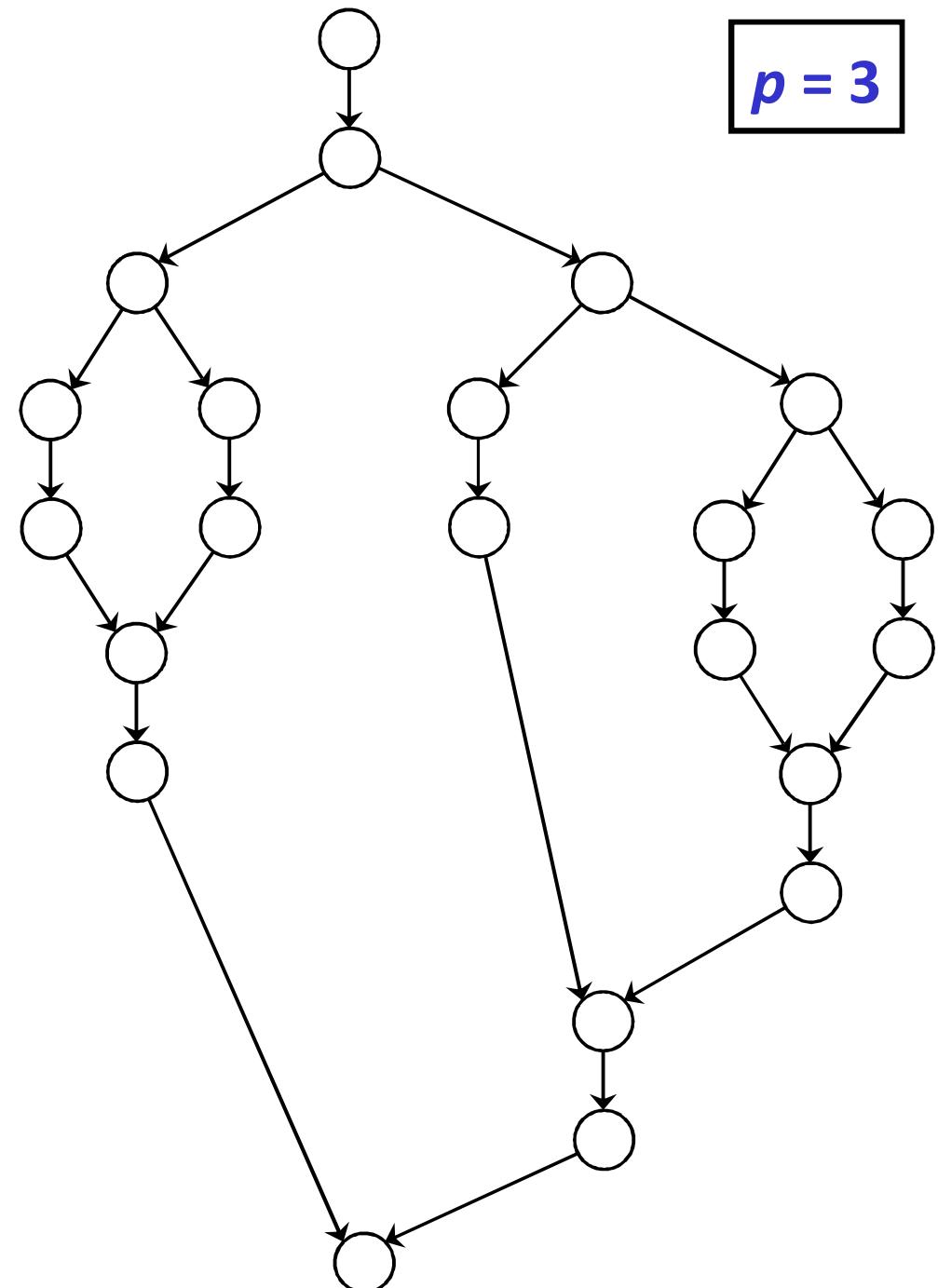
A Centralized Greedy Scheduler

$p = 3$

Let p = number of cores

At every step:

- if $\geq p$ tasks are ready:
execute any p of them
(complete step)
- if $< p$ tasks are ready:
execute all of them
(incomplete step)



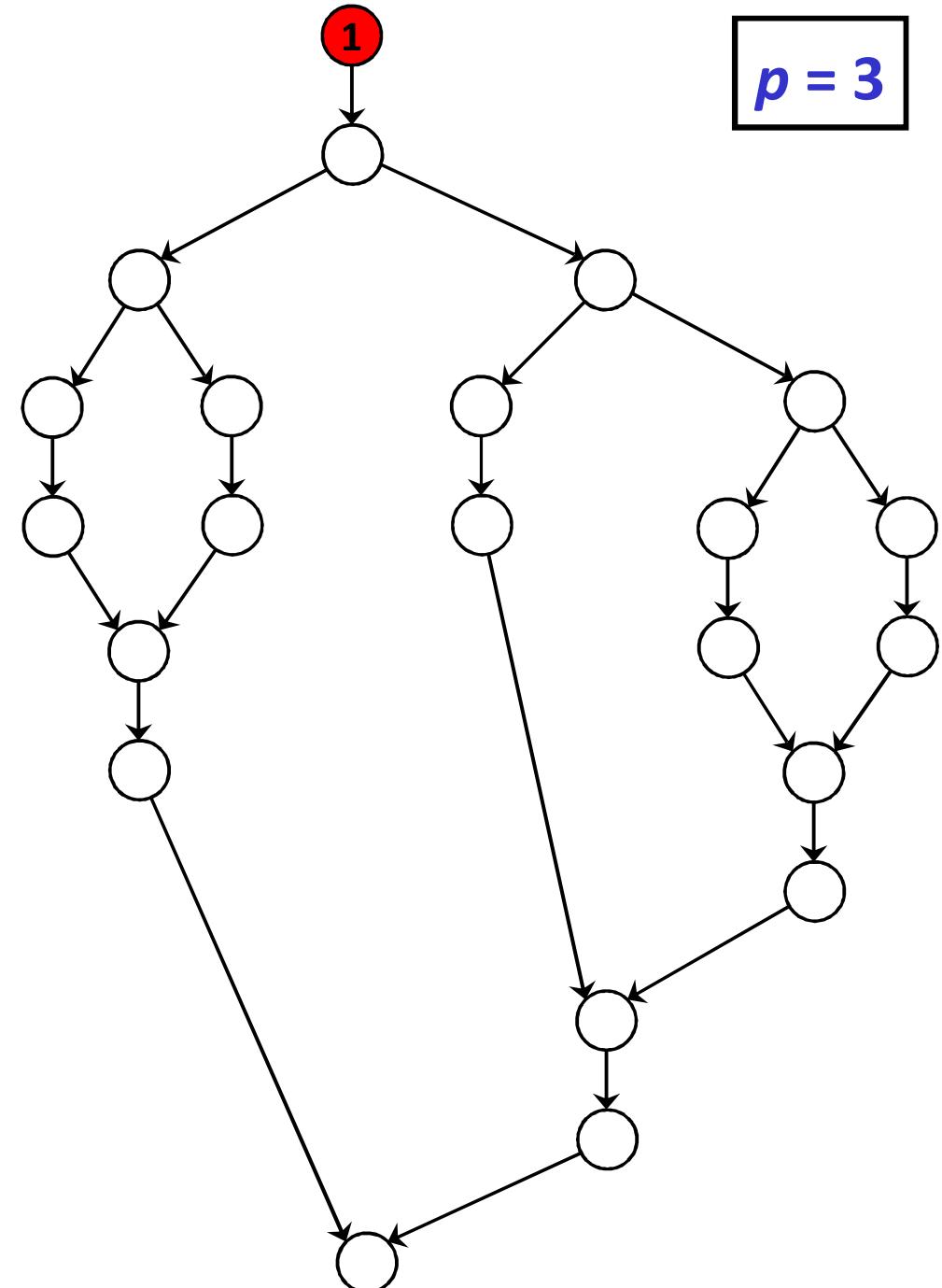
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(incomplete step)



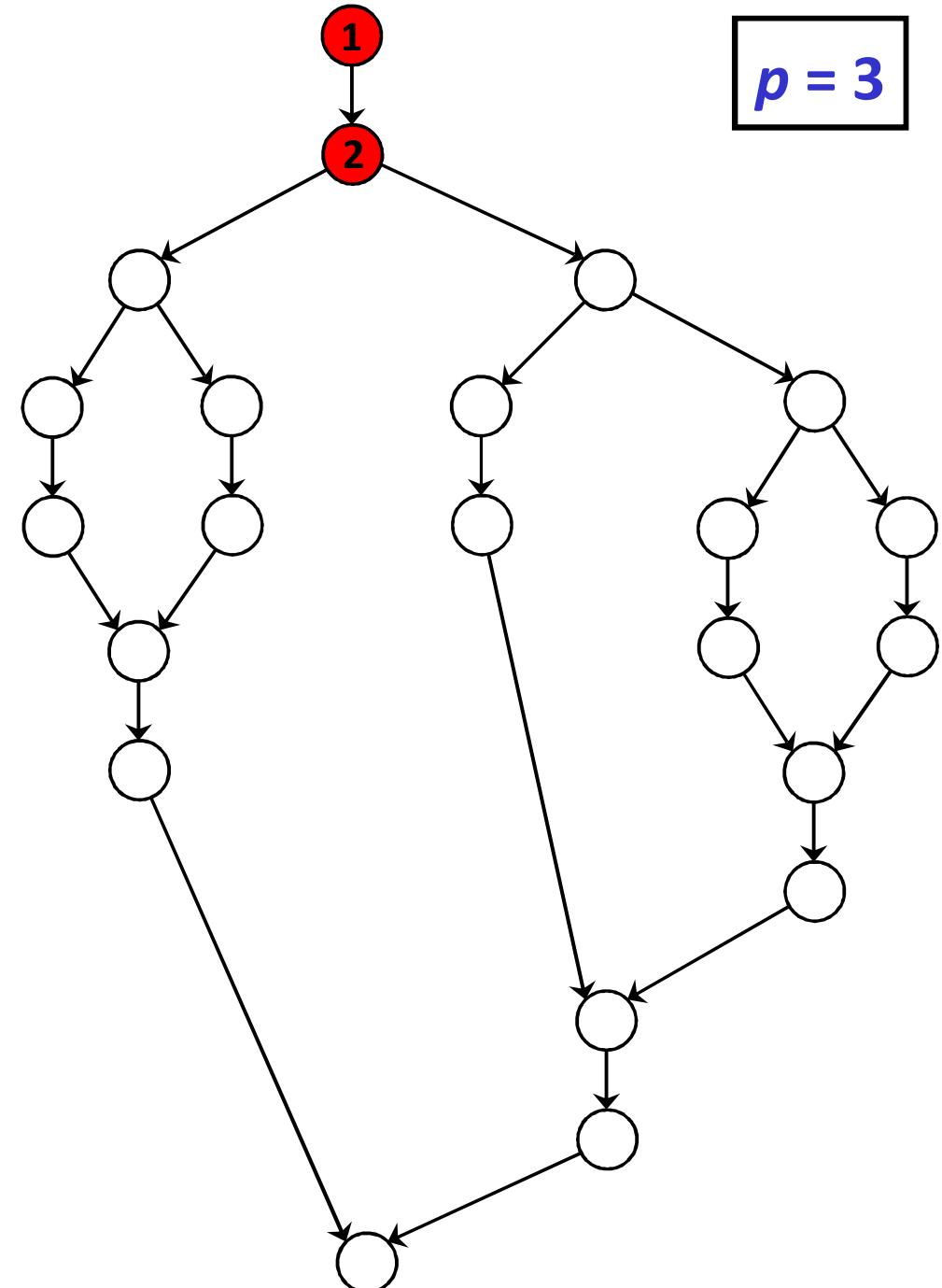
A Centralized Greedy Scheduler

$p = 3$

Let $p = \text{number of cores}$

At every step:

- if $\geq p$ tasks are ready:
execute any p of them
(complete step)
- if $< p$ tasks are ready:
execute all of them
(incomplete step)

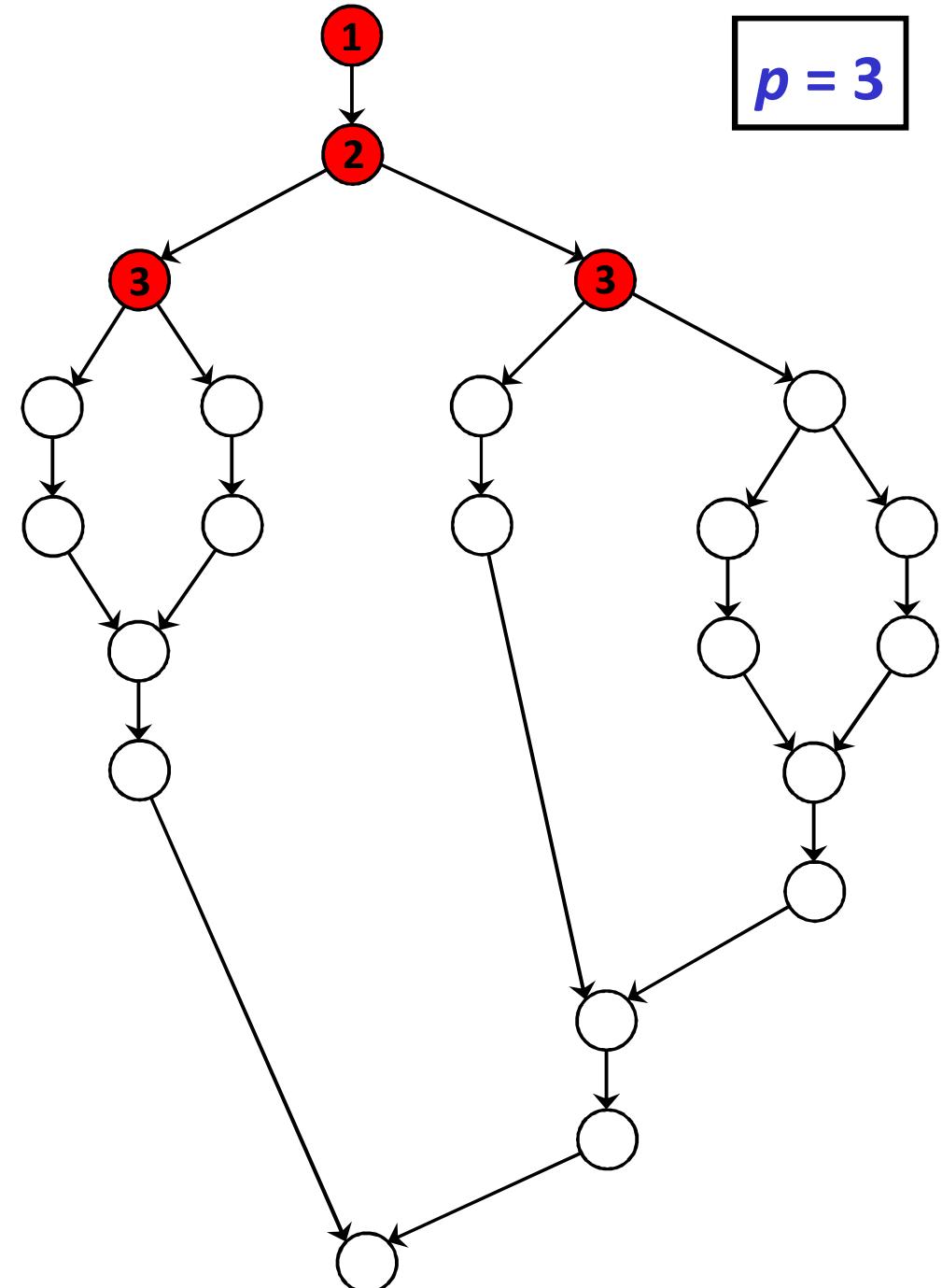


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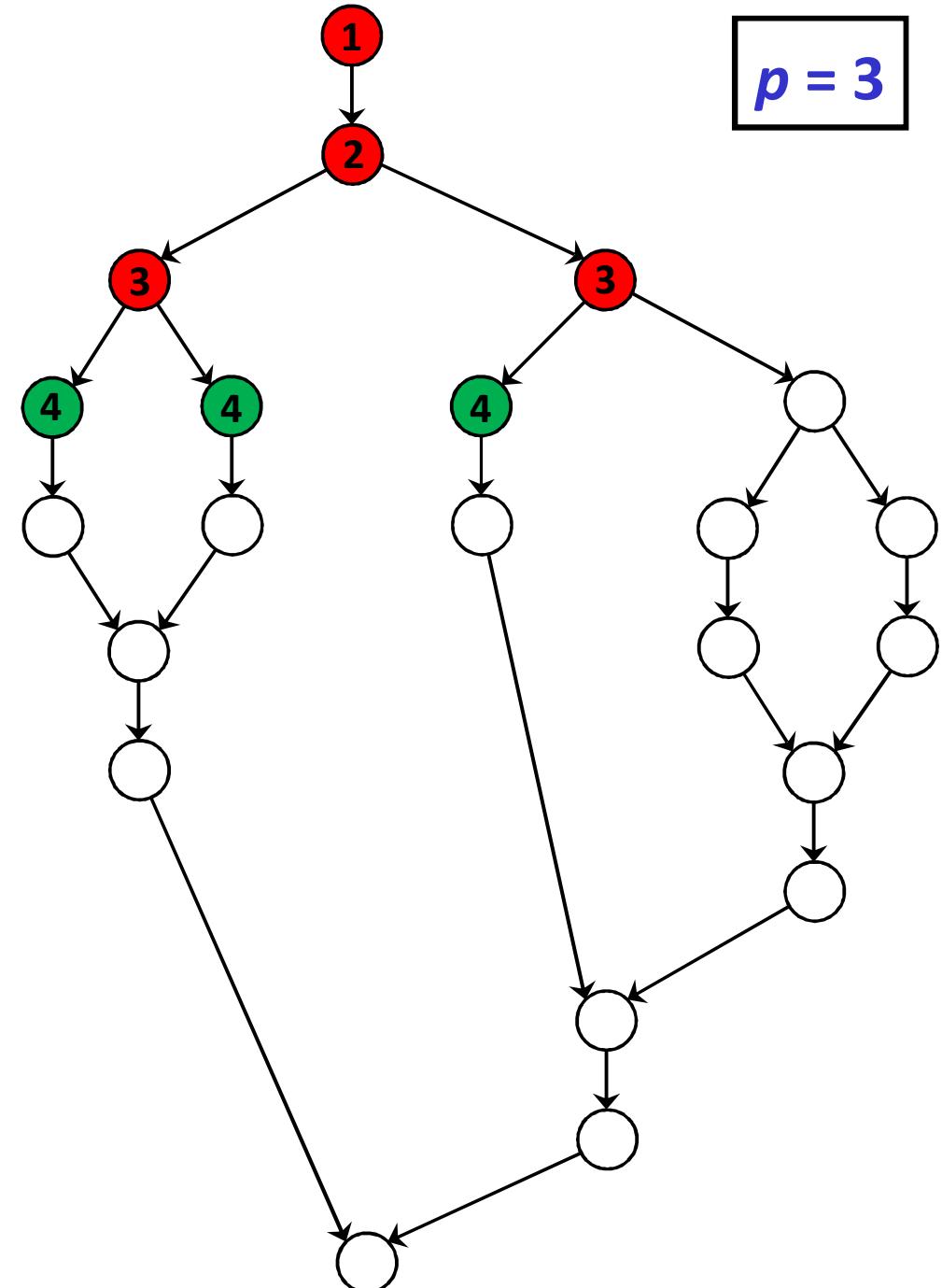
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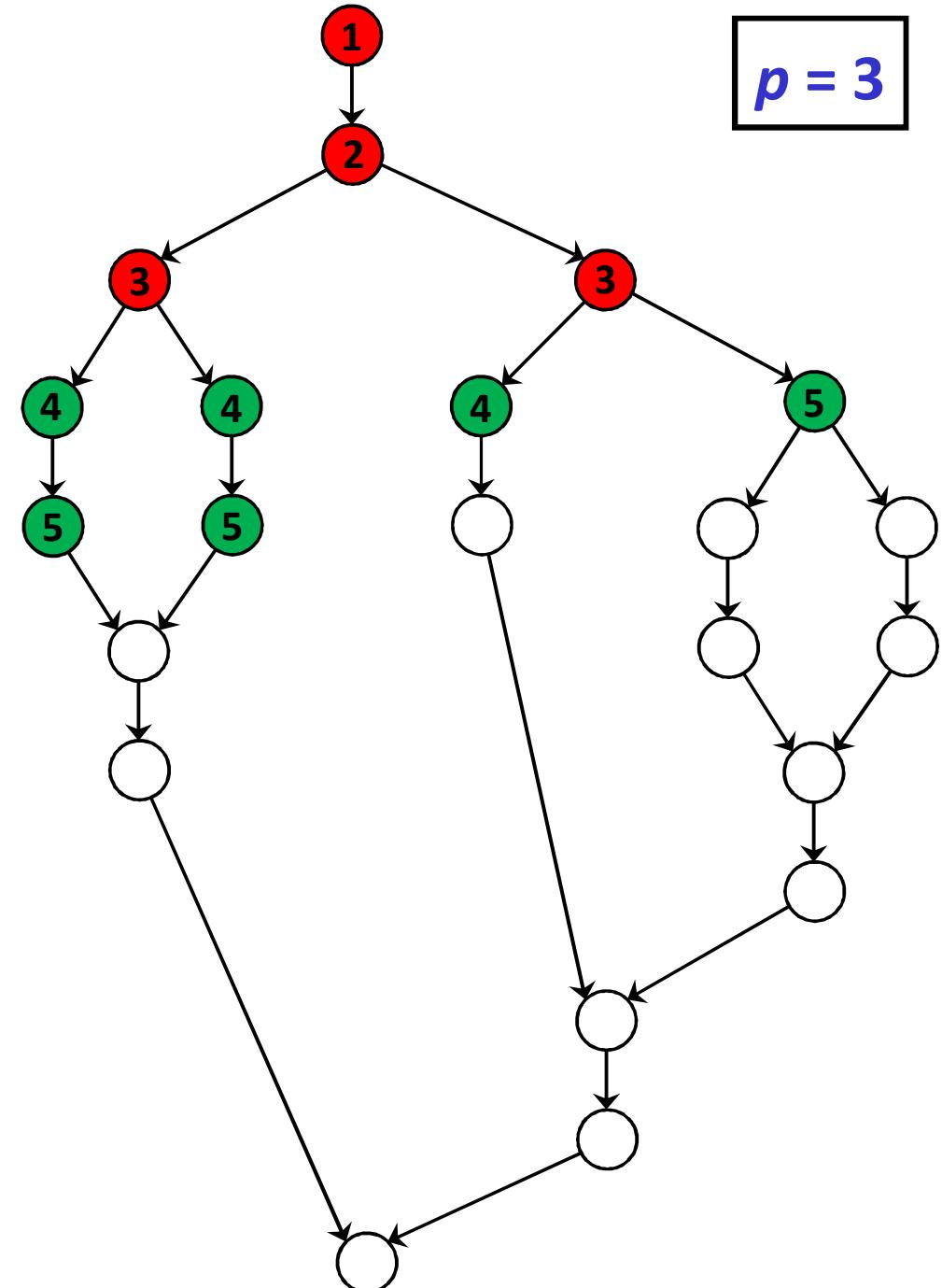
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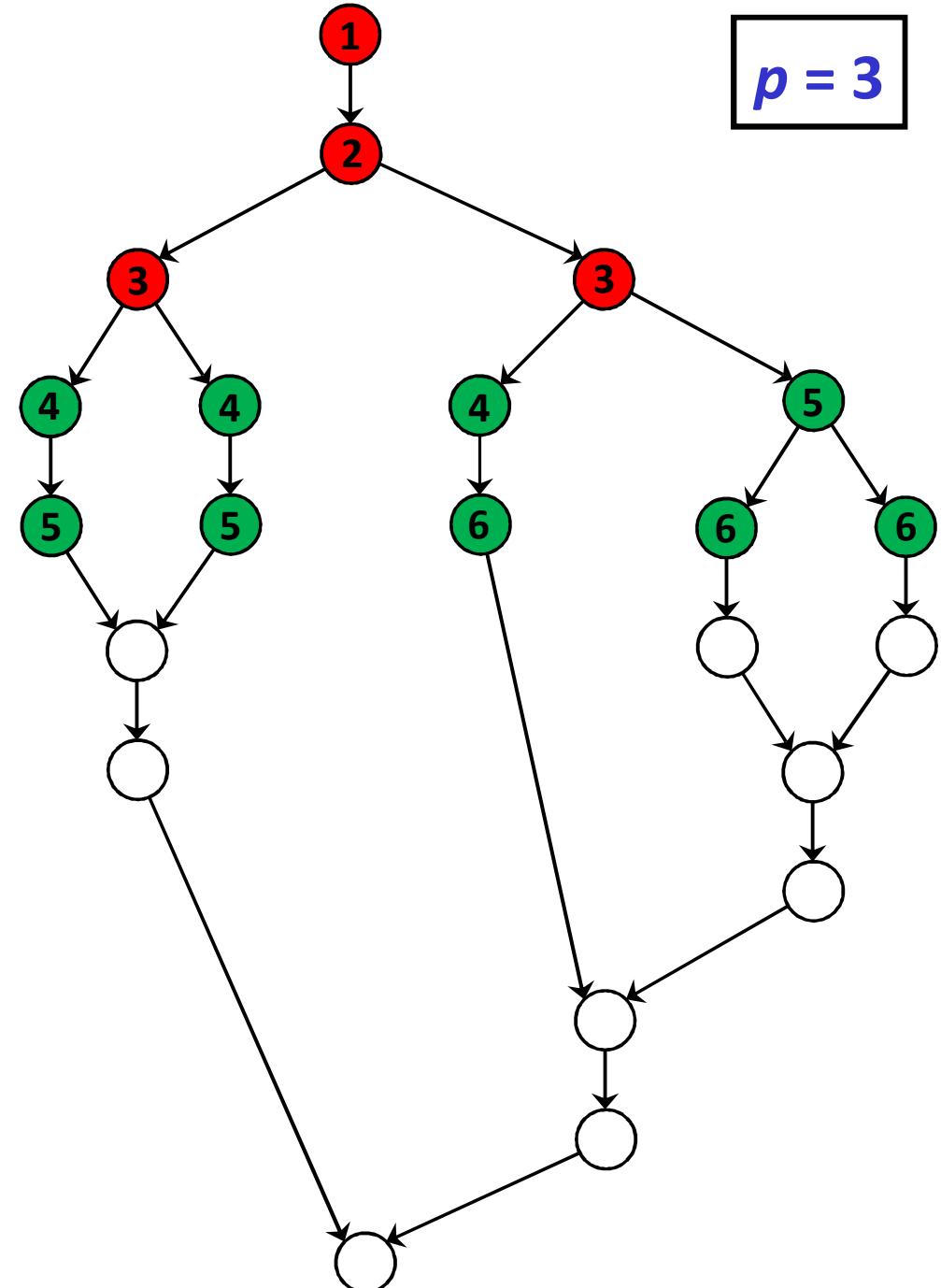


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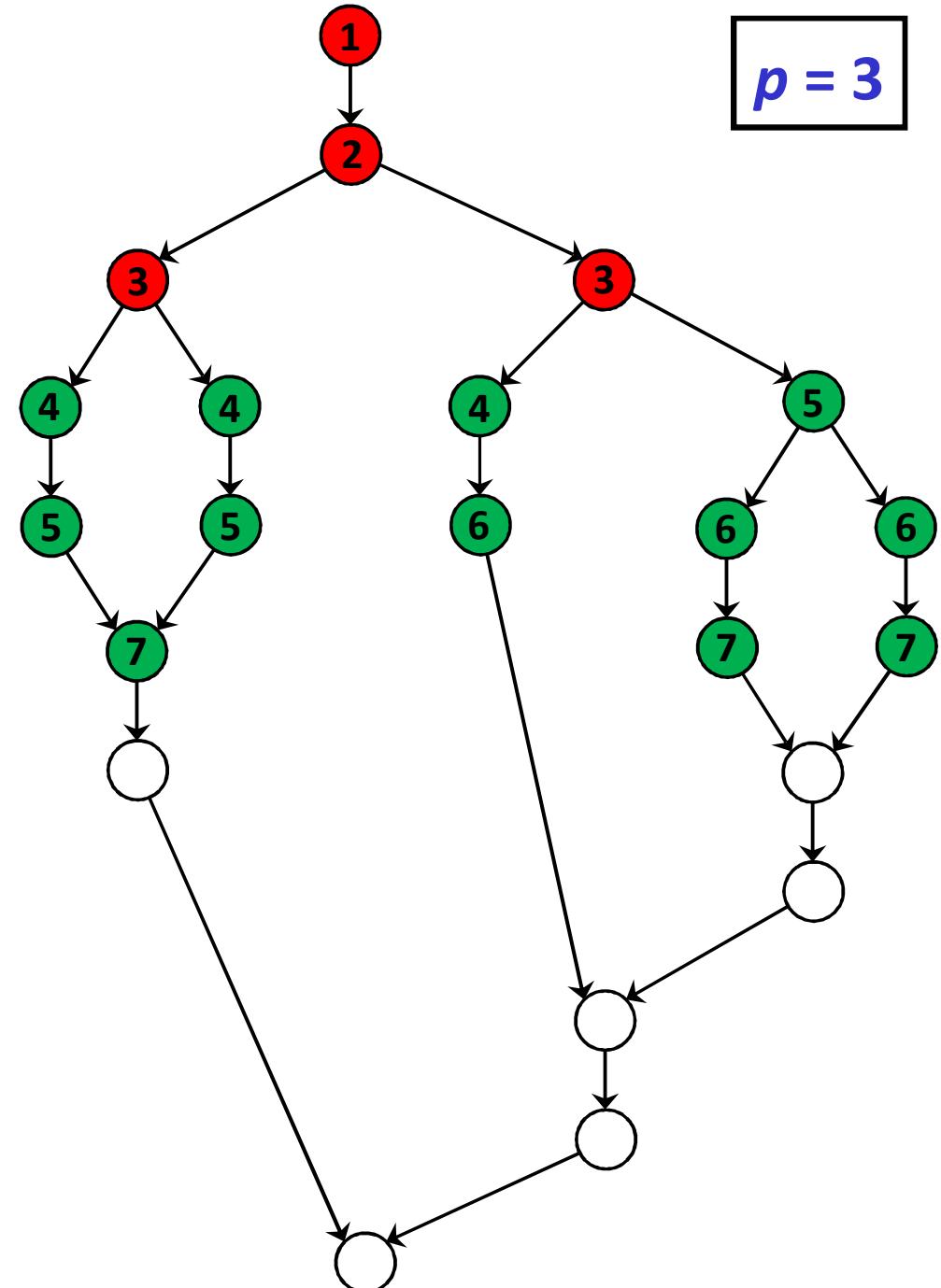
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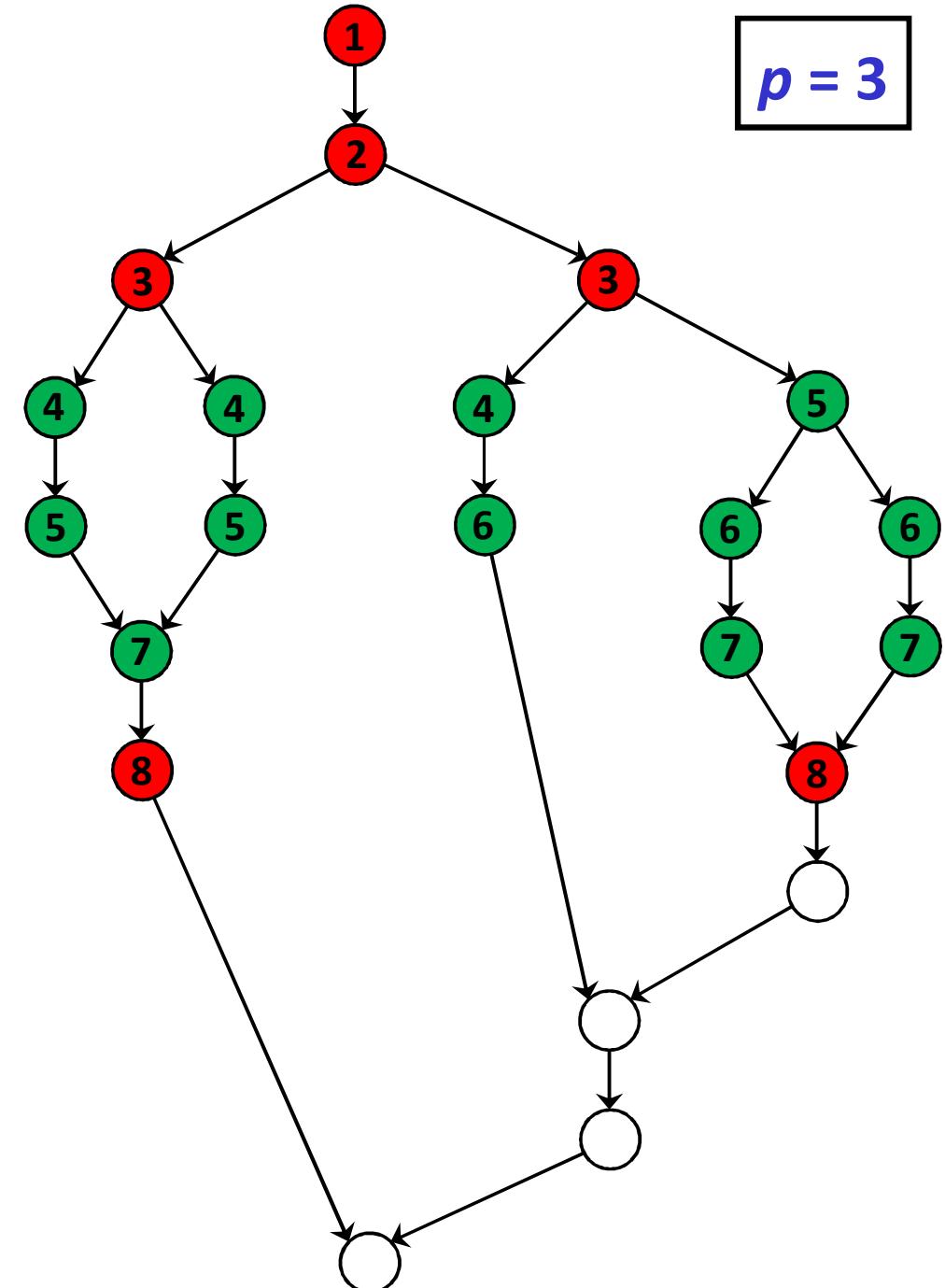
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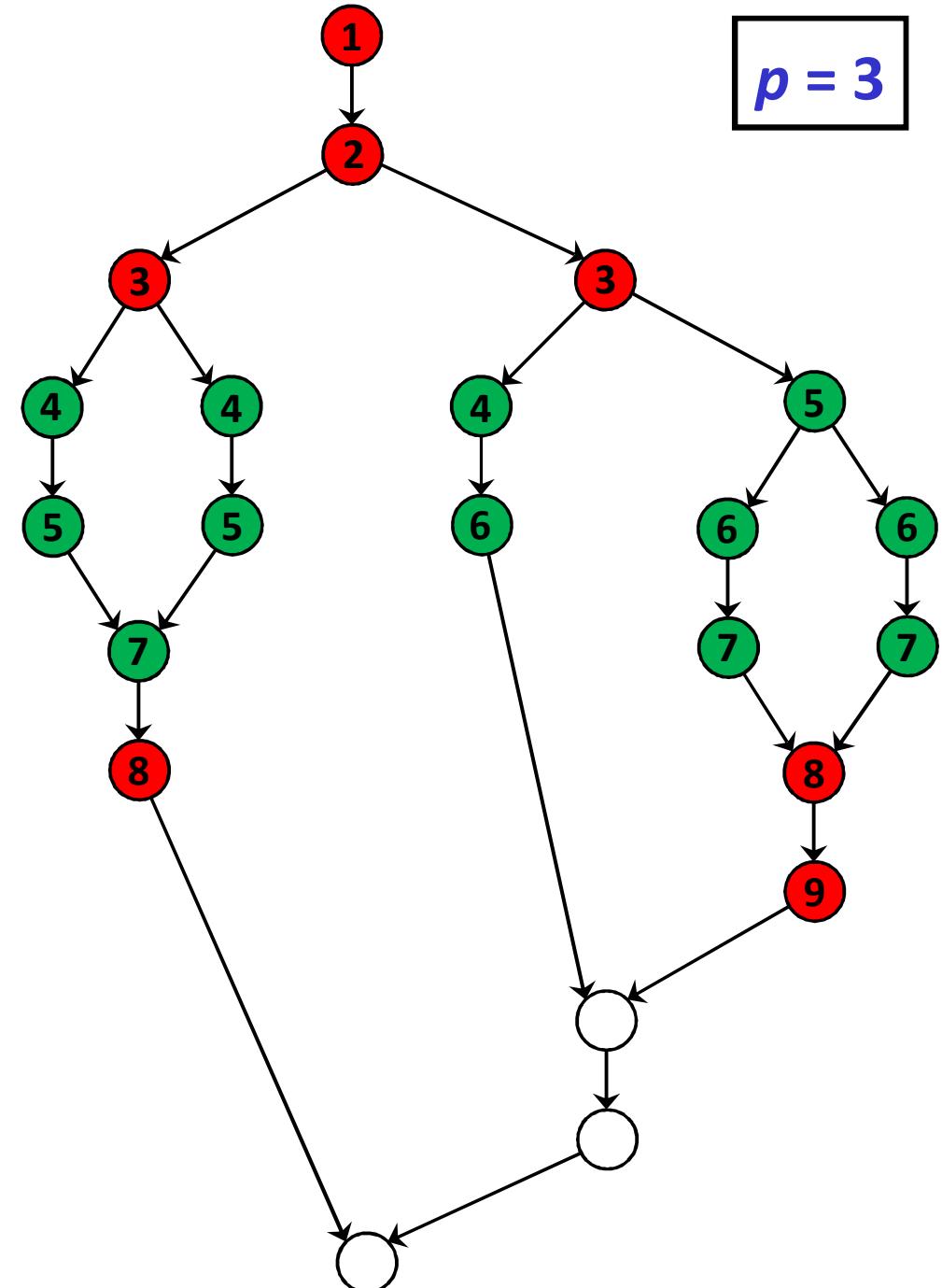
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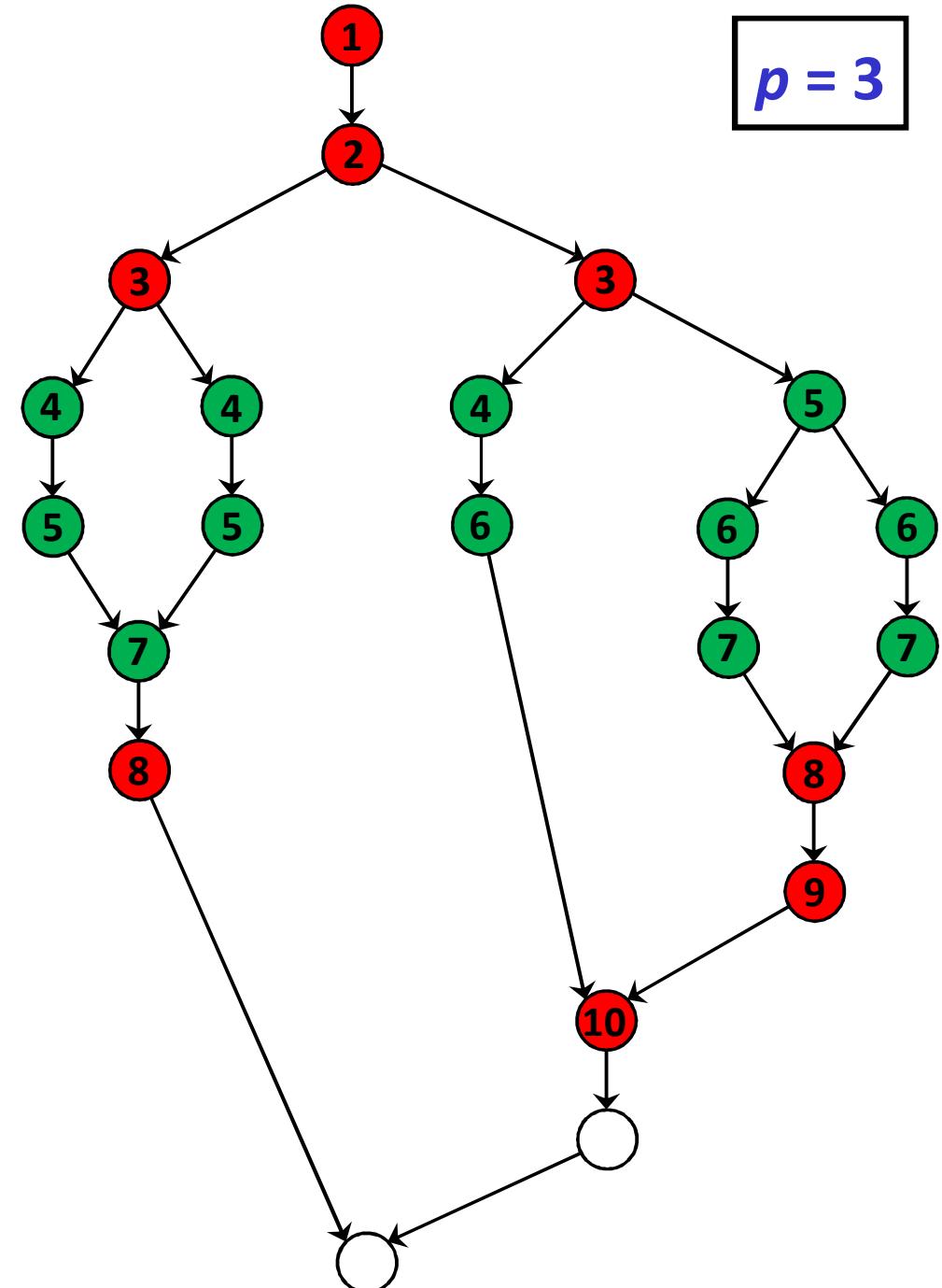
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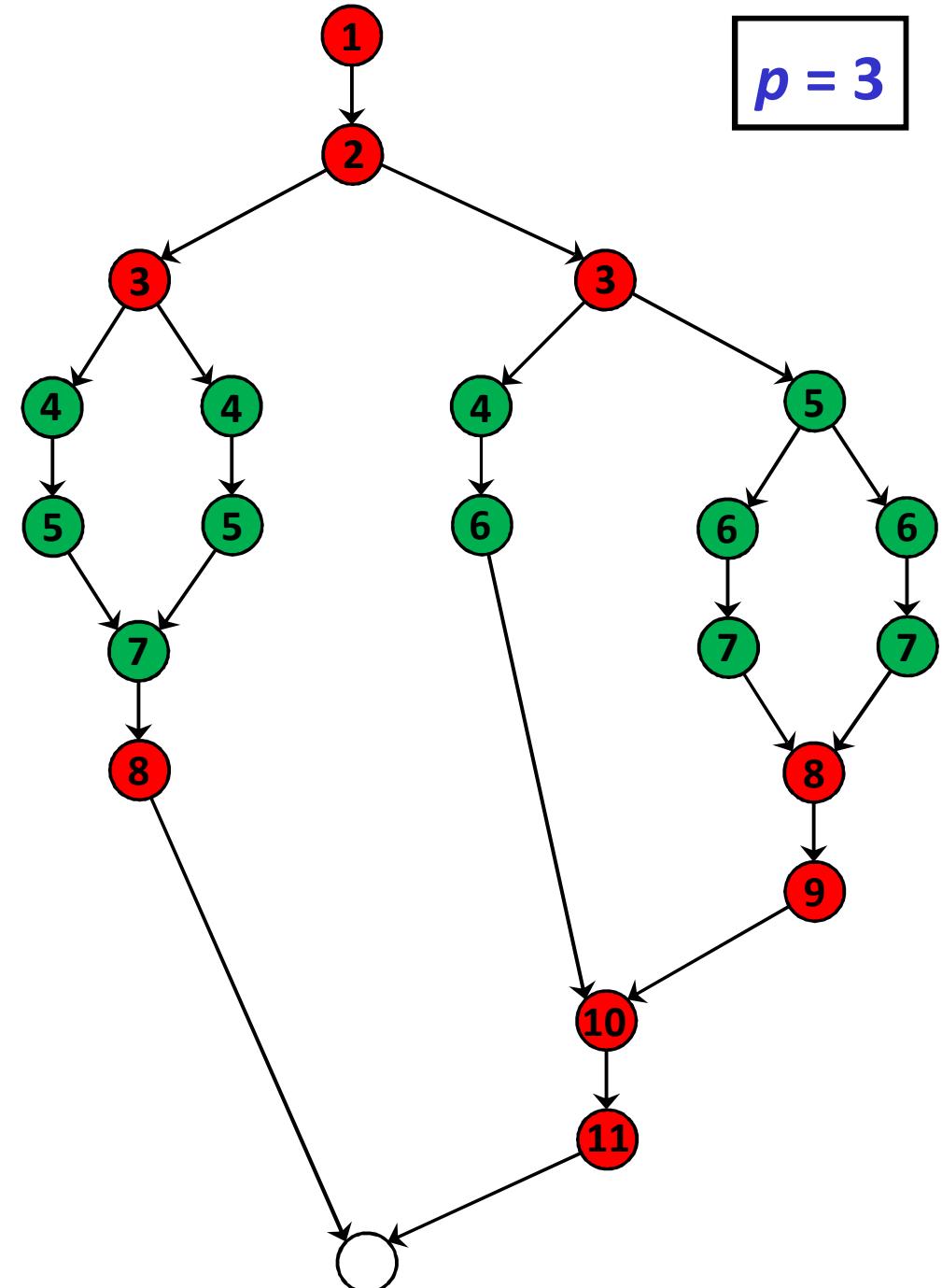
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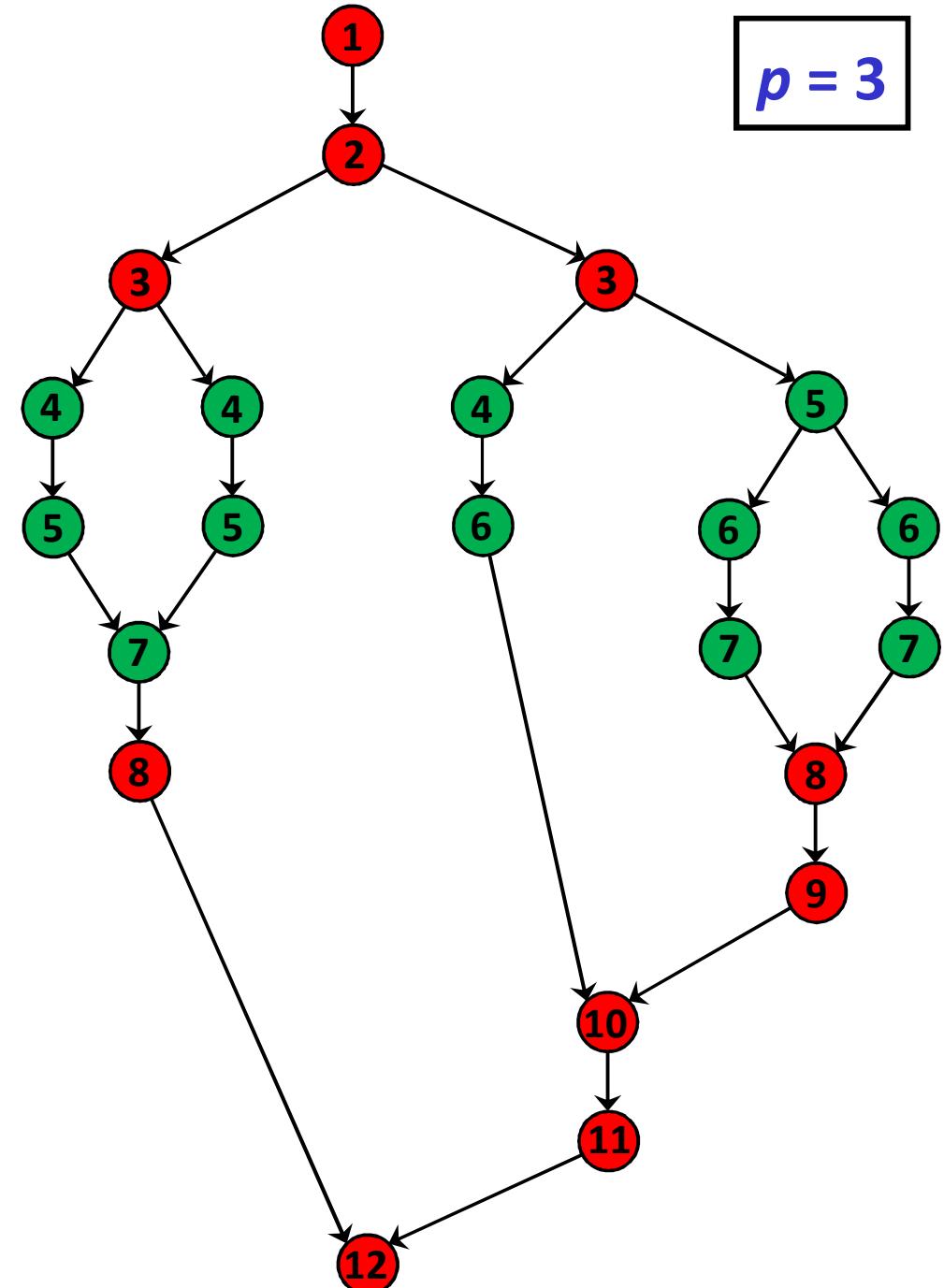
A Centralized Greedy Scheduler

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At every step:

- if $\geq p$ tasks are ready:
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Greedy Scheduling Theorem

Theorem [Graham'68, Brent'74]:

For any greedy scheduler,

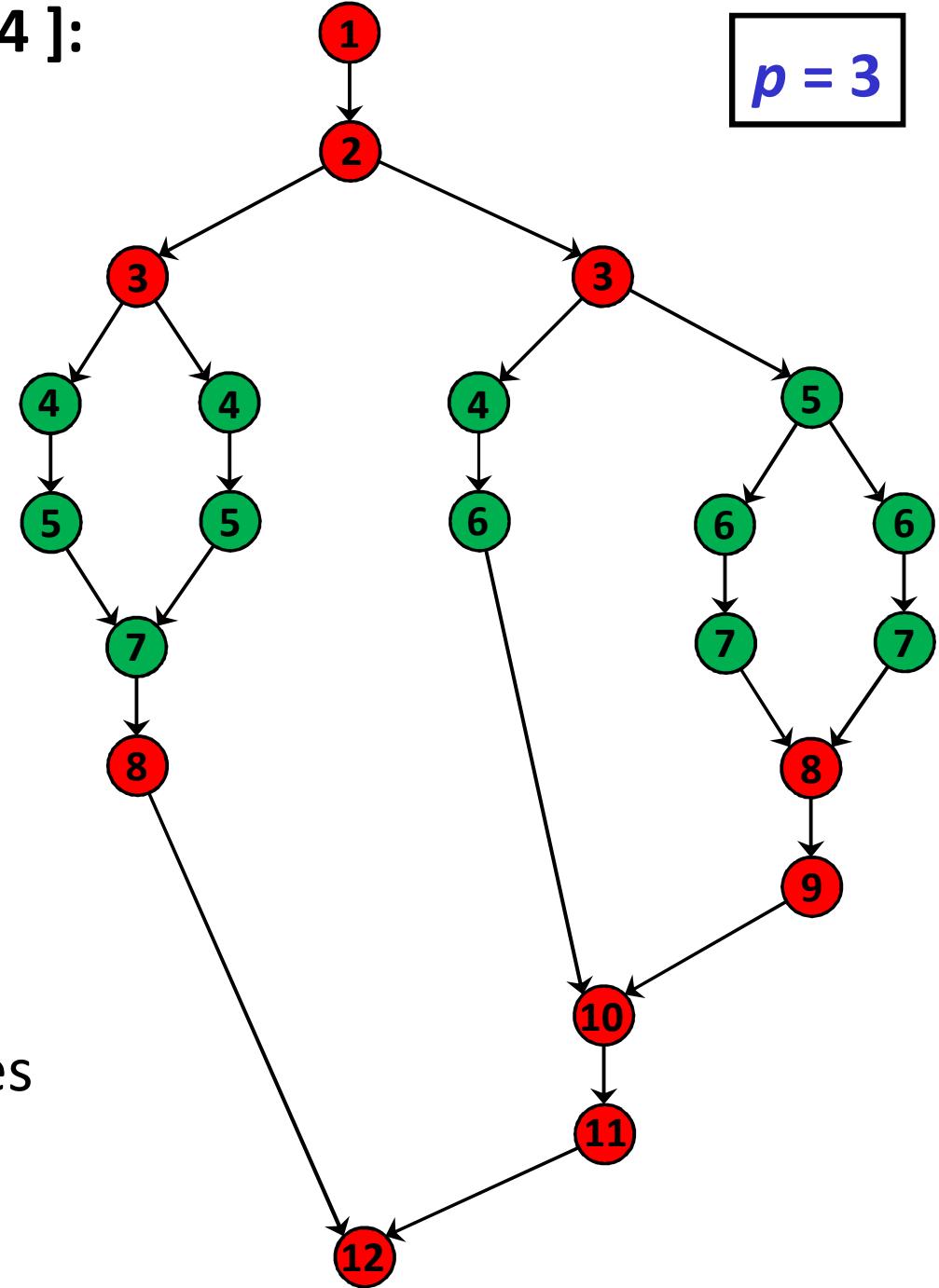
$$T_p \leq \frac{T_1}{p} + T_\infty$$

Proof:

$$\begin{aligned} T_p = & \text{#complete steps} \\ & + \text{#incomplete steps} \end{aligned}$$

- Each complete step performs p work:
 $\text{#complete steps} \leq \frac{T_1}{p}$
- Each incomplete step reduces the span by 1:
 $\text{#incomplete steps} \leq T_\infty$

$$p = 3$$



Optimality of the Greedy Scheduler

Corollary 1: For any greedy scheduler $T_p \leq 2T_p^*$, where T_p^* is the running time due to optimal scheduling on p processing elements.

Proof:

$$\text{Work law: } T_p^* \geq \frac{T_1}{p}$$

$$\text{Span law: } T_p^* \geq T_\infty$$

\therefore From Graham-Brent Theorem:

$$T_p \leq \frac{T_1}{p} + T_\infty \leq T_p^* + T_p^* = 2T_p^*$$

Optimality of the Greedy Scheduler

Corollary 2: Any greedy scheduler achieves $S_p \approx p$ (i.e., nearly linear speedup) provided parallelism, $P = \frac{T_1}{T_\infty} \gg p$.

Proof:

$$\text{Given, } P = \frac{T_1}{T_\infty} \gg p \Rightarrow \frac{T_1}{p} \gg T_\infty$$

\therefore From Graham-Brent Theorem:

$$\begin{aligned} T_p &\leq \frac{T_1}{p} + T_\infty \approx \frac{T_1}{p} \\ \Rightarrow \frac{T_1}{T_p} &\approx p \Rightarrow S_p \approx p \end{aligned}$$

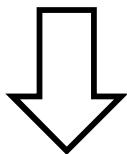
Parallel Matrix Multiplication

Parallel Iterative MM

Iter-MM (Z, X, Y)

{ *X, Y, Z are $n \times n$ matrices,
where n is a positive integer* }

1. *for* $i \leftarrow 1$ *to* n *do*
2. *for* $j \leftarrow 1$ *to* n *do*
3. $Z[i][j] \leftarrow 0$
4. *for* $k \leftarrow 1$ *to* n *do*
5. $Z[i][j] \leftarrow Z[i][j] + X[i][k] \cdot Y[k][j]$



Par-Iter-MM (Z, X, Y)

{ *X, Y, Z are $n \times n$ matrices,
where n is a positive integer* }

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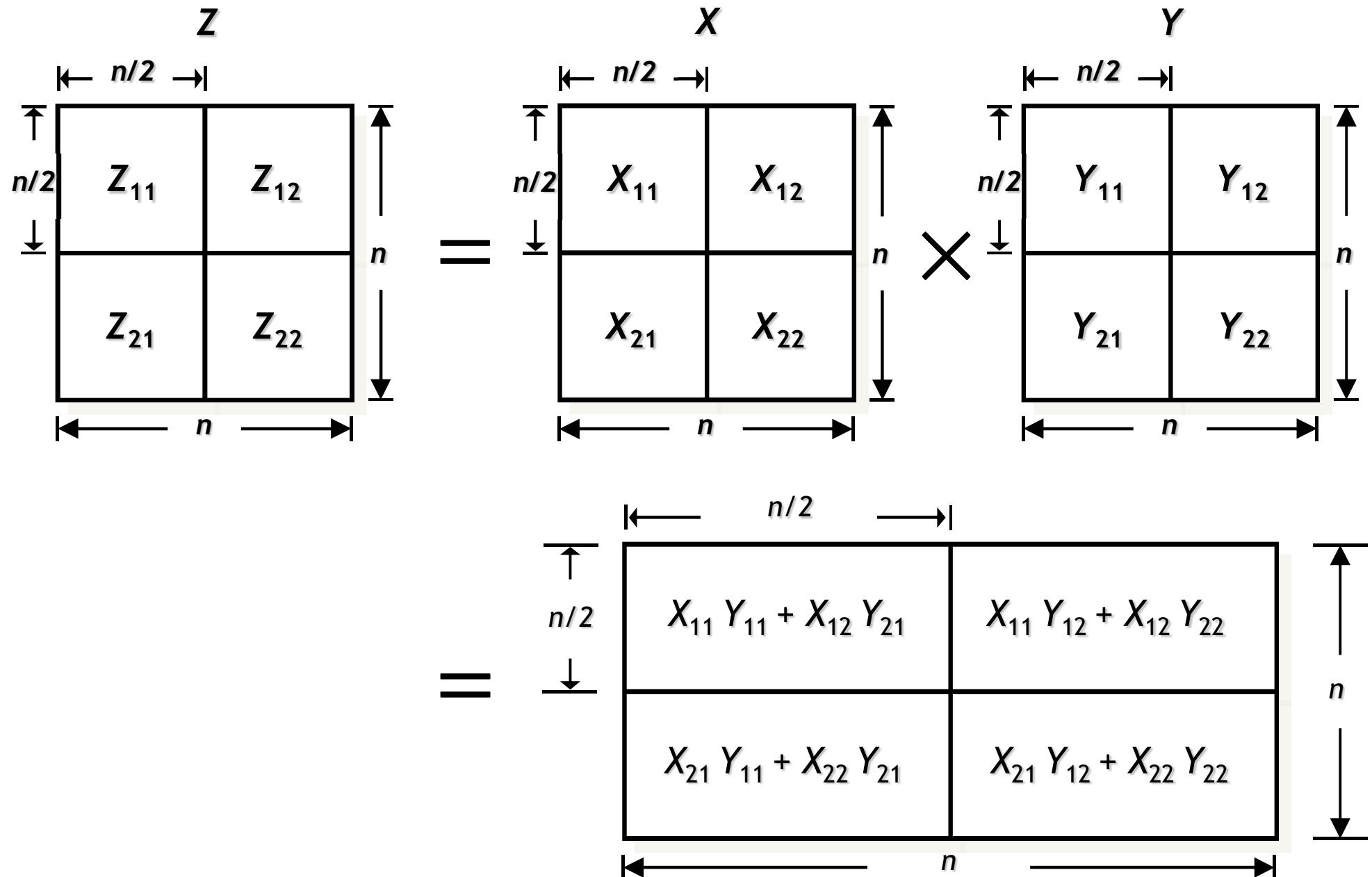
Work: $T_1(n) = \Theta(n^3)$

Span: $T_\infty(n) = \Theta(n)$

Parallel Running Time: $T_p(n) = O\left(\frac{T_1(n)}{p} + T_\infty(n)\right) = O\left(\frac{n^3}{p} + n\right)$

Parallelism: $\frac{T_1(n)}{T_\infty(n)} = \Theta(n^2)$

Parallel Recursive MM



Parallel Recursive MM

*Par-Rec-MM (Z, X, Y) { X, Y, Z are $n \times n$ matrices,
where $n = 2^k$ for integer $k \geq 0$ }*

1. *if* $n = 1$ *then*
2. $Z \leftarrow Z + X \cdot Y$
3. *else*
4. *spawn Par-Rec-MM (Z_{11} , X_{11} , Y_{11})*
5. *spawn Par-Rec-MM (Z_{12} , X_{11} , Y_{12})*
6. *spawn Par-Rec-MM (Z_{21} , X_{21} , Y_{11})*
7. *Par-Rec-MM (Z_{21} , X_{21} , Y_{12})*
8. *sync*
9. *spawn Par-Rec-MM (Z_{11} , X_{12} , Y_{21})*
10. *spawn Par-Rec-MM (Z_{12} , X_{12} , Y_{22})*
11. *spawn Par-Rec-MM (Z_{21} , X_{22} , Y_{21})*
12. *Par-Rec-MM (Z_{22} , X_{22} , Y_{22})*
13. *sync*
14. *endif*

Parallel Recursive MM

*Par-Rec-MM (Z, X, Y) { X, Y, Z are $n \times n$ matrices,
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12. *Par-Rec-MM (Z_{22} , X_{22} , Y_{22})*
13. *sync*
14. *endif*

Work:

$$T_1(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 8T_1\left(\frac{n}{2}\right) + \Theta(1), & \text{otherwise.} \end{cases}$$

$$= \Theta(n^3) \quad [\text{MT Case 1}]$$

Span:

$$T_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 2T_\infty\left(\frac{n}{2}\right) + \Theta(1), & \text{otherwise.} \end{cases}$$

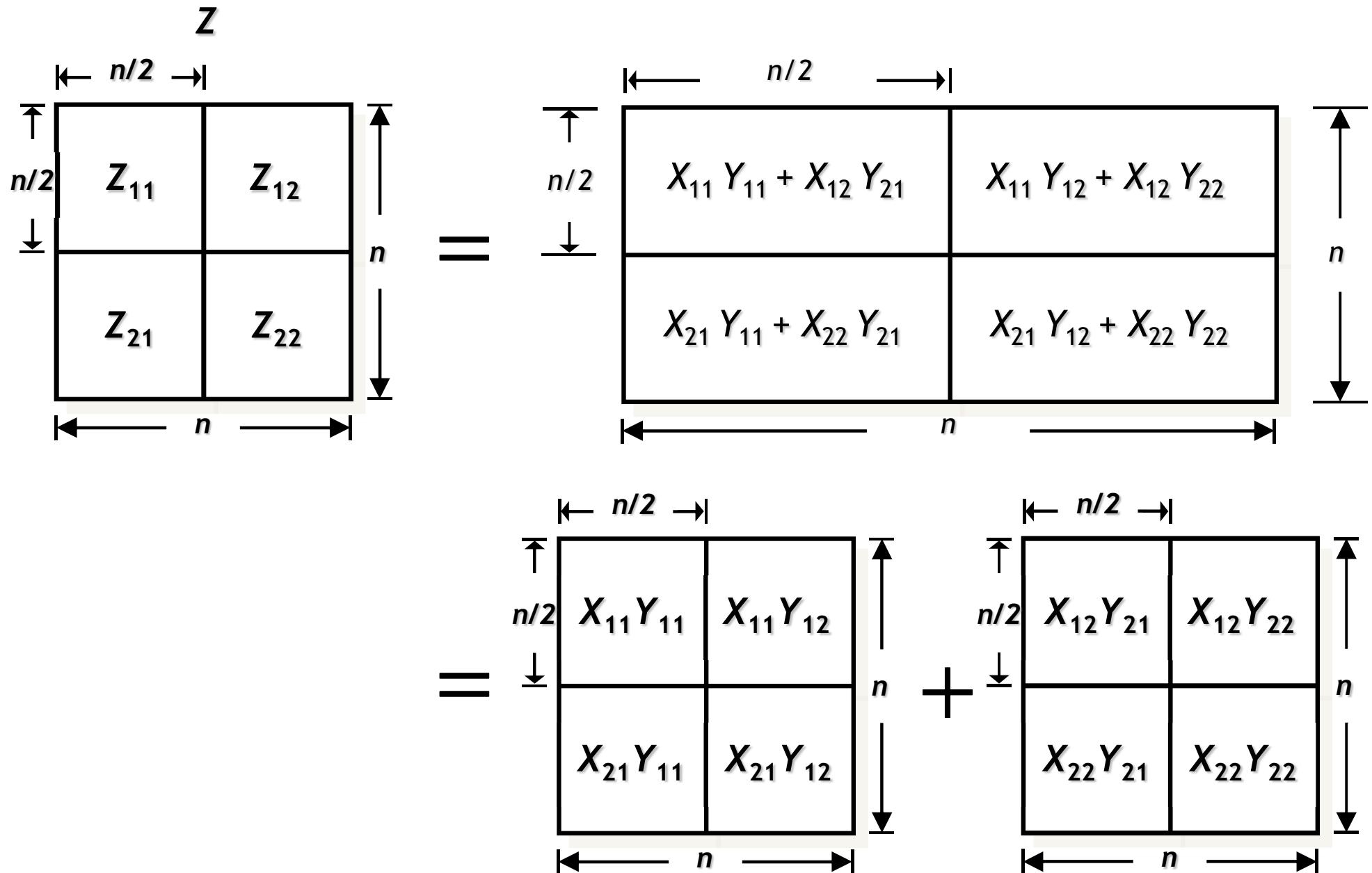
$$= \Theta(n) \quad [\text{MT Case 1}]$$

Parallelism: $\frac{T_1(n)}{T_\infty(n)} = \Theta(n^2)$

Additional Space:

$$s_\infty(n) = \Theta(1)$$

Recursive MM with More Parallelism



Recursive MM with More Parallelism

*Par-Rec-MM2 (Z, X, Y) { X, Y, Z are $n \times n$ matrices,
where $n = 2^k$ for integer $k \geq 0$ }*

1. *if* $n = 1$ *then*
2. $Z \leftarrow Z + X \cdot Y$
3. *else* { T is a temporary $n \times n$ matrix }
4. *spawn* Par-Rec-MM2 (Z_{11} , X_{11} , Y_{11})
5. *spawn* Par-Rec-MM2 (Z_{12} , X_{11} , Y_{12})
6. *spawn* Par-Rec-MM2 (Z_{21} , X_{21} , Y_{11})
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10. *spawn* Par-Rec-MM2 (T_{21} , X_{22} , Y_{21})
11. Par-Rec-MM2 (T_{22} , X_{22} , Y_{22})
12. *sync*
13. *parallel for* $i \leftarrow 1$ *to* n *do*
14. *parallel for* $j \leftarrow 1$ *to* n *do*
15. $Z[i][j] \leftarrow Z[i][j] + T[i][j]$
16. *endif*

Recursive MM with More Parallelism

*Par-Rec-MM2 (Z, X, Y) { X, Y, Z are $n \times n$ matrices,
where $n = 2^k$ for integer $k \geq 0$ }*

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3. *else* { T is a temporary $n \times n$ matrix }
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5. *spawn Par-Rec-MM2 (Z_{12} , X_{11} , Y_{12})*
6. *spawn Par-Rec-MM2 (Z_{21} , X_{21} , Y_{11})*
7. *spawn Par-Rec-MM2 (Z_{21} , X_{21} , Y_{12})*
8. *spawn Par-Rec-MM2 (T_{11} , X_{12} , Y_{21})*
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12. *sync*
13. *parallel for* $i \leftarrow 1$ *to* n *do*
14. *parallel for* $j \leftarrow 1$ *to* n *do*
15. $Z[i][j] \leftarrow Z[i][j] + T[i][j]$
16. *endif*

Work:

$$T_1(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 8T_1\left(\frac{n}{2}\right) + \Theta(n^2), & \text{otherwise.} \end{cases}$$

$$= \Theta(n^3) \quad [\text{MT Case 1}]$$

Span:

$$T_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ T_\infty\left(\frac{n}{2}\right) + \Theta(\log n), & \text{otherwise.} \end{cases}$$

$$= \Theta(\log^2 n) \quad [\text{MT Case 2}]$$

Parallelism: $\frac{T_1(n)}{T_\infty(n)} = \Theta\left(\frac{n^3}{\log^2 n}\right)$

Additional Space:

$$s_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 8s_\infty\left(\frac{n}{2}\right) + \Theta(n^2), & \text{otherwise.} \end{cases}$$

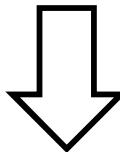
$$= \Theta(n^3) \quad [\text{MT Case 1}]$$

Parallel Merge Sort

Parallel Merge Sort

Merge-Sort (A, p, r) { sort the elements in A[p ... r] }

1. *if* $p < r$ *then*
2. $q \leftarrow \lfloor (p + r) / 2 \rfloor$
3. *Merge-Sort (A, p, q)*
4. *Merge-Sort (A, q + 1, r)*
5. *Merge (A, p, q, r)*



Par-Merge-Sort (A, p, r) { sort the elements in A[p ... r] }

1. *if* $p < r$ *then*
2. $q \leftarrow \lfloor (p + r) / 2 \rfloor$
3. *spawn Merge-Sort (A, p, q)*
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5. *sync*
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Parallel Merge Sort

Par-Merge-Sort (A, p, r) { sort the elements in A[p ... r] }

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3. *spawn* Merge-Sort (A, p, q)
4. Merge-Sort (A, q + 1, r)
5. *sync*
6. Merge (A, p, q, r)

Work: $T_1(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 2T_1\left(\frac{n}{2}\right) + \Theta(n), & \text{otherwise.} \end{cases}$

$$= \Theta(n \log n) \quad [\text{MT Case 2}]$$

Span: $T_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ T_\infty\left(\frac{n}{2}\right) + \Theta(n), & \text{otherwise.} \end{cases}$

$$= \Theta(n) \quad [\text{MT Case 3}]$$

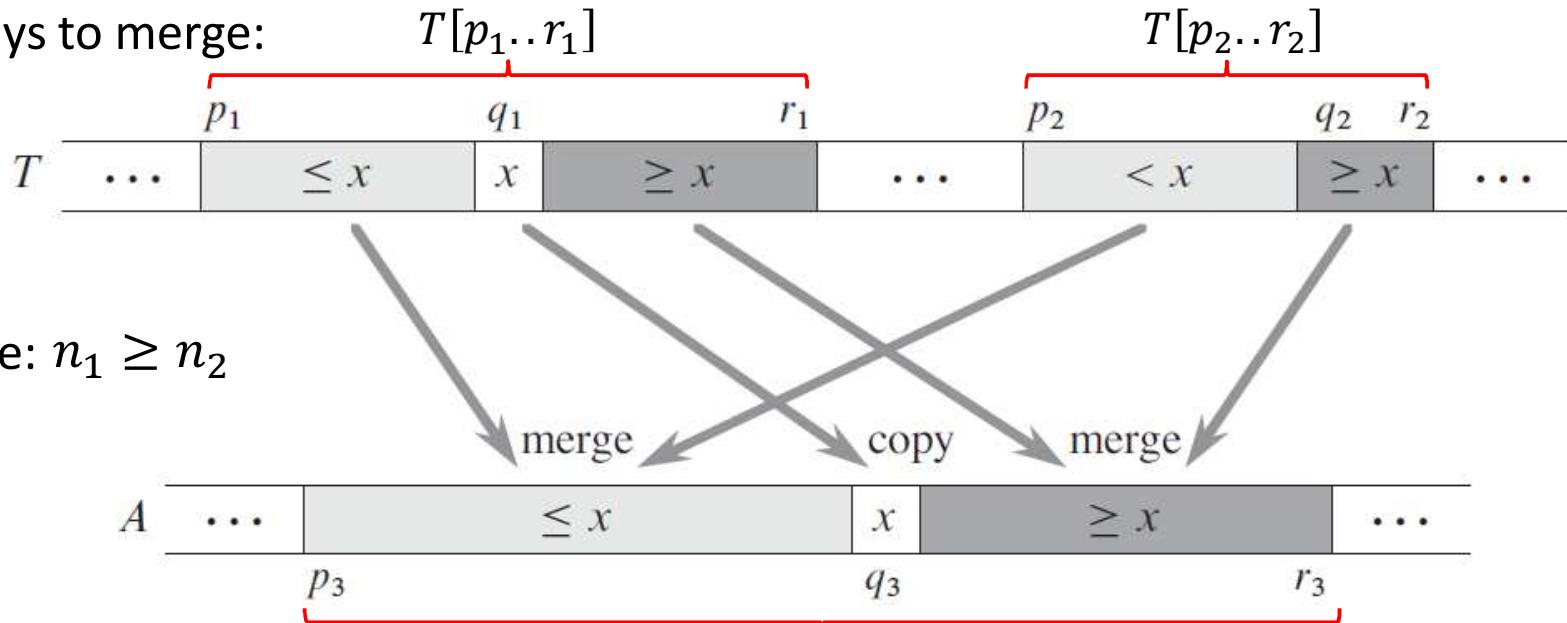
Parallelism: $\frac{T_1(n)}{T_\infty(n)} = \Theta(\log n)$

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

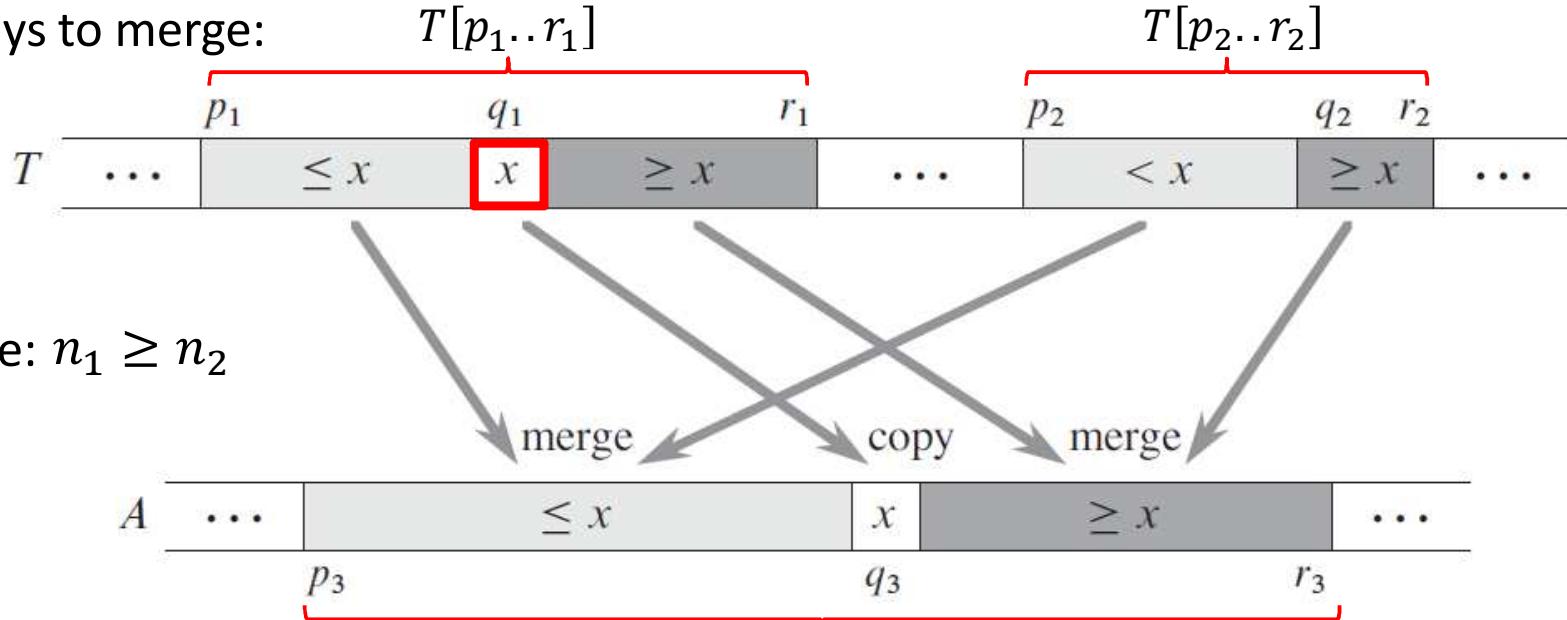
Source: Cormen et al.,
“Introduction to Algorithms”,
3rd Edition

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



suppose: $n_1 \geq n_2$

merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

Source: Cormen et al.,
"Introduction to Algorithms",
3rd Edition

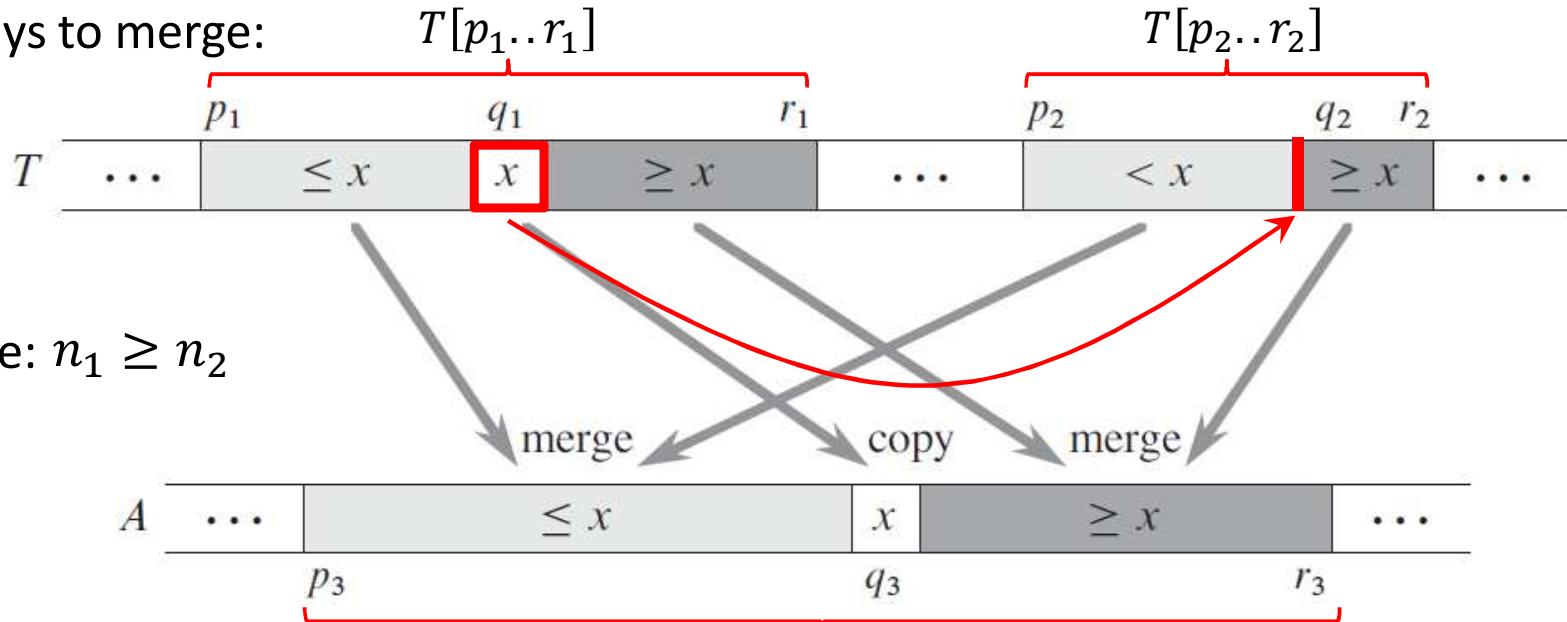
Step 1: Find $x = T[q_1]$, where q_1 is the midpoint of $T[p_1..r_1]$

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



suppose: $n_1 \geq n_2$

merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

Source: Cormen et al.,
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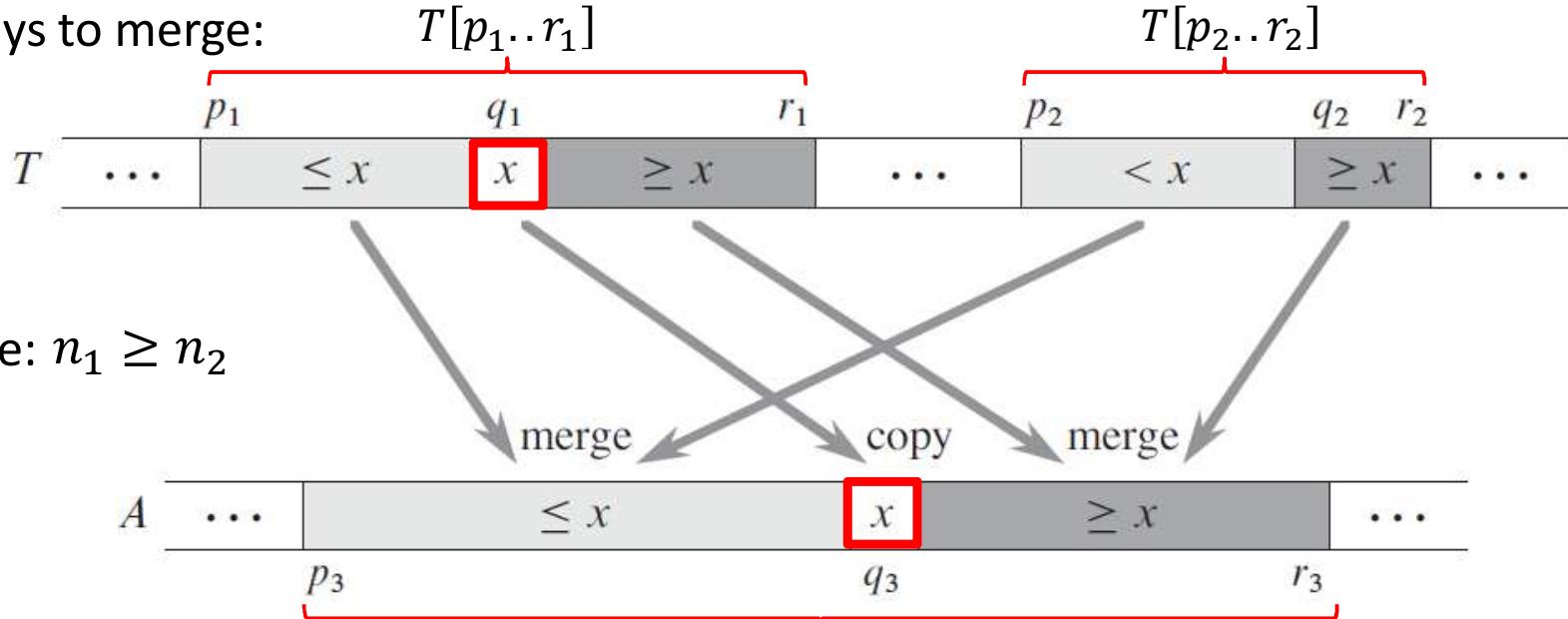
Step 2: Use binary search to find the index q_2 in subarray $T[p_2..r_2]$ so that the subarray would still be sorted if we insert x between $T[q_2 - 1]$ and $T[q_2]$

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

Source: Cormen et al.,
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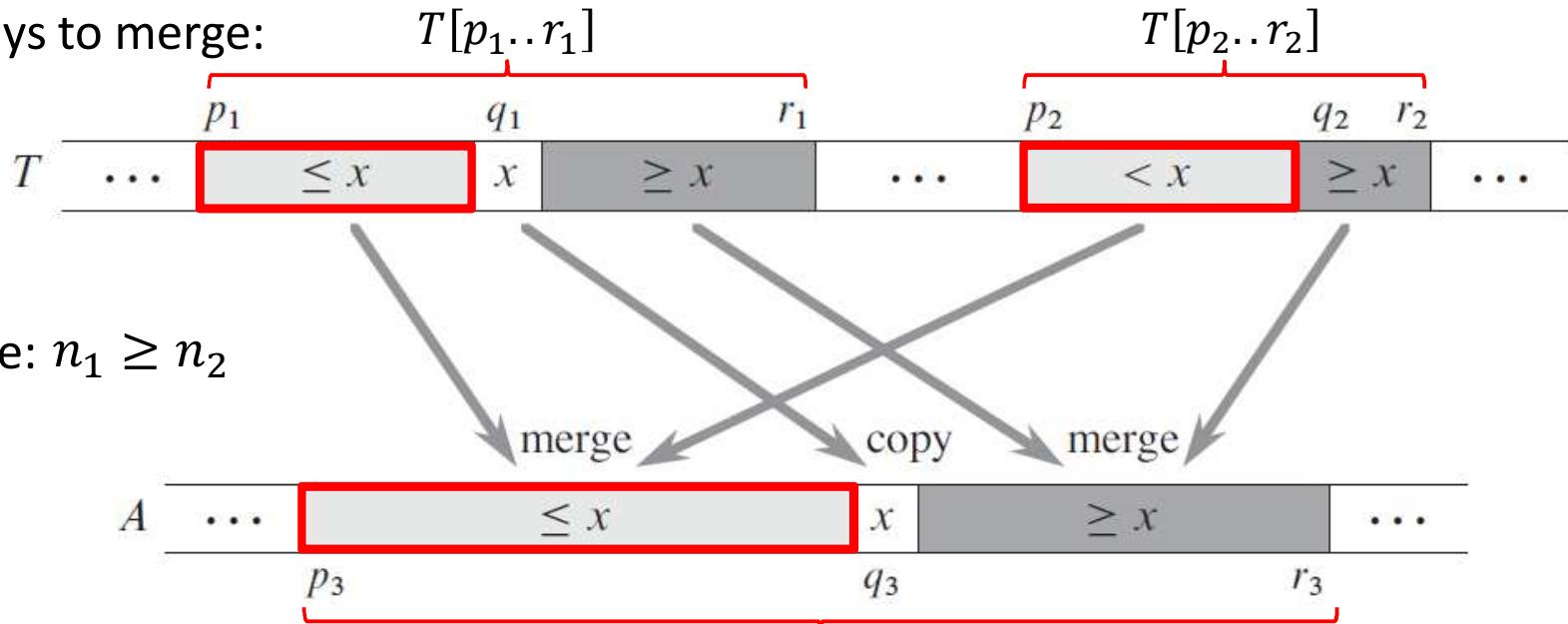
Step 3: Copy x to $A[q_3]$, where $q_3 = p_3 + (q_1 - p_1) + (q_2 - p_2)$

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



suppose: $n_1 \geq n_2$

merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

Source: Cormen et al.,
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3rd Edition

Perform the following two steps in parallel.

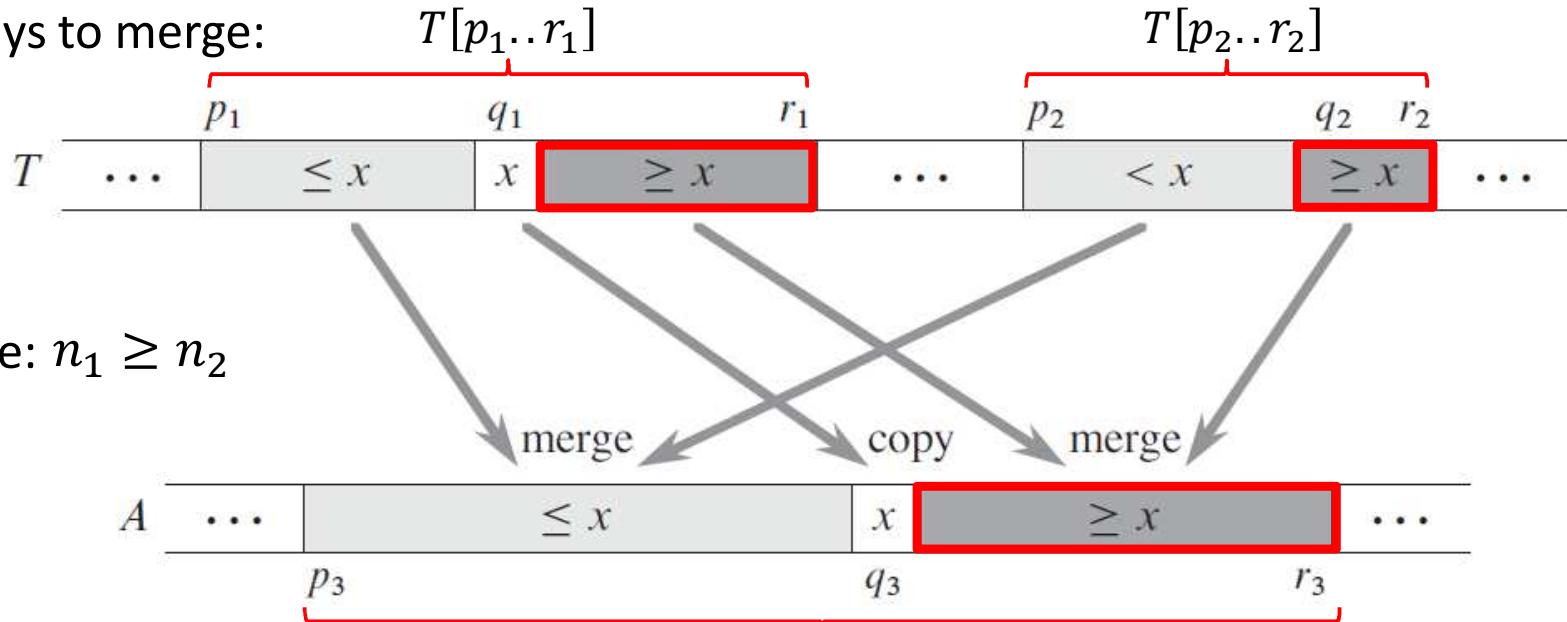
Step 4(a): Recursively merge $T[p_1..q_1 - 1]$ with $T[p_2..q_2 - 1]$,
and place the result into $A[p_3..q_3 - 1]$

Parallel Merge

$$n_1 = r_1 - p_1 + 1$$

$$n_2 = r_2 - p_2 + 1$$

subarrays to merge:



suppose: $n_1 \geq n_2$

merged output:

$$A[p_3..r_3]$$

$$n_3 = r_3 - p_3 + 1 = n_1 + n_2$$

Perform the following two steps in parallel.

Step 4(a): Recursively merge $T[p_1..q_1 - 1]$ with $T[p_2..q_2 - 1]$,
and place the result into $A[p_3..q_3 - 1]$

Step 4(b): Recursively merge $T[q_1 + 1..r_1]$ with $T[q_2 + 1..r_2]$,
and place the result into $A[q_3 + 1..r_3]$

Source: Cormen et al.,
“Introduction to Algorithms”,
3rd Edition

Parallel Merge

Par-Merge ($T, p_1, r_1, p_2, r_2, A, p_3$)

1. $n_1 \leftarrow r_1 - p_1 + 1, \quad n_2 \leftarrow r_2 - p_2 + 1$
2. *if* $n_1 < n_2$ *then*
3. $p_1 \leftrightarrow p_2, \quad r_1 \leftrightarrow r_2, \quad n_1 \leftrightarrow n_2$
4. *if* $n_1 = 0$ *then return*
5. *else*
6. $q_1 \leftarrow \lfloor (p_1 + r_1) / 2 \rfloor$
7. $q_2 \leftarrow \text{Binary-Search} (T[q_1], T, p_2, r_2)$
8. $q_3 \leftarrow p_3 + (q_1 - p_1) + (q_2 - p_2)$
9. $A[q_3] \leftarrow T[q_1]$
10. *spawn Par-Merge ($T, p_1, q_1-1, p_2, q_2-1, A, p_3$)*
11. *Par-Merge ($T, q_1+1, r_1, q_2+1, r_2, A, q_3+1$)*
12. *sync*

Parallel Merge

Par-Merge ($T, p_1, r_1, p_2, r_2, A, p_3$)

1. $n_1 \leftarrow r_1 - p_1 + 1, n_2 \leftarrow r_2 - p_2 + 1$
2. *if* $n_1 < n_2$ *then*
3. $p_1 \leftrightarrow p_2, r_1 \leftrightarrow r_2, n_1 \leftrightarrow n_2$
4. *if* $n_1 = 0$ *then return*
5. *else*
6. $q_1 \leftarrow \lfloor (p_1 + r_1) / 2 \rfloor$
7. $q_2 \leftarrow \text{Binary-Search} (T[q_1], T, p_2, r_2)$
8. $q_3 \leftarrow p_3 + (q_1 - p_1) + (q_2 - p_2)$
9. $A[q_3] \leftarrow T[q_1]$
10. *spawn Par-Merge ($T, p_1, q_1-1, p_2, q_2-1, A, p_3$)*
11. *Par-Merge ($T, q_1+1, r_1, q_2+1, r_2, A, q_3+1$)*
12. *sync*

We have,

$$n_2 \leq n_1 \Rightarrow 2n_2 \leq n_1 + n_2 = n$$

In the worst case, a recursive call in lines 9-10 merges half the elements of $T[p_1..r_1]$ with all elements of $T[p_2..r_2]$.

Hence, #elements involved in such a call:

$$\left\lfloor \frac{n_1}{2} \right\rfloor + n_2 \leq \frac{n_1}{2} + \frac{n_2}{2} + \frac{n_2}{2} = \frac{n_1 + n_2}{2} + \frac{2n_2}{4} \leq \frac{n}{2} + \frac{n}{4} = \frac{3n}{4}$$

Parallel Merge

Par-Merge ($T, p_1, r_1, p_2, r_2, A, p_3$)

1. $n_1 \leftarrow r_1 - p_1 + 1, n_2 \leftarrow r_2 - p_2 + 1$
2. *if* $n_1 < n_2$ *then*
3. $p_1 \leftrightarrow p_2, r_1 \leftrightarrow r_2, n_1 \leftrightarrow n_2$
4. *if* $n_1 = 0$ *then return*
5. *else*
6. $q_1 \leftarrow \lfloor (p_1 + r_1) / 2 \rfloor$
7. $q_2 \leftarrow \text{Binary-Search} (T[q_1], T, p_2, r_2)$
8. $q_3 \leftarrow p_3 + (q_1 - p_1) + (q_2 - p_2)$
9. $A[q_3] \leftarrow T[q_1]$
10. *spawn Par-Merge* ($T, p_1, q_1-1, p_2, q_2-1, A, p_3$)
11. *Par-Merge* ($T, q_1+1, r_1, q_2+1, r_2, A, q_3+1$)
12. *sync*

Span:

$$T_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ T_\infty\left(\frac{3n}{4}\right) + \Theta(\log n), & \text{otherwise.} \end{cases}$$

$$= \Theta(\log^2 n) \quad [\text{MT Case 2}]$$

Work:

Clearly, $T_1(n) = \Omega(n)$

We show below that, $T_1(n) = O(n)$

For some $\alpha \in \left[\frac{1}{4}, \frac{3}{4}\right]$, we have the following recurrence,

$$T_1(n) = T_1(\alpha n) + T_1((1 - \alpha)n) + O(\log n)$$

Assuming $T_1(n) \leq c_1 n - c_2 \log n$ for positive constants c_1 and c_2 , and substituting on the right hand side of the above recurrence gives us: $T_1(n) \leq c_1 n - c_2 \log n = O(n)$.

Hence, $T_1(n) = \Theta(n)$.

Parallel Merge Sort with Parallel Merge

Par-Merge-Sort (A, p, r) { sort the elements in A[p ... r] }

1. *if* $p < r$ *then*
2. $q \leftarrow \lfloor (p + r) / 2 \rfloor$
3. *spawn* Merge-Sort (A, p, q)
4. Merge-Sort (A, q + 1, r)
5. *sync*
6. *Par-Merge* (A, p, q, r)

Work: $T_1(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ 2T_1\left(\frac{n}{2}\right) + \Theta(n), & \text{otherwise.} \end{cases}$

$$= \Theta(n \log n) \quad [\text{MT Case 2}]$$

Span: $T_\infty(n) = \begin{cases} \Theta(1), & \text{if } n = 1, \\ T_\infty\left(\frac{n}{2}\right) + \Theta(\log^2 n), & \text{otherwise.} \end{cases}$

$$= \Theta(\log^3 n) \quad [\text{MT Case 2}]$$

Parallelism: $\frac{T_1(n)}{T_\infty(n)} = \Theta\left(\frac{n}{\log^2 n}\right)$