



CSE549 DNN Applications to Bioinformatics

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Benefits of DNN Learning

Classical Machine Learning Pipeline in Comp Bio



Deep Learning in Comp Bio.



Fig 1A,D from Angermueller et al. (2016) Molecular Systems Biology, (12), 878.

Various Applications

- Regulatory Genomics
 - □ Alternative Splicing (Leung et al 2014; Xiong et al, 2015)
 - □ Accessible Genome Analysis (Zhous & Troyanskaya, 2015; Kelley et al, 2016)
 - □ Protein-Nucleic Acid Binding Prediction (Alipananhi et al, 2015)
 - Variant Analysis

Protein Structure Prediction

- Secondary structure Prediction
- Order/Disorder Region Prediction
- Residue-Residue Contact Prediction

Applications on High throughput Data

- □ QSAR Prediction
- **Circadian Rhythms**

Other Topics Not Covered

- Cellular Image Analysis
- Medical Time Series Data

Early works of DNN in Alternative Splicing



Fig 1 of Xiong et al. (2015) Science 347(6218):1254806

Leung et al. (2014) Bioinformatics 30(12) 121-129

Group #	Name	Description	Туре	# of Features
01	short-seq-1mer		real (0-1)	28
02	short-seq-2mer	Frequency of nucleotide patterns of different lengths (1 to 3).		112
03	short-seq-3mer			320
04	translatable-C1			1
05	translatable-C1A	Describes whether exons can be translated without a stop codon in		1
06	translatable-C1AC2	one of three possible reading frames. For example, CIA means the	binary	1
07	translatable-C1C2	exons of interest are C1 + A.		1
08	mean-con-score-AI2			1
09	mean-con-score-IIA	M	1.00.10	1
10	mean-con-score-I2C2	Mean conservation score.	real (0-1)	1
11	mean-con-score-C111	1		1
12	log-length	Log base 10 lengths of exons.	real	5
13	log-length-ratio	Log base 10 length ratios of exons.	real	3
14	acceptor-site-strength		real	2
15	donor-site-strength	Strength of acceptor and donor sites.		2
16	frameshift-exonA	Whether exon A introduces frame shift.	binary	1
17	ma-sec-struct	RNA secondary structures.	real (0-1)	32
18	5mer-motif-down			54
19	6mer-motif-down	1		76
20	7mer-motif-down	Counts of motif clusters of different lengths (5 to 7) weighted by		28
21	5mer-motif-up	conservation upstream and downstream from alternative exon.	real	49
22	6mer-motif-up			78
23	7mer-motif-up	1		29
24	ese-ess-A		real	4
25	ese-ess-C1	Counts of exonic splicing enhancers and silencers.		4
26	ese-ess-C2			4
27	pssm-SC35	PSSM scores of SC35 splicing regulator protein.		5
28	pssm-ASF-SF2	PSSM scores of ASF/SF2 splicing regulator protein.	real	5
29	pssm-SRp40	PSSM scores of SRp40 splicing regulator protein.		10
30	nucleosome-position	Nucleosome positioning.	real	4
31	PTB	Phosphotyrosine-binding domain.	real	50
32	Nova-counts	Counts of Nova motif.	integer	27
33	Nova-cluster	Nova cluster score.	real	8
34	T-rich		real	24
35	G-rich			8
36	UG-rich	Counts of motif with and without weighting by conservation.		16
37	GU-rich	1		32
38	Fox			24
39	Ouak	1		8
40	SC35	1		22
41	SRm160	1		11
42	SRrp20/30/38/40/55/75	1		77
43	CELF-like	1	real	2
44	CUGBP	1		16
45	MBNL			24
46	TRA2-alpha	Counts of motif with and without weighting by conservation.		22
47	TRA2-beta	1		22
48	hnRNP-A	1		44
49	hnRNP-H	1		22
50	hnRNP-G	1		22
51	9G8	1		22
52	ASF/SF2	1		11
53	Sugnet	1		2
54	alt-AG-pos	Position of the alternative AG and GT position.	integer	2
55	Alu-Al2	Counts of ALU repeats.	integer	12
				-

CI and C2 denote the flanking constitutive exons; A denotes the alternative exon; II denotes the intron between CI and A; I2 denotes the intron between A and C2

DNA/RNA Sequence Analysis with Deep CNN

Convolution step in Deep CNN resembles traditional sequence "windowing" scheme



Angermueller et al. (2016) Molecular Systems Biology, (12), 878.

DeepSEA: CNN-based noncoding variant effect prediction

GOAL: Identifying functional effects of noncoding variants



Innovative points:

- 1. Use long seq. 1kbp
- 2. multitask architecture
- -> multiple output variables
 919 chromatin features (125 DNase features, 690 TF features, 104 histone features)



Zhou, J., & Troyanskaya, O. G. (2015). Nature Methods, 12(10), 931-4.

DanQ: Quantifying the Function of DNA

- Motivation: Over 98% of the human genome is non-coding and 93% of disease-associated variants lie in noncoding regions.
- Proposed: DanQ, hybrid convolutional and bi-directional long short-term memory recurrent neural network predicting non-coding function.

Data:

- Input: GRCh37 reference genome segmented into non-overlapping 200-bp bins.
- Labels: Intersecting 919 ChIP-seq and DNase-seq peak sets from uniformly processed ENCODE and Roadmap Epigenomics data



Daniel Quang and Xiaohui Xie. 2016. DanQ: A hybrid convolutional and recurrent deep neural network for quantifying the function of DNA sequences. *Nucleic Acids Research* 44, 11.

DanQ vs DeepSEA



Basset: CNN-based Accessible Genome Analysis



1. convert the sequence to a "one hot code" representation

2. scanning weight matrices across the input matrix to produce an output matrix with a row for every convolution filter and a column for every position in the input

3. linear transformation of the input vector and apply a ReLU.

4. linear transformation to a vector of 164 elements that represents the target cells

Kelley et al. (2016). Genome Research, 26(7), 990-999

DeepBind: Protein–Nucleic acid Binding Site Prediction

DeepBind is a CNN based supervised learning where

Input: segments of sequences and

labels (output): experimentally determined binding score (ex. ChIP-seq peaks)



Alipanahi et al (2015) Nature Biotechnology, 33(8), 831–838.

Motif Extraction capability of DEEPBIND

The trained motif detector M_k and visualization with sequence logo



Generating sequence logo to find motifs

- 1. Feed all sequences from the test set through the convolutional and rectification stages of the DeepBind model,
- 2. Align all the sequences that passed the activation threshold for at least one position *i*.
- 3. Generate a position frequency matrix (PFM) and transform it into a sequence logo.

Alipanahi et al (2015) Nature Biotechnology, 33(8), 831–838.

RNN for variable length Seq. Input

- □ Recurrent Neural Network
 - □ Able to work with sequence input of variable length
 - □ Capture long range interactions within the input sequences and across outputs.
 - Difficult to work with and train



□ Not many success here

Protein Structure Prediction

- Protein structure prediction methods tend to apply unsupervised method or combination of NN methods
- □ Types of unsupervised DNN methods:
 - □ Restricted Boltzmann Machines (RBM)
 - Deep Belief Networks
- Combination methods
 - Deep Conditional Neural Fields

Stacking RBM in Protein Fold Recognition



84 features from five types of sequence alignment and/or protein structure prediction tools

Layer by layer learning with restricted Boltzmann machine (RBM).

Same fold or not

Jo et al. (2015). Scientific Reports, 5, 17573.

DEEPCNF: Secondary Structure Prediction



Calculates conditional probability of SS labels on input features

Wang et al. (2016) Scientific Reports, 6(January), 18962.

Circadian Rhythms

GOAL: inferring whether a given genes oscillate in circadian fashion or not and inferring the time at which a set of measurements was taken



BIO_CYCLE: estimate which signals are periodic in high-throughput circadian experiments, producing estimates of amplitudes, periods, phases, as well as several statistical significance measures. DATA: data sampled over 24 and 48h BIO_CLOCK The outputs are BIO_CLOCK: estimate the time at which a particular single-time-point transcriptomic experiment was carried

Agostinelli, et al. (2016). Bioinformatics, 32(12), i8-i17.

Predicting Properties of Drugs

- Input: transcriptional response data sets (transcriptional profile)
- □ Goal: classify various drugs to therapeutic categories



input layers of 977 and 271 neural nodes,

A. Aliper, et al. 2016. Deep learning applications for predicting pharmacological properties of drugs and drug repurposing using transcriptomic data. *Molecular Pharmaceutics* 13, 7.

Deep Patient: Unsupervised Prognostic Prediction based on EHR

□ Feature learning:

three-layer stack of denoising autoencoders

□ Data: EHRs of

- about 700,000 patients from the Mount Sinai data warehouse.
- evaluation using 76,214 test patients comprising 78 diseases from diverse clinical domains and temporal windows
- Prediction: random forest classifier





R. Miotto et al. 2016. Deep Patient: An Unsupervised Representation to Predict the Future of Patients from the Electronic Health Records. *Scientific reports* 6, April.

Raw Patient Dataset



Figure 2. Diagram of the unsupervised deep feature learning pipeline to transform a raw dataset into the deep patient representation through multiple layers of neural networks. Each layer of the neural network is trained to produce a higher-level representation from the result of the previous layer.

Disease classification results

Time Interval = 1 year (76,214 patients)						
		Classification Threshold = 0.6				
Patient Representation	AUC-ROC	Accuracy	F-Score			
RawFeat	0.659	0.805	0.084			
PCA	0.696	0.879	0.104			
GMM	0.632	0.891	0.072			
K-Means	0.672	0.887	0.093			
ICA	0.695	0.882	0.101			
DeepPatient	0.773 *	0.929	0.181			

Disease classification experiment

Time Interval = 1 year (76,214 patients)						
	Area under the ROC curve					
Disease	RawFeat	PCA	DeepPatient			
Diabetes mellitus with complications	0.794	0.861	0.907			
Cancer of rectum and anus	0.863	0.821	0.887			
Cancer of liver and intrahepatic bile duct	0.830	0.867	0.886			
Regional enteritis and ulcerative colitis	0.814	0.843	0.870			

Reference

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Reference to Reviews

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- 4. Ladislav Rampasek and Anna Goldenberg. 2016. TensorFlow: Biology's Gateway to Deep Learning? *Cell Systems* 2, 1: 12–14.

Tensor Flow Tutorial

Contents and examples extended from **Udacity Deep Learning** by Google https://classroom.udacity.com/courses/ud730/

Off-the-shelf Deep learning Tools



Table 1 in Angermueller et al. (2016) Molecular Systems Biology, (12), 878.

Installing

□ Install 64-bit Python 3.5 & pip (or Anaconda3-4.2.0-Windows-x86_64)

Install virtualenv:

- □ CMD: pip install virtualenv
- □ CMD: pip install virtualenvwrapper-win
- □ Create virtual environment
 - □ CMD: mkvirtualenv tensorflowCPU
- Install the CPU-only version of TensorFlow in the virtual environment
 - □ (TENSOR~) C:\Users\Name> pip install --upgrade <u>https://storage.googleapis.com/tensorflow/windows/cpu/tensorf</u> <u>low-0.12.1-cp35-cp35m-win_amd64.whl</u>

- The role of the Python code in TensorFlow is to build this external computation graph, and to dictate which parts of the computation graph should be run.
- Other heavy lifting such as numerical computations are don outside Python.

Mnist data

10 labels
1 channel
28x28 images

11543 75353 55300

Trying out MNIST tutorials in Tensorflow.org

GOTO: https://www.tensorflow.org/tutorials/mnist/pros/

Load MNIST Data

from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets('MNIST_data', one_hot=True)

stores the training, validation, and testing sets

Start TensorFlow InteractiveSession

import tensorflow as tf
sess = tf.InteractiveSession()

It allows you to interleave operations which build a computation graph with ones that run the graph.

MODEL1: Build a Softmax Regression Model



- to 10 outputs
- Bias vector b is a 10-dimensional vector
 - we have 10 classes

Placeholders: create nodes for the input images and target output classes.

x = tf.placeholder(tf.float32, shape=[None, 784])
y_ = tf.placeholder(tf.float32, shape=[None, 10])

Variables: define & initalize weights W and bias b variables

W = tf.Variable(tf.zeros([784,10])) b = tf.Variable(tf.zeros([10]))

sess.run(tf.global_variables_initializer())

Define the regression model.

$$z = tf.matmul(x,W) + b$$

Define the loss function : one used to update W and bias





train_step = tf.train.GradientDescentOptimizer(0.5).minimize(cross_entropy)

Steepest gradient descent, with a step length of 0.5, to descend the cross entropy. Other built-in optimization functions: https://www.tensorflow.org/api_docs/python/train/#o ptimizers

- TensorFlow actually added set of new operations to the computation graph.
 - Ones to compute gradients,
 - Ones to compute parameter update steps, and
 - Ones apply update steps to the parameters.

TensorFlow Back-propagation approach

TensorFlow take a computational graph and add additional nodes to the graph that provide a symbolic description of the desired derivatives.



symbol-to-symbol approach to computing derivatives

Training iteration



evaluate our accuracy on the test data

print(accuracy.eval(feed_dict={x: mnist.test.images, y_: mnist.test.labels}))

```
C:\Users\Sael Lee>workon tensorflowCPU
(TENSOR~1) C:\Users\Sael Lee>python
Python 3.5.2 [Continuum Analytics, Inc.] (default, Jul 5 2016, 11:41:13) [MSC v.1900 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license" for more information.
>>> from tensorflow.examples.tutorials.mnist import input_data
>>> mnist = input_data.read_data_sets('MNIST_data', one_hot=True)
Successfully downloaded train-images-idx3-ubyte.gz 9912422 bytes.
Extracting MNIST_data\train-images-idx3-ubyte.gz
Successfully downloaded train-labels-idx1-ubyte.gz 28881 bytes.
Extracting MNIST_data\train-labels-idx1-ubyte.gz
Successfully downloaded t10k-images-idx3-ubyte.gz 1648877 bytes.
Extracting MNIST_data\t10k-images-idx3-ubyte.gz
Successfully downloaded t10k-labels-idx1-ubyte.gz 4542 bytes.
Extracting MNIST_data\t10k-labels-idx1-ubyte.gz
>>>
>>> import tensorflow as tf
>>> sess = tf.InteractiveSession()
>>> x = tf.placeholder(tf.float32, shape=[None, 784])
>>> y_ = tf.placeholder(tf.float32, shape=[None, 10])
>>> W = tf.Variable(tf.zeros([784,10]))
>>> b = tf.Variable(tf.zeros([10]))
>>> sess.run(tf.global_variables_initializer())
>>>
>>>
>>> v = tf.matmul(x,W) + b
>>> cross_entropy = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(y, y_))
>>> train_step = tf.train.GradientDescentOptimizer(0.5).minimize(cross_entropy)
>>> for i in range(1000):
      batch = mnist.train.next_batch(100)
      train_step.run(feed_dict={x: batch[0], y_: batch[1]})
 - -
>>> correct_prediction = tf.equal(tf.argmax(y,1), tf.argmax(y_,1))
>>> accuracy = tf.reduce_mean(tf.cast(correct_prediction, tf.float32))
>>> print(accuracy.eval(feed_dict={x: mnist.test.images, y_: mnist.test.labels}))
0.9165
```

Get 92% accuracy => very bad for MNIST

MODEL2: Build a Multilayer Convolutional Network

```
Weight Initialization
```

One way to randomize. initialize weights with a small amount of noise for symmetry breaking, and to prevent 0 gradients.

```
def weight_variable(shape):
    initial = tf.truncated_normal(shape, stddev=0.1)
    return tf.Variable(initial)
```

```
def bias_variable(shape):
    initial = tf.constant(0.1, shape=shape)
    return tf.Variable(initial)
```

Since we're

using <u>ReLU</u> neurons, we should initialize them with a slightly positive initial bias to avoid "dead neurons" Define Convolution and Pooling function

Model:

- Convolution stride of 1 and are zero padded so that the output is the same size as the input (same padding).
- Pooling: max pooling over 2x2 blocks.

def conv2d(x, W):
 return tf.nn.conv2d(x, W, strides=[1, 1, 1, 1], padding='SAME')

*Computes a 2-D convolution given 4-D input and filter tensors. tf.nn.conv2d(input, filter, strides, padding, use_cudnn_on_gpu=None, data_format=None, name=None)

- Flattens the filter to a 2-D matrix with shape [filter_height * filter_width * in_channels, output_channels].
- 2. Extracts image patches from the input tensor to form a *virtual* tensor of shape [batch, out_height, out_width, filter_height * filter_width * in_channels].
- 3. For each patch, right-multiplies the filter matrix and the image patch vector.

https://www.tensorflow.org/api_docs/python /nn/convolution#conv2d tf.nn.max_pool(value, ksize, strides, padding, data_format='NHWC', name=None)

ARGUMENTS:

- value: A 4-D Tensor with shape [batch, height, width, channels] and type tf.float32.
- **ksize**: A list of ints that has length >= 4. The size of the window for each dimension of the input tensor.
- **strides**: A list of ints that has length >= 4. The stride of the sliding window for each dimension of the input tensor.
- padding: A string, either 'VALID' or 'SAME'. The padding algorithm.
- data_format: A string. 'NHWC' and 'NCHW' are supported.
- name: Optional name for the operation.

1st Convolutional Layer



Densely Connected Layer

```
W_fc1 = weight_variable([7 * 7 * 64, 1024])
b_fc1 = bias_variable([1024])
```

h_pool2_flat = tf.reshape(h_pool2, [-1, 7*7*64]) h_fc1 = tf.nn.relu(tf.matmul(h_pool2_flat, W_fc1) + b_fc1)

fully-connected layer with 1024 neurons to allow processing on the entire image.

Add Dropout

To reduce overfitting, apply **dropout** before the readout layer.

Readout Layer

W_fc2 = weight_variable([1024, 10]) b_fc2 = bias_variable([10])

y_conv = tf.matmul(h_fc1_drop, W_fc2) + b_fc2

Train and Evaluate the Model

Almost similar the SoftMax example with the following differences:

- Replace the steepest gradient descent optimizer with the more sophisticated ADAM optimizer.
- Include the additional parameter keep_prob in feed_dict to control the dropout rate.
- Add logging to every 100th iteration in the training process.

WARNING but it does 20,000 training iterations and may take a while (possibly up to half an hour), depending on your processor.

cross_entropy = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(y_conv, y_)) train_step = tf.train_AdamOptimizer(1e-4).minimize(cross_entropy) correct_prediction = tf.equal(tf.argmax(y_conv,1), tf.argmax(y_,1)) accuracy = tf.reduce_mean(tf.cast(correct_prediction, tf.float32)) sess.run(tf.global_variables_initializer()) Let's change this to 2000 not to for i in range (20000): crush your laptop batch = mnist.train.next_batch(50) if i%100 == 0: train_accuracy = accuracy.eval(feed_dict={ x:batch[0], y_: batch[1], keep_prob: 1.0}) print("step %d, training accuracy %g"%(i, train_accuracy)) train_step.run(feed_dict={x: batch[0], y_: batch[1], keep_prob: 0.5}) print("test accuracy %g"%accuracy.eval(feed_dict={

x: mnist.test.images, y_: mnist.test.labels, keep_prob: 1.0}))

step	12600,	training	accuracy	1
step	12700,	training	accuracy	0.98
step	12800	training	accuracy	1
steb	12900.	training	accuracy	1
steb	13000.	training	accuracy	1
step	13100.	training	accuracy	1
sten	13200	training	accuracy	1
sten	13300	training	accuracy	1
sten	13400	training	accuracy	1
sten	13500	training	accuracy	1
sten	13600	training	accuracy	1
sten	13700	training	accuracy	1
sten	13800	training	accuracy	1
sten	13900	training	accuracy	1
sten	14000	training	accuracy	0 98
ten	14100	training	accuracy	1
ten	14200	training	accuracy	1
ten	14300	training	accuracy	1
ten	14400	training	accuracy	1
ten	14500	training	accuracy	1
ton	14600	training	accuracy	1
ton	14700	training	accuracy	0 08
ton	1/800	training	accuracy	1
ton	1/000,	training	accuracy	1
top	15000	training	accuracy	1
tep	15100,	training	accuracy	1
tep	15100,	training	accuracy	1
top	15200,	training	accuracy	0 00
ton	15400	training	accuracy	1
ten	15500	training	accuracy	0 98
t on	15600	training	accuracy	1
ten	15700	training	accuracy	1
ten	15800	training	accuracy	1
sten	15900	training	accuracy	ī
sten	16000	training	accuracy	ī
step	16100.	training	accuracy	1
step	16200.	training	accuracy	1
step	16300.	training	accuracy	1
step	16400	training	accuracy	1
step	16500	training	accuracy	1
step	16600	training	accuracy	1
step	16700,	training	accuracy	1
step	16800,	training	accuracy	1
step	16900,	training	accuracy	1
step	17000,	training	accuracy	1
step	17100,	training	accuracy	1
step	17200,	training	accuracy	1
step	17300,	training	accuracy	1
step	17400,	training	accuracy	1
step	17500,	training	accuracy	1
step	17600,	training	accuracy	1
step	17700,	training	accuracy	0.98
step	1/800,	training	accuracy	1
step	1/900,	training	accuracy	1
step	18000,	training	accuracy	1
step	18100,	training	accuracy	1
step	18200,	training	accuracy	1
step	18300,	training	accuracy	1
step	18400,	training	accuracy	1